

1.1 Eigenvalues of a real and symmetric matrix

Prove that a real and symmetric matrix has three real eigenvalues and three corresponding orthogonal eigenvectors.

1.2 Similarity transformations

Consider a square matrix, \mathbf{A} , select a nonsingular square matrix, \mathbf{P} , whose dimensions match those of \mathbf{A} , and compute the new matrix $\mathbf{B} = \mathbf{P}^{-1} \cdot \mathbf{A} \cdot \mathbf{P}$. This operation is called a similarity transformation, and we say that the matrix \mathbf{B} is similar to \mathbf{A} . Show that the eigenvalues of the matrix \mathbf{B} are identical to those of \mathbf{A} ; thus, similarity transformations preserve the eigenvalues.

1.3 Momentum tensor

Show that the matrix $\rho u_i u_j$ is a second-order tensor, called the momentum tensor.

1.4 Rigid-body rotation

Compute the velocity gradient tensor, rate-of-deformation tensor, and vorticity of a two-dimensional flow expressing rigid-body rotation where $u_r = 0$ and $u_\theta = \Omega r$, where Ω is a constant.

1.5 Flow due to the motion of a rigid body

Consider the flow due to the steady motion of the rigid body translating with velocity \mathbf{U} and rotating about the origin with angular velocity Ω in an otherwise quiescent fluid of infinite expanse. In a frame of reference fixed on the body, the flow is steady. Explain why the velocity field must satisfy the equation

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{U} + \Omega \times \mathbf{x}) \cdot \nabla \mathbf{u}.$$

1.6 Boundary condition on a propagating wavy material line

Consider a material line in the xy plane described by the function $y = a \sin[k(x - ct)]$, where k is the wave number and c is the phase velocity. Derive a boundary condition for the velocity.