

(c) The variable depletion layer model

includes now the variation of the charge in the depletion layer between source and drain.

$$Q_{inv} = -C_{ox} (V_{GS} - V_T) \quad V_{GS} > V_T$$

however now ~~we~~ we include the ~~implicit~~ implicit dependence of  $V_T$  on the charge ~~in~~ the depletion layer.

$$V_T = V_{FB} + V_S + \frac{\sqrt{2\epsilon q N_A V_S}}{C_{ox}}$$

$$V_S = 2V_F + V_C$$

$$\Rightarrow \left[ V_T = V_{FB} + 2V_F + V_C + \frac{\sqrt{2\epsilon q N_A (2V_F + V_C)}}{C_{ox}} \right]$$

The voltage ~~across~~  $V_C$  is the ~~difference~~ channel voltage  $V_C(y)$

$$\Rightarrow I_D = \mu C_{ox} \frac{W}{L} (V_{GS} - V_{FB} - 2V_F - V_C(y)) \left( - \frac{\sqrt{2\epsilon q N_A (2V_F + V_C(y))}}{C_{ox}} \right) dy$$

$y$  varies from 0 to  $L$ .  $V_C(y)$  varies from  $V_{DS}$  to  $V_{GS}$

$$\begin{aligned} I_D &= \mu C_{ox} \frac{W}{L} (V_G - V_{FB} - 2V_F - \frac{V_{DS}}{2}) V_{DS} \\ &\quad - \frac{2}{3} \mu \frac{W}{L} \sqrt{2\epsilon q N_A} \left[ (2V_F + V_{DS})^{\frac{3}{2}} - (2V_F)^{\frac{3}{2}} \right] \end{aligned}$$

or integration from  $V_S$  to  $V_D$

$$I_D = \mu C_{ox} \frac{W}{L} \left\{ \left( V_G - V_{FB} - 2V_F - V_S - \frac{V_{DS}}{2} \right) V_{DS} - \frac{2}{3} \gamma \left[ (2V_F + V_D)^{3/2} - (2V_F + V_S)^{3/2} \right] \right\}$$

$$\gamma = \sqrt{\frac{2qE_s N_A}{C_{ox}}}$$

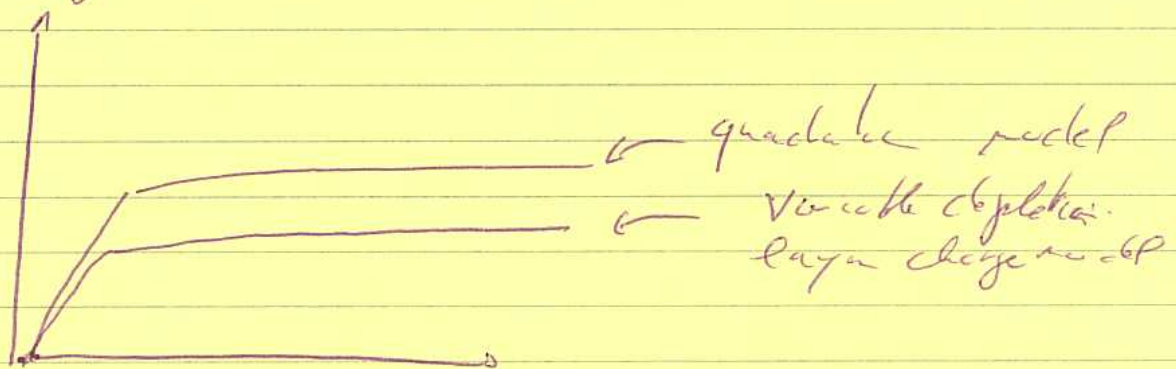
Again this expression is not valid after the pinch-off point for describing the saturation regime.

The drain voltage at which saturation occurs can be

$V_{D,sat} = V_G - V_{FB} - 2V_F$  found setting  $\frac{dI_D}{dV_D} = 0$ .

$$\Rightarrow V_{D,sat} = V_G - V_{FB} - 2V_F + \frac{\gamma^2}{2} - \gamma \sqrt{V_G - V_{FB} + \frac{\gamma^2}{4}}$$

Actually the quadratic model yields to larger current compared to this more accurate derivation.





it can fall transconductance.

$$g_{m, \text{sat}} = \mu C_{ox} \frac{W}{L} [V_G - V_{Fe} - 2V_F]$$

$$g_{m, \text{sat}} = \mu C_{ox} \frac{W}{L} V_{DS} \quad (\text{shift})$$

$$\text{and } \boxed{g_{m, \text{sat}} = \mu C_{ox} \frac{W}{L} V_{DS, \text{sat}}} \Rightarrow \text{almost linear with } V_G$$

so it can be also written

$$\boxed{g_{m, \text{sat}} = \mu^* C_{ox} \frac{W}{L} (V_G - V_T)} \quad \text{with modified } \mu^*$$

$$\mu^* = \mu \left[ 1 - \frac{1}{\sqrt{1 + \frac{2(V_F + V_S) C_{ox}^2}{q N_A \epsilon_{Si}}}} \right]$$

# (c) Influence of substrate bias on threshold voltage

we saw that  $V_T = V_{FB} + 2V_F + \gamma \sqrt{2V_F}$

$$\gamma = \frac{\sqrt{2q\epsilon_{si}Na}}{C_{ox}}$$

where we supposed that both the source and the substrate were grounded.  $V_s - V_{sub} = 0$ .

In many applications, the source and the substrate may be at different potential.

The depletion charge under the channel is obtained by.

$$Q_d(y) = -\sqrt{2q\epsilon_{si}Na(2V_F + V_c(y) - V_{sub})} \quad \underline{V_{sub} < 0}$$

$$V_T = V_{FB} + 2V_F + V_c(y) + \gamma \sqrt{2V_F + V_c(y) - V_{sub}}$$

$$\text{at } y=0 \Rightarrow V_c(y) = V_s$$

$$y \quad (i) \quad V_{sub} = 0; \quad V_s > 0 \Rightarrow$$

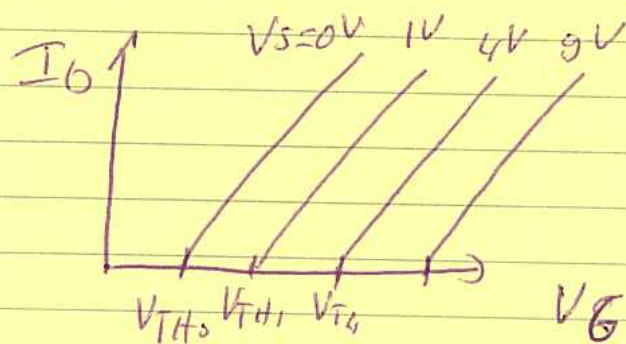
$$V_{TH} = V_s + V_{FB} + 2V_F + \gamma \sqrt{2V_F + V_s}$$

$$(ii) \quad V_{sub} < 0; \quad V_s = 0$$

$$V_{TH} = V_{FB} + 2V_F + \gamma \sqrt{2V_F - V_{sub}}$$



In conclusion,  $V_T$  increases as a function of the potential difference between source and ~~drain~~ substrate.



$V_{DS}$  is small  
and  $V_{SD} = 0$  (grounded).

### (3) Surface mobility

The mobility  $\mu_m$  that we used is the one associated with the "surface mobility". Surface mobility is lower than ~~sub~~ bulk mobility because of scattering at the silicon-oxide interface.

The surface mobility depends on how much  $e^-$  interact at the interface, and therefore it depends on the vertical ~~the~~ electrical field which 'pushes'  $e^-$  against the interface.  
~~with~~  $E = 0$  we denote  $\mu_m \equiv \mu_{m0}$ .

The current in the transistor is given by

$$I_D = \frac{W}{L} \int_{V_S}^{V_D} \mu_m (-Q_{inv}(y)) d(y)$$

constant electric field

There exists an empirical relationship that describes the dependence of surface mobility on vertical electric field in the channel,  $E_x$ .

$$\mu_n(y) = \frac{\mu_{n0}}{1 + \theta E_x(y)} \quad \theta = \text{mobility reduction factor}$$

The average electric field in the channel is given by

$$E_x(y) = \frac{E_{so}(y) + E_{si}(y)}{2} \quad E_{so} = \text{electric field at the silicon-oxide interface}$$

$E_{si}$  = electric field at the boundary between inversion layer and depletion region

According to Gauss Law

$$(i) \quad E_{si} E_{so}(y) = E_x E_{ox}(y) \quad E_{ox} = \frac{V_G - V_{FB} - V_{sy}(y)}{d_{ox}} \quad \text{where } d_{ox} = \text{oxide thickness}$$

$$\Rightarrow E_{si} E_{so}(y) = C_{ox} [V_G - V_{FB} - V_{sy}(y)] = - [Q_{inv}(y) + Q_d(y)] = -Q_E(y)$$

$$(ii) \quad E_{si} E_{si}(y) = -Q_d(y) = \gamma C_{ox} \sqrt{V_{sy}(y)}$$

$$\Rightarrow \left[ E_x(y) = \frac{C_{ox}}{2 E_{si}} (V_G - V_{FB} - V_{sy}(y) + \gamma \sqrt{V_{sy}(y)}) \right]$$



$$\Rightarrow \mu_n(y) = \frac{\mu_{n0}}{1 + \theta \frac{C_{ox}}{2\epsilon_{si}} (V_G - V_{FB} - V_{sf}(y) + \delta \sqrt{V_{sf}(y)})}$$

We want to simplify the calculation of the Draw current.

$$\boxed{I_D \text{ calculated with } \mu_n(y) \text{ depending on } E_x(y) \equiv I_D \text{ calculated with a cte } \mu_{eff}}$$

• Let us consider a small element  $dy$ .

$$\Rightarrow I_D dy = W \mu_{eff} (-Q_{in}(y)) dV(y)$$

$$\Rightarrow I_D \cdot dy = \frac{W \mu_{n0} (-Q_{in}(y)) dV(y)}{1 + \theta \frac{C_{ox}}{2\epsilon_{si}} (V_G - V_{FB} - V_{sf}(y) + \delta \sqrt{V_{sf}(y)})}$$

we substitute and integrate from source to drain.

$$\left[ \int_0^L \left\{ 1 + \theta \frac{C_{ox}}{2\epsilon_{si}} (V_G - V_{FB} - V_{sf}(y) + \delta \sqrt{V_{sf}(y)}) \right\} dy \right] = L \frac{\mu_{n0}}{\mu_{eff}} \quad (*)$$

Remark  $V_{sf}(y) = 2V_F + V_c(y)$

$$\frac{dV}{dy} \approx \frac{V_D - V_S}{L} \quad (\text{linear approximation}).$$

we can write the following identity:

$$\int_0^L [V(y) - 2\sqrt{2V_F + V_D}] dy = \frac{L}{V_D - V_S} \int_{V_D}^{V_D} [V(y) - 2\sqrt{2V_F + V_D}] dy$$

$$= \frac{L}{V_D - V_S} \left[ \frac{V_D^2}{2} - \frac{V_S^2}{2} - \frac{2}{3} \left\{ (2V_F + V_D)^{3/2} - (2V_F + V_S)^{3/2} \right\} \right]$$

introducing in (\*), we get (after calculation).

$$\frac{\mu_{no}}{\mu_{eff}} = 1 + \frac{Q_{ox}}{2\epsilon_{si}} \left[ V_G - V_T + 2\sqrt{2V_F - V_S + V_D} + \frac{2}{3} \frac{(2V_F + V_D)^{3/2} - (2V_F + V_S)^{3/2}}{V_D - V_S} \right]$$

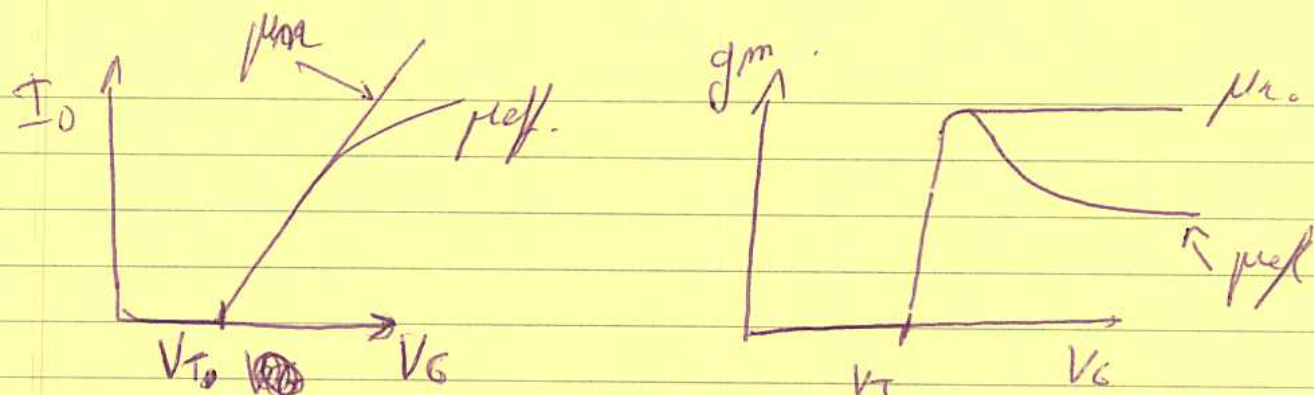
$$\Rightarrow \left[ \mu_{eff} = \frac{\mu_{no}}{1 + \frac{Q_{ox}}{2\epsilon_{si}} (V_G - V_T - V_S + 2\sqrt{2V_F + V_D})} \right]$$

~~Assuming~~ Neglecting the influence of depletion charge near the source; after simplification and also

with  $\alpha = \frac{Q_{ox}}{2\epsilon_{si}}$

$$\Rightarrow \left[ \mu_{eff} = \frac{\mu_{no}}{1 + \alpha (V_G - V_{TH} - V_S)} \right]$$





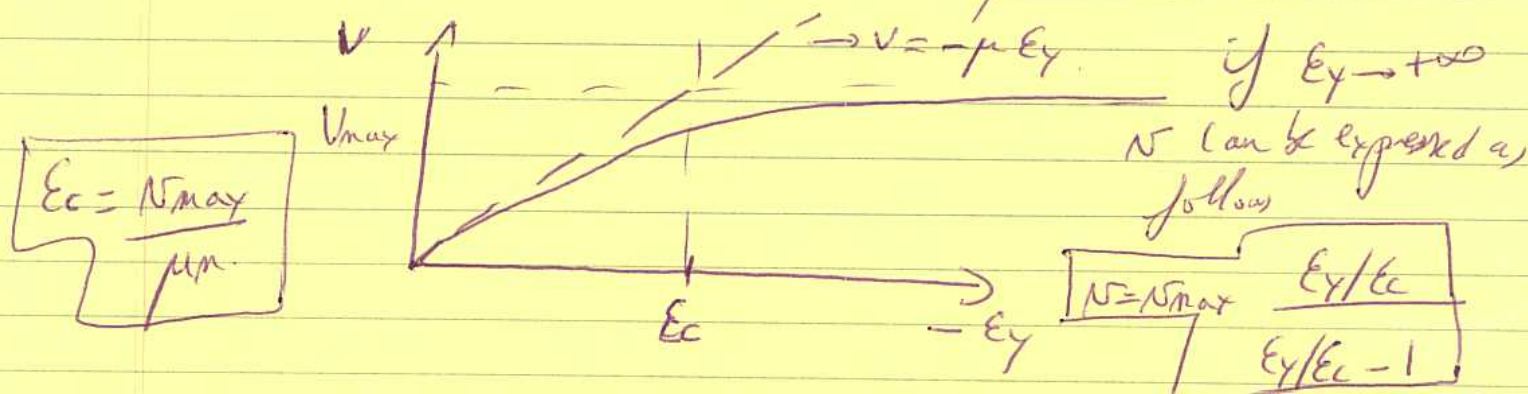
#### ④ Carrier velocity saturation

So far we consider a linear dependency of the drift current on the lateral electric field.  $\rightarrow y$

$$[q \mu_n n E_y = -q v n] \quad v = \text{velocity of carrier in the inversion layer}$$

Actually, this is wrong for low electric field only. At high electric field, and above a critical value, the carrier velocity saturates.

ex = e in silicon, max velocity is  $10^7$  cm/s



What is the impact of the velocity saturation effect on the expression of the drain current of a MOSFET.

If  $V_D \geq V_{Dsat}$   $E_y$  reaches high value near the drain junction.

The drain current is:

$$I_D = -W Q_{inv}(y) \mu_n \frac{dV(y)}{dy} = W Q_{inv} \mu_n E_y$$

If  $E_y \rightarrow +\infty$  then  $Q_{inv}(y) \rightarrow 0$ .

from  $v = v_{max} \frac{E_y / E_c}{E_y / E_c + 1}$  and using  $\begin{cases} E_c = v_{max} / \mu_n \\ E_y = -dV(y)/dy \end{cases}$

$$\Rightarrow v(y) = v_{max} \frac{-\frac{1}{E_c} \frac{dV(y)}{dy}}{-\frac{1}{E_c} \frac{dV(y)}{dy} + 1} = \mu_n \frac{\frac{dV(y)}{dy}}{1 + \frac{1}{E_c} \frac{dV(y)}{dy}}$$

The expression of the current becomes:

$$I_D = -W \left( \frac{\mu_n}{1 + \frac{1}{E_c} \frac{dV(y)}{dy}} \right) Q_{inv}(y) \frac{dV(y)}{dy}$$

just replacing  $\mu_n \rightarrow \frac{\mu_n}{1 + \frac{1}{E_c} \frac{dV(y)}{dy}}$  to account for velocity saturation



integrating from source to Drain yields

$$I_D = -\frac{W}{L} \left( \frac{\mu_n}{1 + \frac{V_{DS}}{L E_c}} \right) \int_{V_S}^{V_D} Q_{inv}(y) dV(y).$$

$$\Rightarrow I_D = \frac{W}{L} \left( \frac{\mu_n}{1 + \frac{V_{DS}}{L E_c}} \right) C_{ox} \left[ (V_G - V_T) V_{DS} - \frac{V_{DS}^2}{2} \right]$$

this is gradual model

by imposing  $\frac{dI_D}{dV_{DS}} = 0 \Rightarrow$  drain saturation voltage is

$$V_{D\text{ sat}} = L E_c \left[ \sqrt{1 + \frac{2(V_G - V_T)}{L E_c}} - 1 \right]$$

when velocity saturation is taken into account this is equivalent to making the channel longer  $L$  is multiply

by  $\left( 1 + \frac{V_{DS}}{L E_c} \right)$

Hence  $\Rightarrow$  the Drain Saturation voltage and the drain saturation current are reduced.

## Characteristics.

### (5) Subthreshold current

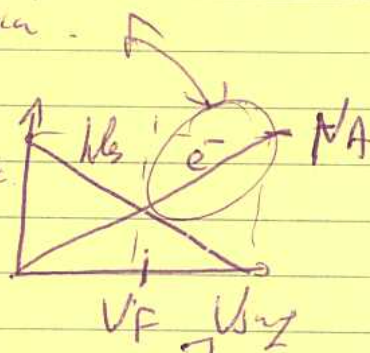
(a) Subthreshold current

So far we assumed that  $I_D = 0$  if  $V_G \ll V_t$

Actually there is a significant amount of  $e^-$  near the surface if the device operates at below strong inversion.

$$V_F < V_{surf} < 2V_F$$

Reminds Log current



[The actual dependence of the  $e^-$  concentration at the surface is an exponential function of  $V_{surf}$ ]

⇒ Experimentally we have that the Drain current below threshold "subthreshold current" is independent of the drain voltage. ⇒ This means that the subthreshold current is caused by diffusion rather than drift mechanism.

current density from source to Drain  
can be written

$$J_{ny} = -qD \frac{dn}{dy} \Rightarrow \boxed{I_D = qA D n \frac{mole}{cm^2} \frac{cm}{s}}$$

A is the cross-sectional area of the channel region.



$e^-$  density at the ~~center~~ edge of source and drain =

$$n(0) = n_{p0} \exp\left(\frac{qV_{\text{surf}}}{k_B T}\right)$$

$$n(L) = n_{p0} \exp\left(\frac{q(V_{\text{surf}} - V_0)}{k_B T}\right)$$

$$n_{p0} = \frac{n_i^2}{N_A}$$

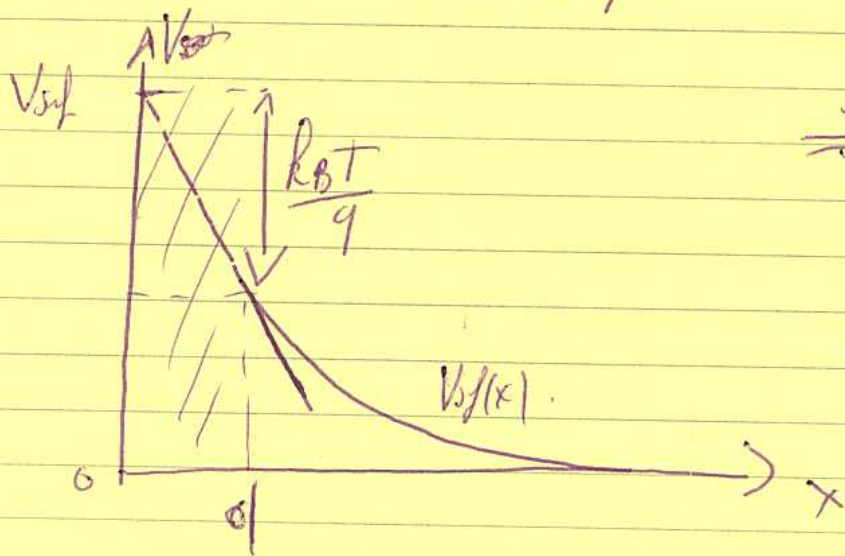
( $\rightarrow$  Source is considered here at ground).

what is the area  $A$ ?

we know that the  $e^-$  density varies as  $\exp\left(\frac{qV_{\text{surf}}}{k_B T}\right)$  near the surface. we however going to

approximate the exp-profile by a constant  $e^-$  density extending to a depth  $d$  below the surface.

The depth  $d$  is defined as the depth at which the potential has decreased by  $k_B T / q$ . Below the surface potential value



$$\Rightarrow \text{so } A = W \times d$$

$W$  (width of the transistor)

$$d = \frac{k_B T / q}{E_s} \quad E_s = -\frac{dV(x)}{dx} \Big|_0$$

Using the ~~inverted~~ Einstein relationship  $\mu_n \frac{k_B T}{q} = D_n$

we get the subthreshold current

$$I_D = \mu_n \frac{W}{L} q \left( \frac{k_B T}{q} \right) \frac{n_i^2}{N_A} \left[ 1 - \exp(-qV_D/k_B T) \right] \times \exp(qV_{GS}/k_B T) \cdot \frac{dV_{GS}}{dx}$$

The electric field at the surface  $E_s$  is given by

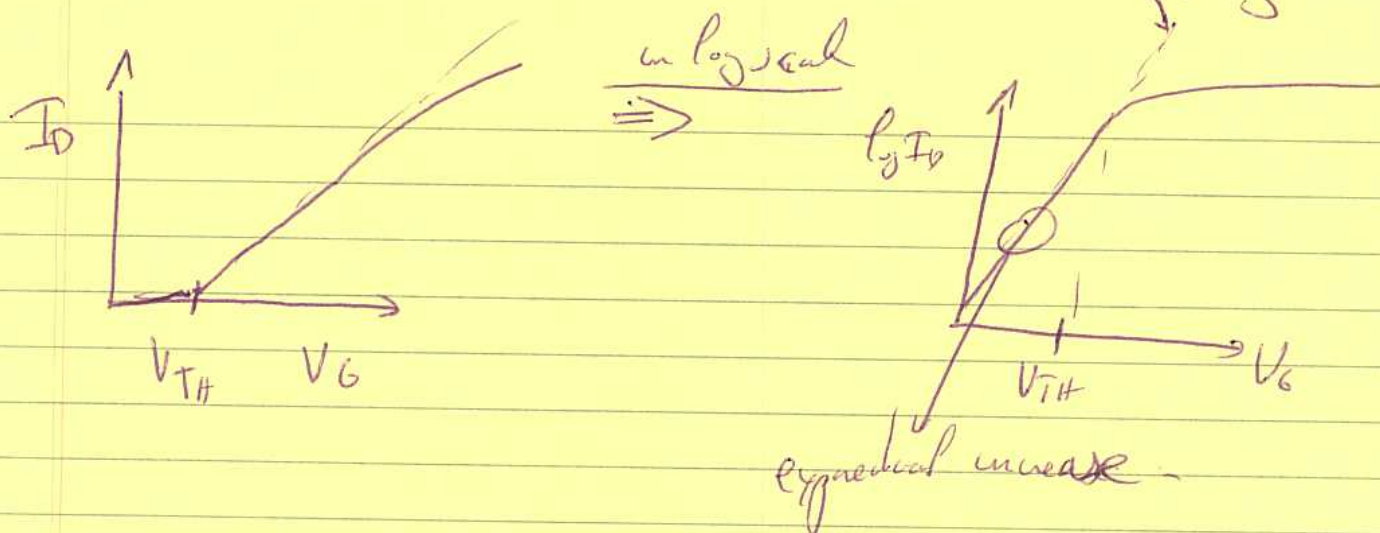
(Max capacitor relation)  $-\frac{dV_{GS}}{dx} \bigg|_{x=0} = E_s = \sqrt{\frac{2q N_A \psi_s}{\epsilon_{Si}}}$

$$\Rightarrow E_s = \frac{q N_A}{C_D}$$

$\Rightarrow I_D$  is independent of  $V_D$  as long as  $V_D$  is larger than a few  $\frac{k_B T}{q}$ . (exponential term  $\rightarrow 0$ )

$\Rightarrow I_D$  also increases exp. with the surface potential.





### ⑤ Subthreshold slope

it is  $\frac{1}{S}$  (inverse of the slope)  $\Rightarrow$   $\boxed{S = \frac{dV_G}{d \log(I_D)}}$

$\Rightarrow$  represent how many millivolts per decade.

$\Rightarrow$  "how many millivolts  $V_G$  be increased to increase  $I_D$  by a factor 10"

$\downarrow S \downarrow$  efficiency and switching speed of the device from off-state to on-state  $\uparrow$

$$S = \frac{\ln(10)}{\frac{d(\ln(I_D))}{dV_G}}$$

$$\log_{10} \rightarrow \log_e \equiv \ln$$

Also  $\frac{d(\ln(I_D))}{dV_G} = \frac{d(\ln I_D)}{dV_{GS}} \frac{dV_{GS}}{dV_G}$

$$\frac{d \ln(I_0)}{dV_{\text{bias}}} = \frac{d}{dV_{\text{bias}}} \left[ \ln \left( e^{\frac{qV_{\text{bias}}}{k_B T}} \right) - \ln \left( \frac{dV_{\text{biat}}}{dx} \right) \right]$$

$$= \left[ \frac{q}{k_B T} - \frac{\frac{d}{dV_{\text{bias}}} \left( -\frac{dV_{\text{biat}}}{dx} \right)}{-\frac{dV_{\text{biat}}}{dx}} \right] \quad (*)$$

$$\frac{d}{dV_{\text{bias}}} \left( -\frac{dV_{\text{biat}}}{dx} \right) = \cancel{\frac{d}{dV_{\text{bias}}}} \frac{C_D}{\epsilon_{\text{Si}}} \quad \leftarrow \text{(from Poisson)}$$

$$C_D \text{ is depletion capacitance} \quad \left[ C_D = -\frac{dQ_d}{dV_{\text{biat}}} \right] = \frac{\epsilon_{\text{Si}}}{x_d}$$

$$\Rightarrow \frac{\frac{d}{dV_{\text{bias}}} \left( -\frac{dV_{\text{biat}}}{dx} \right)}{-\frac{dV_{\text{biat}}}{dx}} = \frac{C_D^2}{q N_A \epsilon_{\text{Si}}} = \frac{1}{2 V_{\text{biat}}}$$

in weak inversion regime  $V_F < V_{\text{bias}} < 2V_F$ ,

$\frac{1}{2 V_{\text{biat}}}$  is small compared to  $\frac{q}{k_B T} \Rightarrow$  it can be neglected in  $(*)$ .

$$\boxed{\frac{d(\ln(I_0))}{dV_G} \approx \frac{q}{k_B T} \frac{dV_{\text{biat}}}{dV_G}}$$



Also 
$$V_G = V_{FB} + V_{bi} - \frac{Q_d}{C_{ox}}$$

$$\Rightarrow \frac{dV_{bi}}{dV_G} = \left(1 + \frac{C_D}{C_{ox}}\right)^{-1} \left[ \frac{dQ_d}{dV_G} \frac{dV_G}{dV_G} \right]$$

$\Rightarrow$  finally

$$S = \frac{k_B T}{q} \ln(10) \left(1 + \frac{C_D}{C_{ox}}\right)$$

$$\left(1 + \frac{C_D}{C_{ox}}\right) = \frac{n}{1}$$

body factor

Also since  $\frac{d(\ln I_D)}{dV_G} = \frac{q}{k_B T}$

$$\Rightarrow I_D \propto \exp\left(\frac{qV_G}{n k_B T}\right)$$

The subthreshold current varies exponentially as a function of the gate voltage.

x In case where we consider interface state, (or traps) in the  $Si$  energy bandgap at the silicon/oxide interface. One can ~~define~~ associate a ~~charge~~ change of the interface state  $Q_{it}$ .

$$\Rightarrow C_{it} = -\frac{dQ_{it}}{dV_{bi}}$$

we get after calculations.

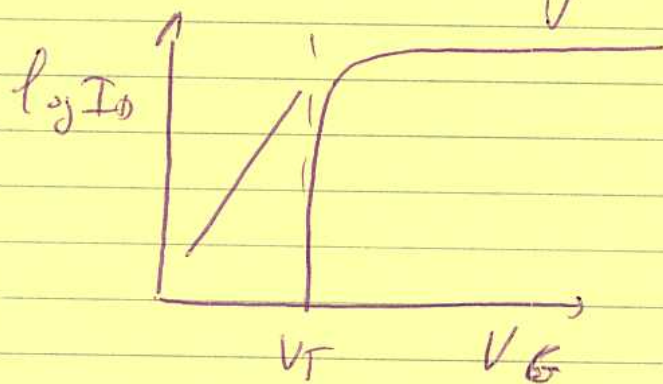
$$S = \frac{k_B T}{q} \ln(10) \left( 1 + \frac{C_D + C_{it}}{C_{ox}} \right)$$

$$= 60 \left( 1 + \frac{C_D + C_{it}}{C_{ox}} \right) \text{ mV/decade}$$

at room temperature

## (6) Continuous model

The model developed so far for  $V_G > V_T$  or for  $V_G < V_T$  do not connect well around  $V_G = V_T$  (discontinuity). Since often  $V_G$  is close to  $V_T$ , this is a problem.



A model which is valid everywhere can be derived.



Indeed, 
$$I_D = \mu_n C_{ox} \frac{W}{L} \int_{V_S}^{V_D} - \frac{Q_{inv}(y)}{C_{ox}} d(V(y))$$

can be rewritten

$$I_D = \mu_n C_{ox} \frac{W}{L} \left\{ \int_{V_S}^{V_P} - \frac{Q_{inv}(y)}{C_{ox}} d(V(y)) - \int_{V_P}^{V_P} - \frac{Q_{inv}(y)}{C_{ox}} d(V(y)) \right\}$$

$V_P = (V_G - V_T) \equiv$  channel saturation voltage if source is grounded and  $V_G > V_T$

$$I_D = I_F - I_R$$

forward  
current

Reverse current

It is possible to find a mathematical function which describes the evolution of the current as a function of gate and drain voltage for all regime of operation (depletion, weak and strong inversion)

$\Rightarrow$  Emz, Krummenacker, Uttox

$\Rightarrow$  EKV Model

$$I_D = 2\mu_n C_{ox} \frac{W}{L} \left( \frac{k_B T}{q} \right)^2 \left\{ \frac{1}{4} \left( \ln \left( 1 + \exp \left( \frac{V_P - V_S}{2 k_B T / q} \right) \right) \right)^2 - \frac{1}{4} \left( \ln \left( 1 + \exp \left( \frac{V_P - V_D}{2 k_B T / q} \right) \right) \right)^2 \right\}$$

For example:

if  $V_s = 0$ ,  $V_D < V_P$   $V_G > V_T \Rightarrow$  the transistor operates in non-saturated regime.  
 $\Rightarrow$  exponential terms  $\gg 1$

$$I_D = 2 \mu_n C_{ox} \frac{W}{L} \left[ \frac{k_B T}{q} \right]^2 \left[ \left( \frac{V_P}{2 k_B T / q} \right)^2 - \left( \frac{V_P - V_D}{2 k_B T / q} \right)^2 \right]$$

$$= \frac{1}{2} \mu_n C_{ox} \frac{W}{L} [2 V_D V_P - V_D^2]$$

$\Rightarrow$  quadratic model

$$I_D = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} \left[ (V_G - V_T) V_D - \frac{V_D^2}{2} \right]$$

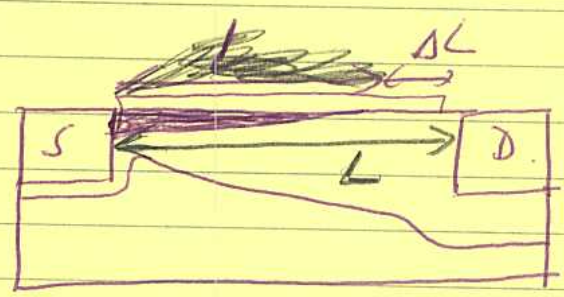
## ⑦ Channel length modulation

Previously we assumed that when  $V_D > V_{Dsat}$ , the Drain current of a MOSFET is constant and equal to  $I_{Dsat}$ .

Actually if  $V_D >$  beyond  $V_{Dsat}$ , the depletion region and local threshold voltage near the Drain are increased



The effective length of the channel is  $L - \Delta L$   
 (channel length modulation)

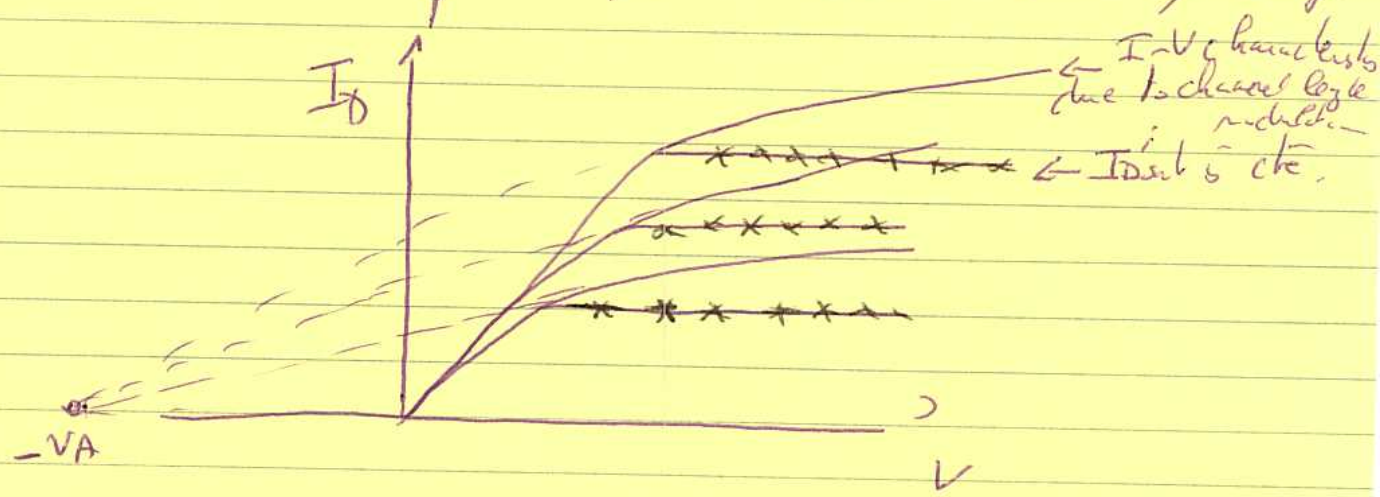


and shorter channel length  $\Rightarrow$  increase in Drain current.

If  $I_{Dsat}$  is obtained if  $(V_D = V_{Dsat})$   
 if  $V_D > V_{Dsat}$

$$I_{Dsat}' = I_{Dsat} \left( 1 + \frac{V_D - V_{Dsat}}{V_A + V_{Dsat}} \right)$$

where  $V_A$  is a positive voltage value that can be obtained experimentally.  $V_A$  is called "early voltage"



in term of channel length modulation, we get

$$\frac{I_{Dsat}}{L} = \frac{I_{Dsat}}{L - \Delta L}$$

$$\Rightarrow \Delta L = L \left[ 1 - \frac{1}{1 + \frac{V_D - V_{Dsat}}{V_A + V_{Dsat}}} \right]$$

The saturation output ~~current~~ conductance, which was previously considered equal to zero, is now given by:

$$g_{Dsat} = \frac{dI_{Dsat}}{dV_D} = \frac{I_{Dsat}}{V_A + V_{Dsat}} \approx \frac{I_{Dsat}}{V_A}$$

\* The channel length modulation effect. Typically increases in small devices with low-doped substrates.

\* Finger Doping can reduce the channel length modulation by increasing the doping density (as the gate length is reduced)



## ⑧ Short-channel effect

evolution of semiconductor processing technology enables scaling of transistors -

Ex gate length of MOSFET used in 256K DRAM in 1984 was  $\sim 1.2 \mu\text{m}$ .

in 1994, 64 M DRAM were produced using  $0.4 \mu\text{m}$

prediction 50nm in 2009  
35nm in 2012.

~~aggressive~~ aggressive scaling  $\Rightarrow$  undesirable effects including the short-channel effect.

Here the depletion layer widths of the source and drain junction become comparable to the channel length.

Let us look at the threshold  $V_T = V_{FB} + 2V_F - \frac{Q_d}{C_{ox}}$   
where  $Q_d$  can be represented by a trapezoidal area.



Area of the trapezoid is  $\frac{(L+L_1)x_{dmax}}{2}$ .

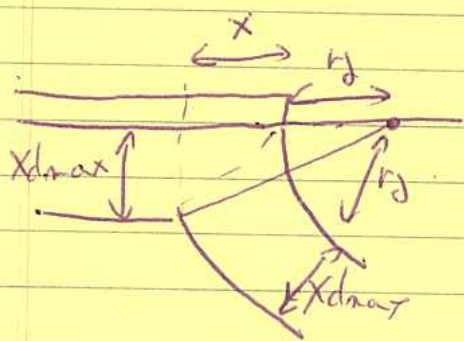
• if the channel is long  $L \approx L_1 \Rightarrow$  area  $\approx L x_{dmax}$  (Rectangular area)

$V_t$  is then accurately described by the equation derived previously.

• if the channel (gate) is short  $L_1 < L$ , then the depletion charge due to  $V_G$  under the gate electrode is reduced.

Consider that  $V_G = V_T$  and  $V_{DS} \approx 0$ .

Based on geometrical consideration we get:



$$x_{dmax}^2 + (x + r_d)^2 = (r_d + x_{dmax})^2$$

Here we suppose also that the built-in potential of the source and drain junction is approximately equal to  $2V_F$   
 $\Rightarrow$  width of the depletion region around source and drain is then  $\approx x_{dmax}$

$$\Rightarrow x^2 + 2r_d x - 2r_d x_{dmax} = 0$$

where

$$x = -r_d \pm \sqrt{r_d^2 + 2r_d x_{dmax}} = r_d \left[ \frac{1}{2} \left( 1 \pm \sqrt{1 + \frac{2x_{dmax}}{r_d}} \right) \right]$$

$\Rightarrow x$  must be positive. So



$L_1$  then is given by

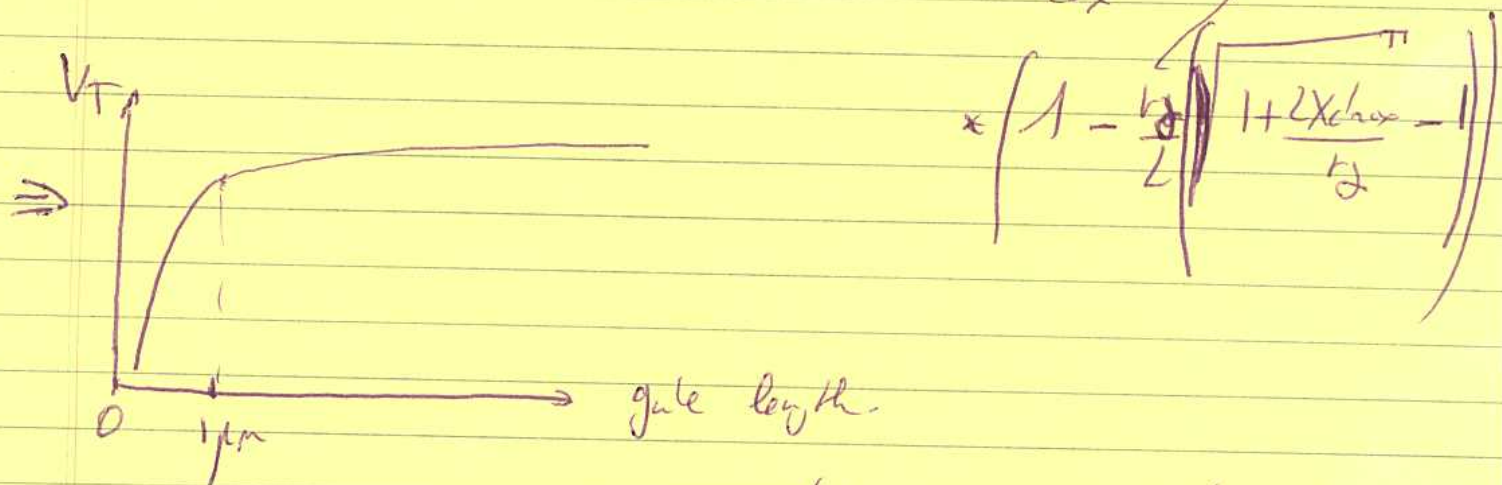
$$L_1 = L - 2x = L - 2r_j \left( \sqrt{1 + \frac{2X_{dmax}}{r_j}} - 1 \right)$$

The depletion charge controlled by the gate voltage is

$$Q_d = -q X_{dmax} N_A \left( \frac{L + L_1}{2} \right) \\ = -q X_{dmax} N_A L \left( 1 - \frac{r_j}{L} \left( \sqrt{1 + \frac{2X_{dmax}}{r_j}} - 1 \right) \right)$$

$\Rightarrow$   $Q_d$  which is the depletion charge if the depletion region would be considered rectangular.

$$V_T = V_{FB} + 2V_F - \frac{Q_d}{C_{ox}} = V_{FB} + 2V_F + \frac{q X_{dmax} N_A}{C_{ox}}$$



in short devices. Small statistical variations in gate length give rise to large statistical variations of  $V_T$  (problem of reproducibility in integrated circuits)

### Remarks

- The short channel effect can be reduced by using shallower junctions and higher substrate doping  $\Rightarrow$  to reduce the extension of the source & Drain depletion regions in the channel.
- if the gate length is very small and  $V_{DS}$  is high enough, the source and Drain depletion region can touch one another  $\psi_1 < 0 \Rightarrow$  the potential in the channel region is no longer controlled by the gate and a large current can flow from source to Drain.  
 $\Rightarrow$  this is called "punchthrough"