

Project Crossroads Vehicular Ad-Hoc Network for Collision Warning



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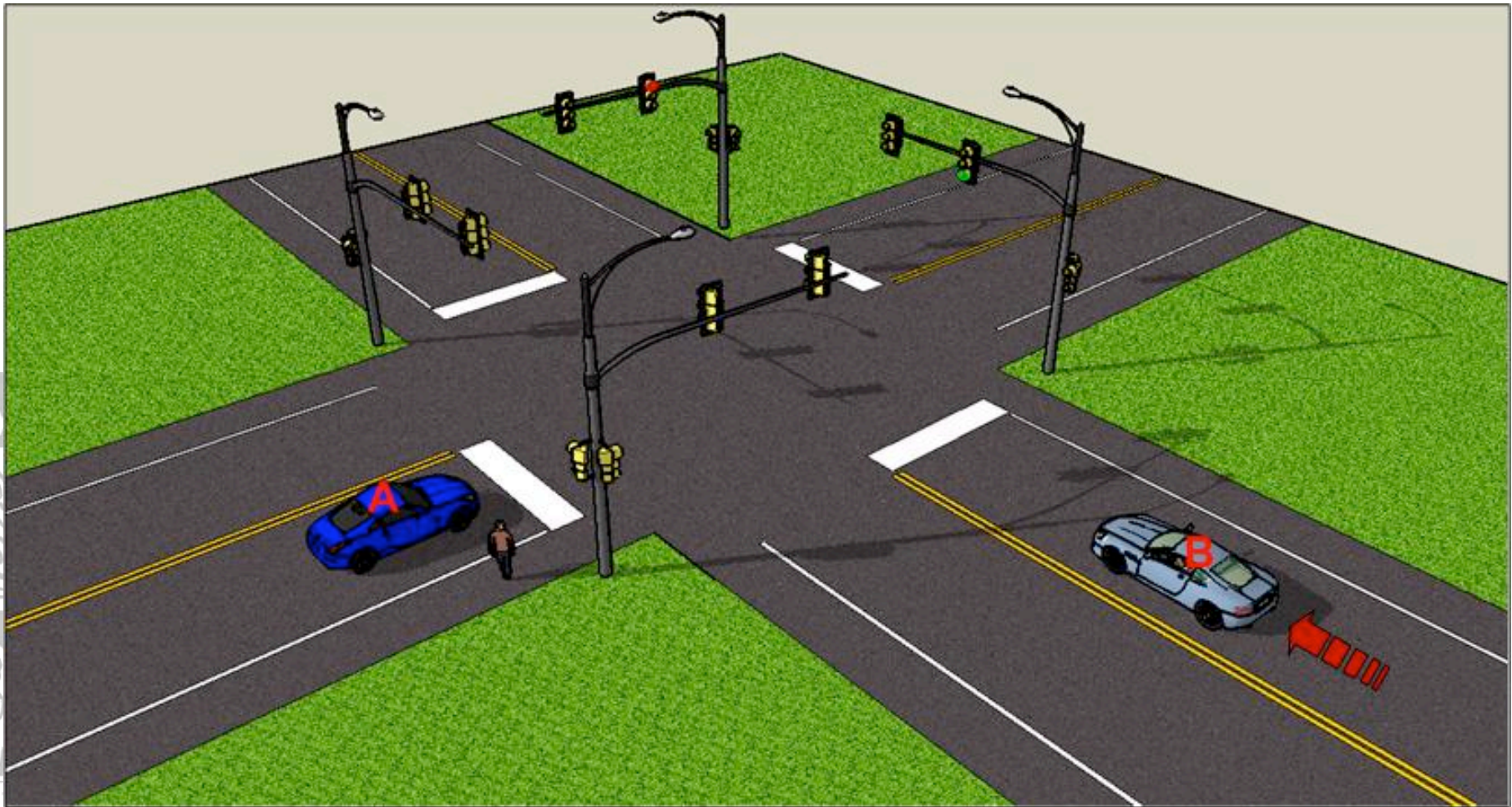
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Outline

- Introduction Scenario
- Motivation
- Proposed Solution/Theory of Operation
- Design Constraints
- Block Diagrams
- Time Scenario
- Field Testing
- Realized System
- Conclusion

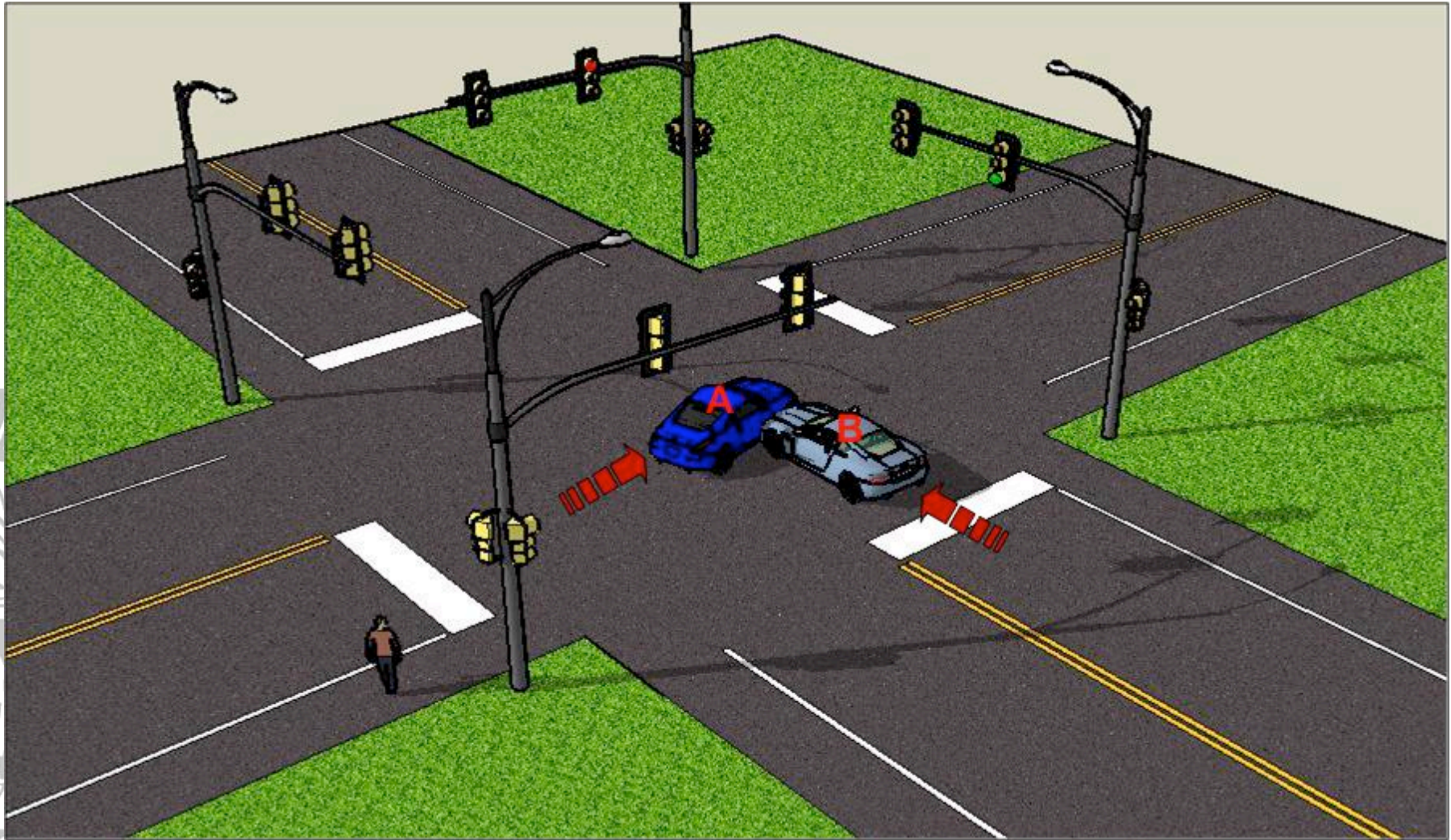


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Introduction Scenario



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Motivation

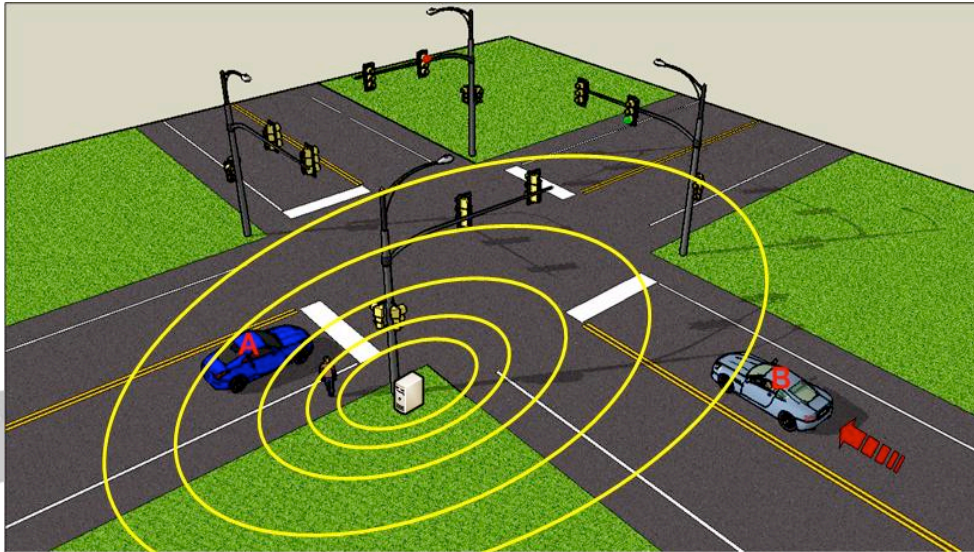
- In the United States of America
 - 45% of all collisions occur at intersections
 - 21% of these are fatal (9213 Total in 2003)
 - More than one person per hour
- Result: Lost Lives, Money, and Time
- Considered High Priority by DOT
- Currently No Adequate Solution
- Easily Adaptable to Other Scenarios



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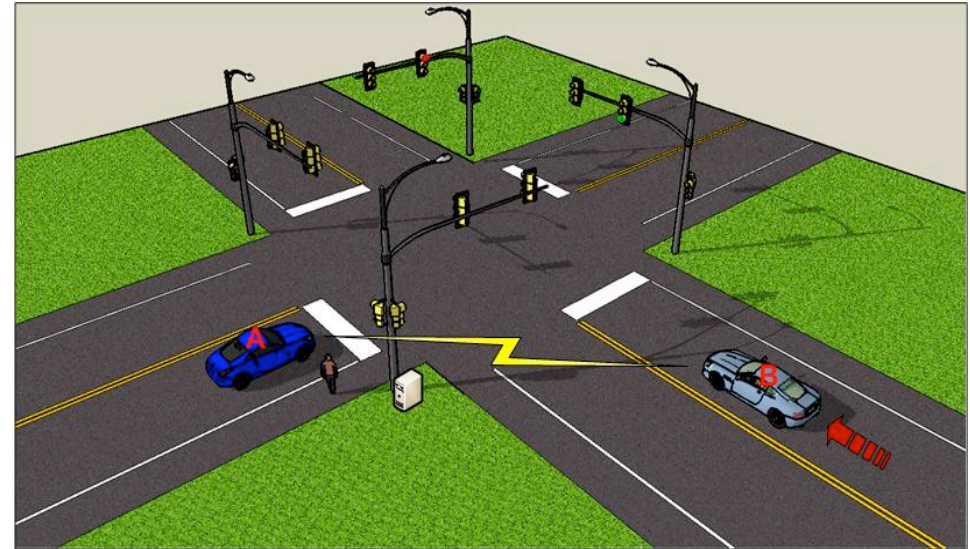
Proposed Solution

Roadside-to-Vehicle Communication Roadside Equipment (RSE)



- RSE broadcasts environment variables
 - Stop light conditions
 - Stop line coordinates
 - Intersection ID

Vehicle-to-Vehicle Communication Onboard Equipment (OBE)



- OBE
 - Obtains speed, location from GPS
 - Obtains intersection info from RSE
 - Calculates warning possibility



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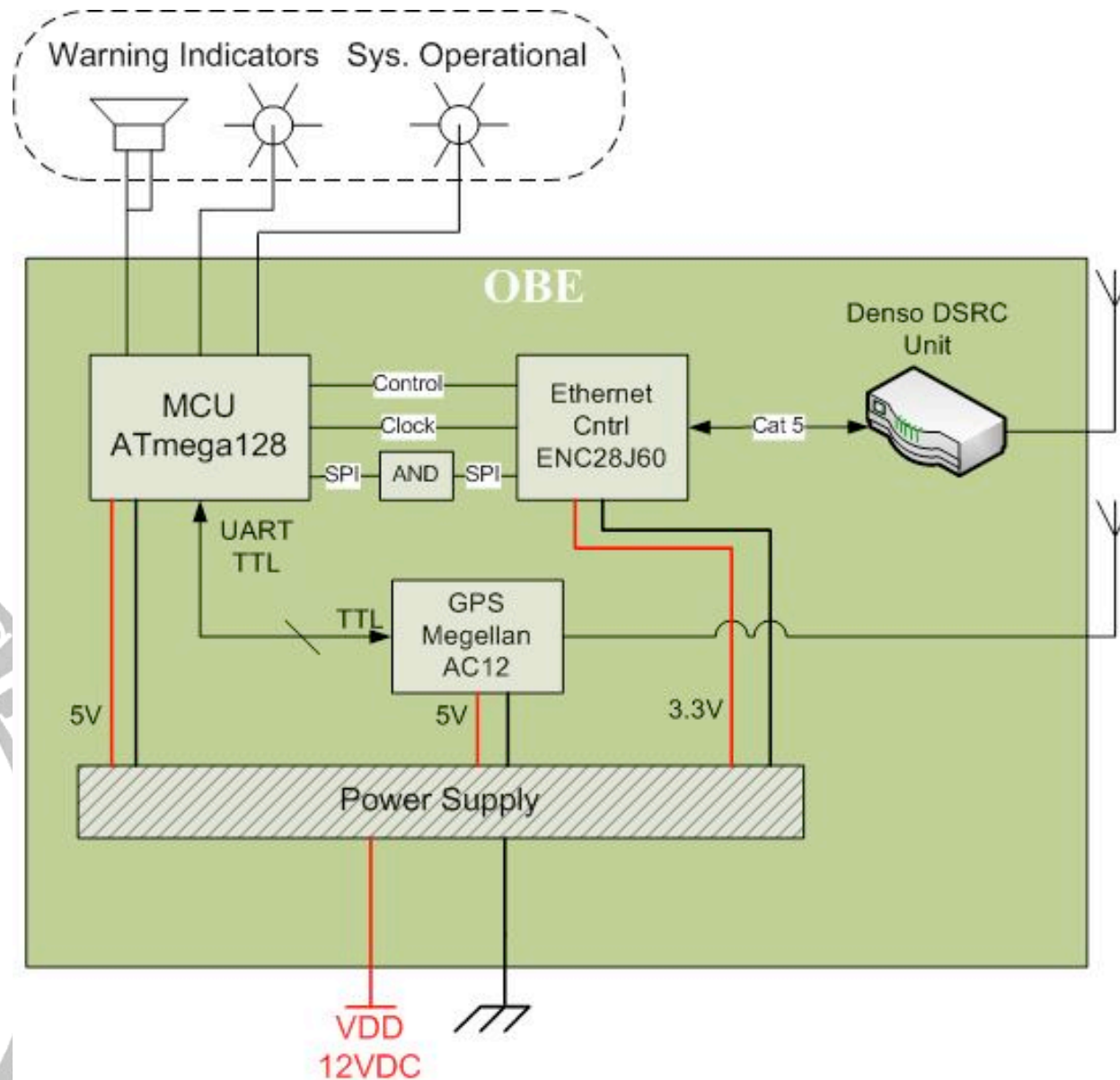
Design Constraints

- Strict Timing Constraints
 - Safety Critical
 - Consideration toward Human Reaction
- Budget
- GPS Accuracy (within 1.5 meters)
- Debug Interface for Testing
- Non-Invasive User Interface
- Modular Design for Future Adaption
 - Interface with OBD-II
 - Future Transportation Applications



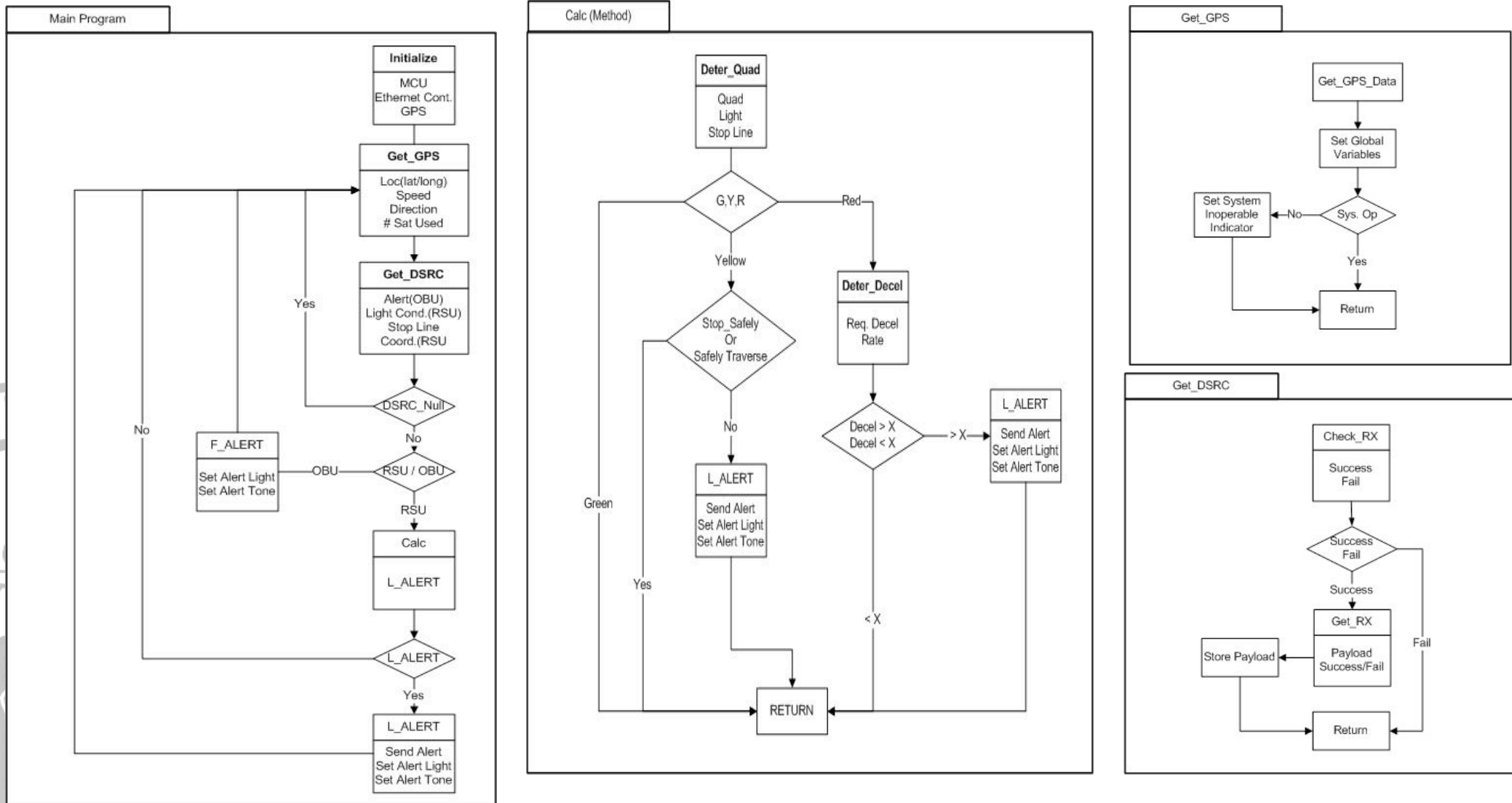
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OBE Block Diagram



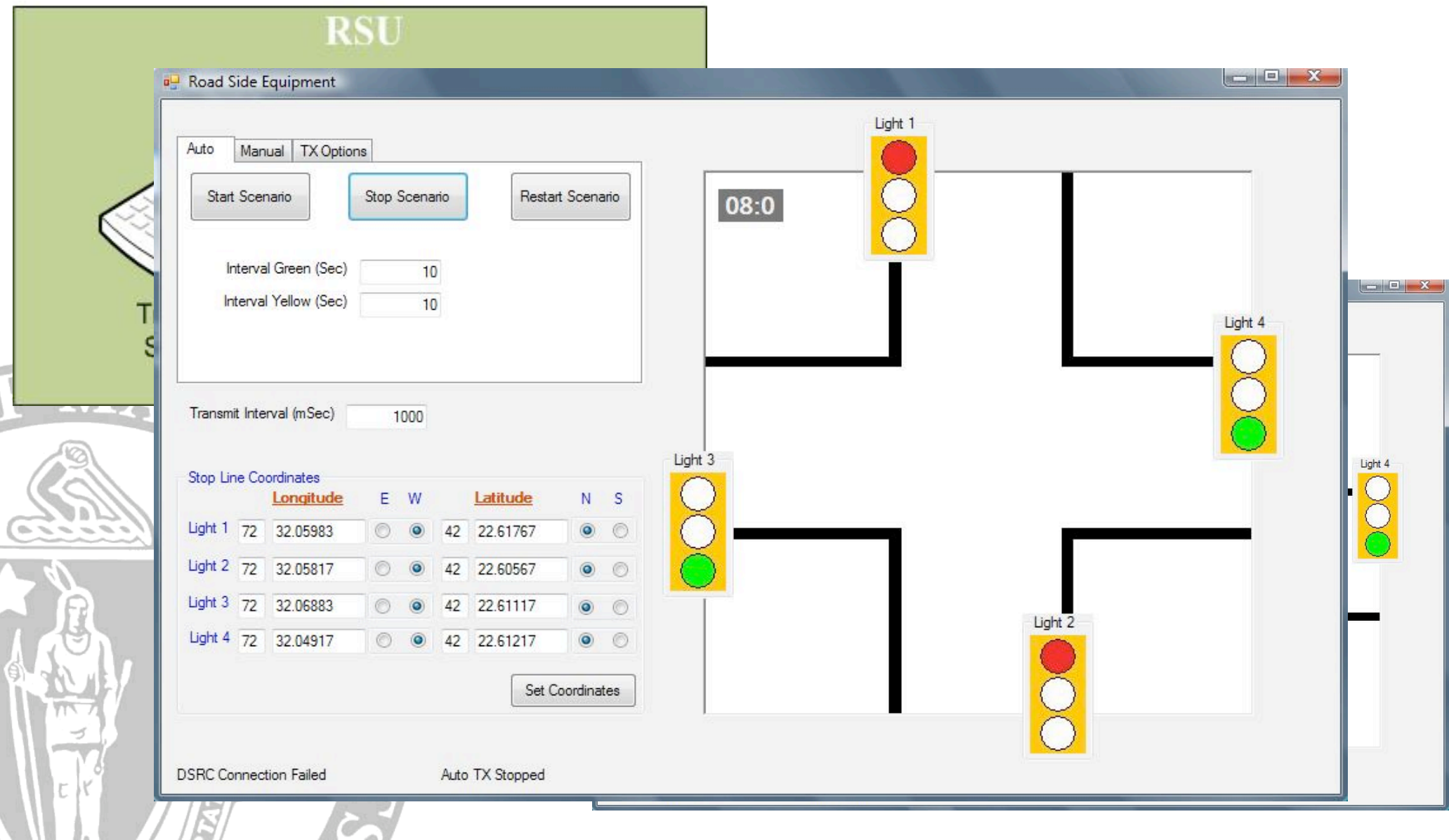
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OBE Flow Diagram



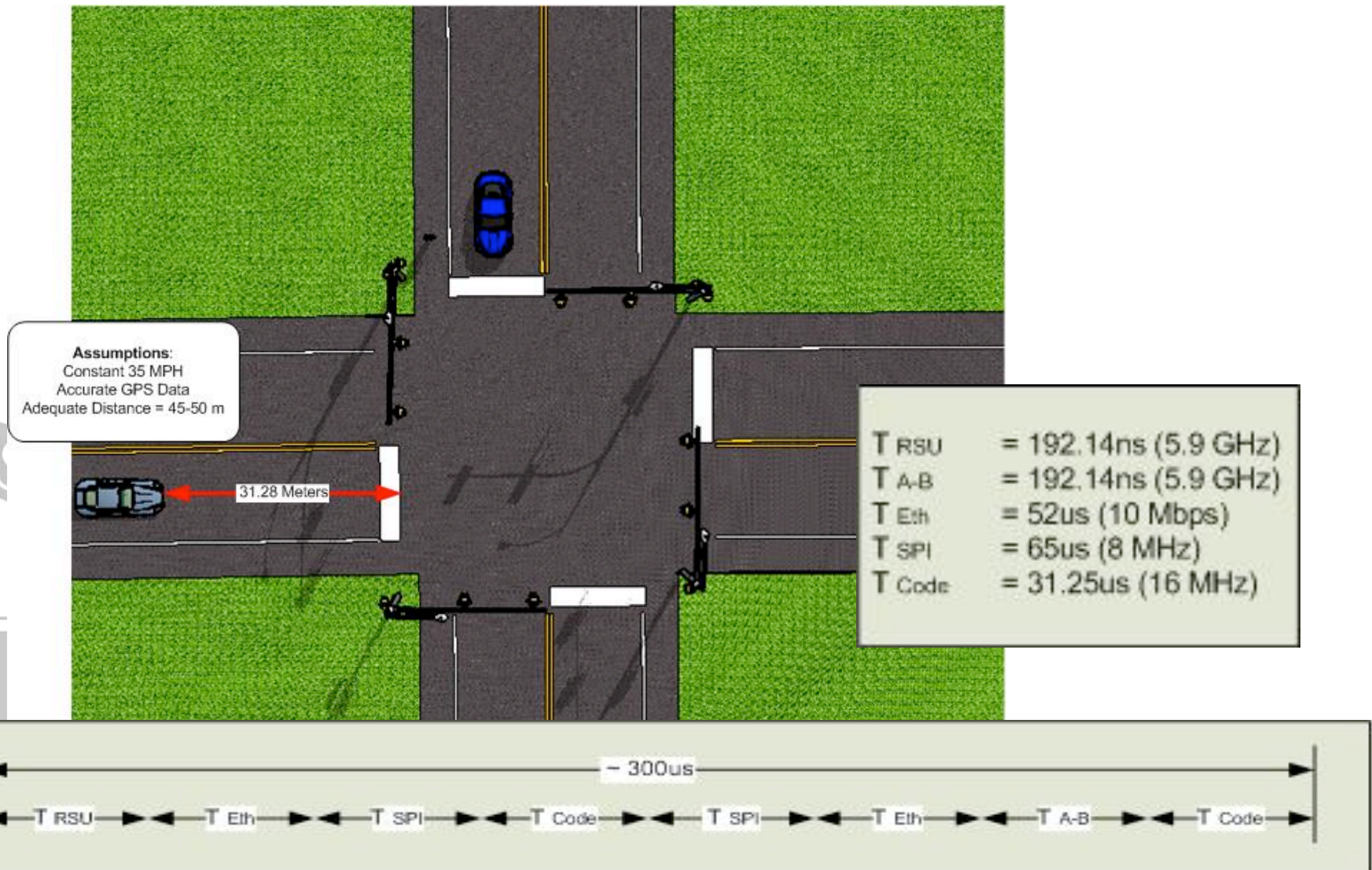
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RSE Block Diagram



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Timing Scenario

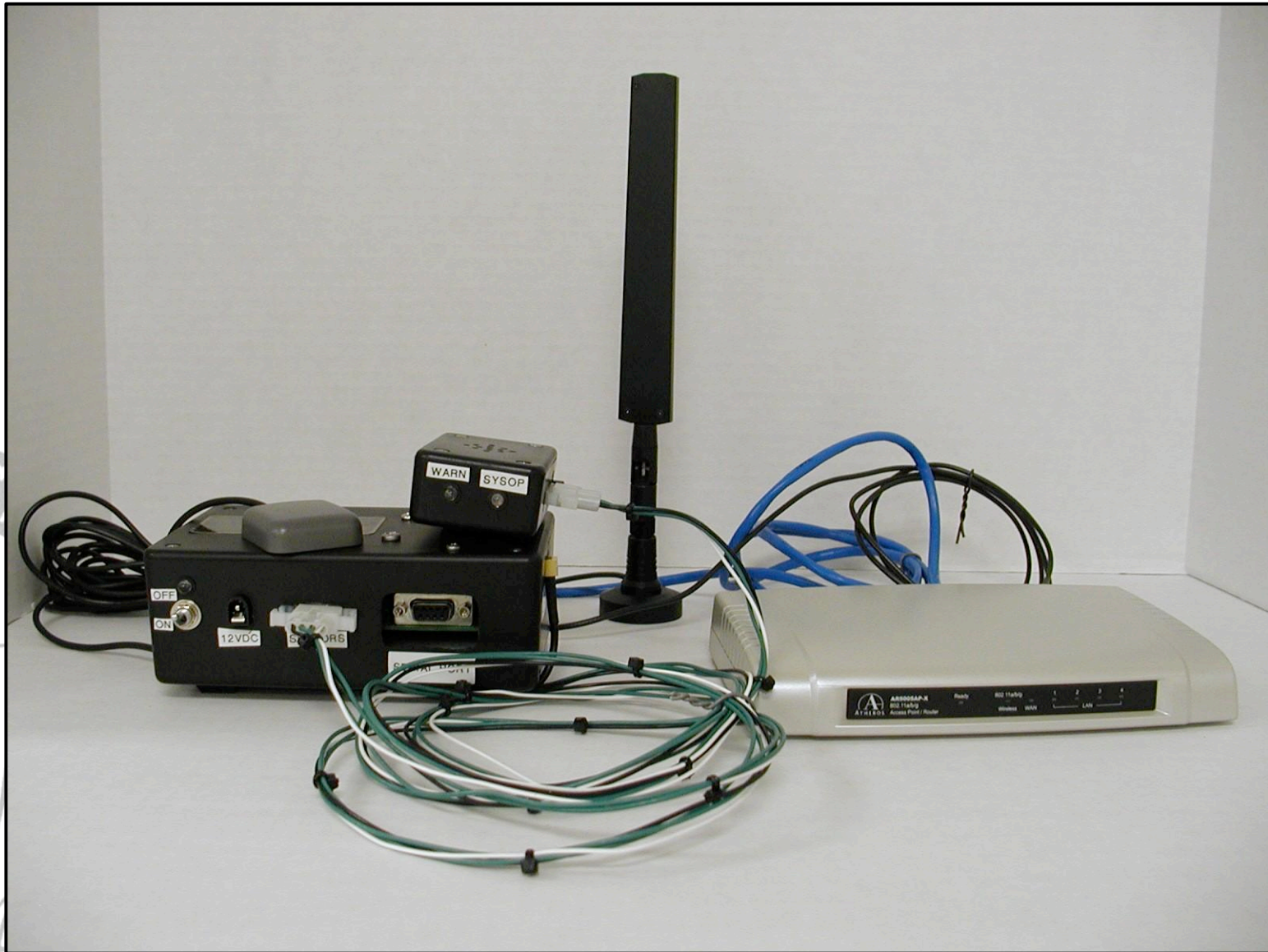


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- Conducted at UMass Football Stadium
- Utilized the RSE for Virtual Traffic Scenarios



UMassAmherst Realized System



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Concluding Remarks

- Functional Testing
- Restrictions with DSRC
- Inaccuracies of GPS
- Full Scale Implementation
 - RSE Integration
 - OBE Integration
- Future Adaptability

