


ECE 354
Assembly Tutorial

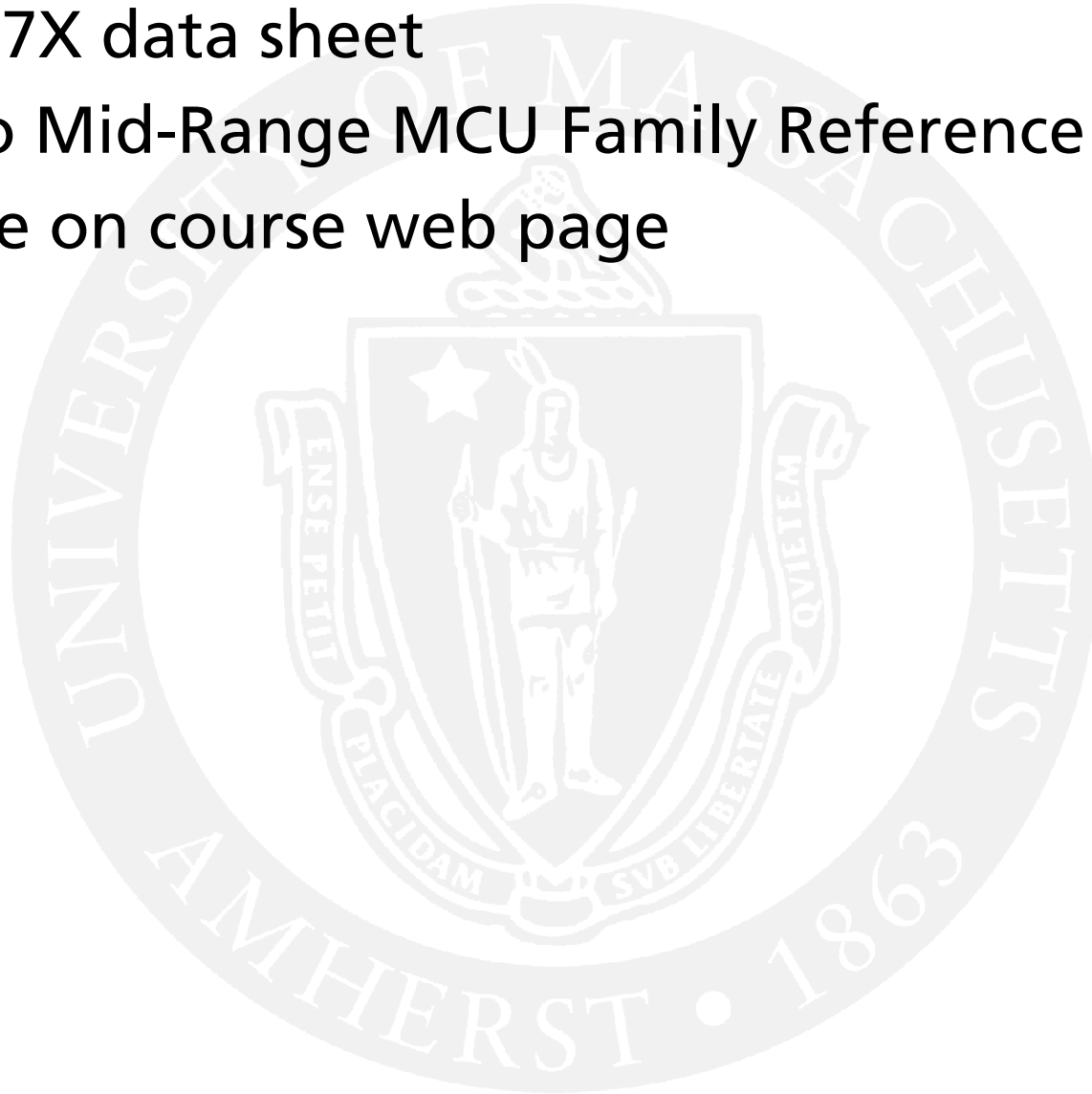
02/04/03

Outline

- Scope
- PIC 16F877 architecture overview
- PIC assembly
 - Instruction set examples
 - Assembler directives
 - Subroutines
 - Interrupts
- Common code examples

Reference Material

- PIC 16F87X data sheet
- PICMicro Mid-Range MCU Family Reference Manual
- Available on course web page

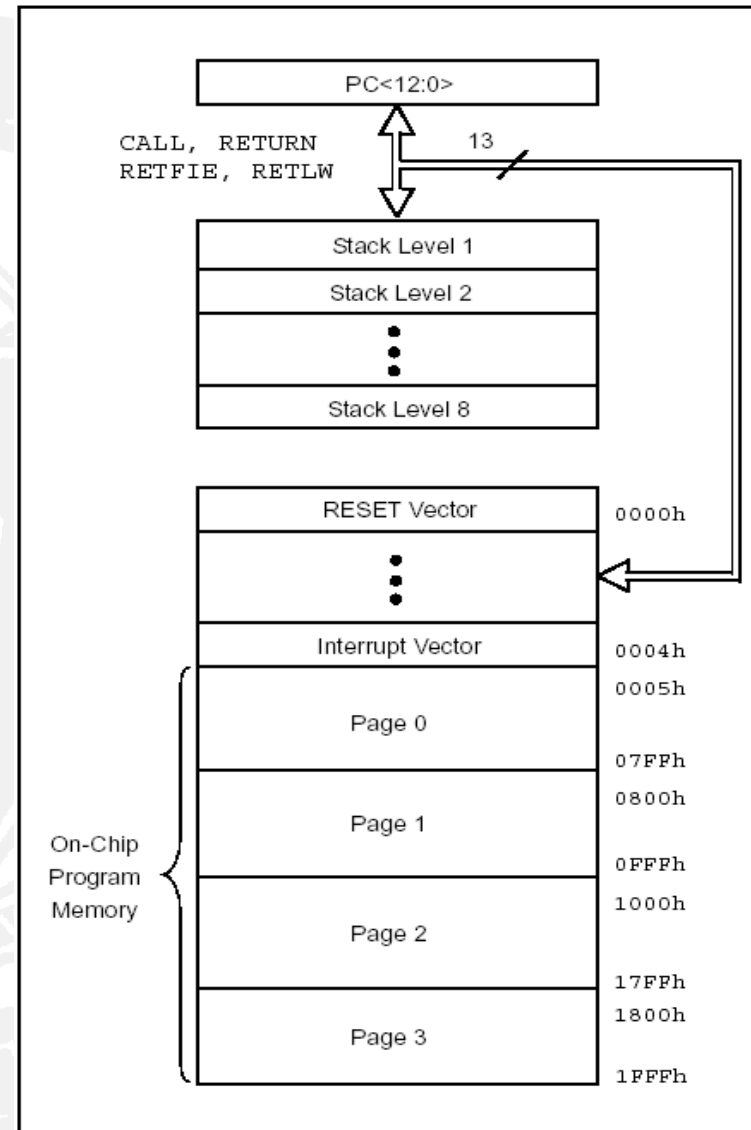


PIC16F877 Architecture Overview

- RISC CPU
- Harvard architecture
 - Program storage 8k x 14 bit
 - Data storage 256 x 8 bit, 384 x 8 bit
- 35 instructions
 - 14 bit instructions
 - 8 bit data values

Program Memory

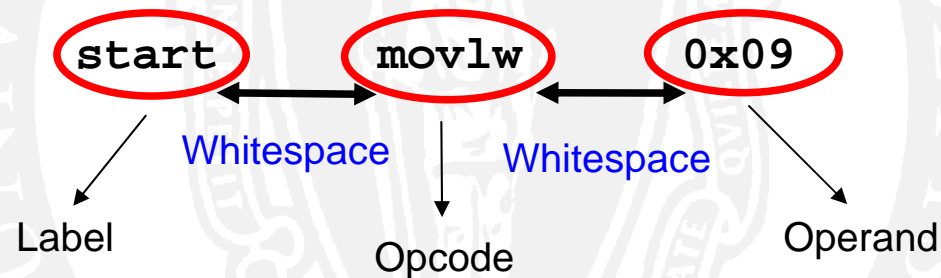
- 13 bit program counter
- Divided into 4 banks
- Important locations
 - 0x00 reset vector
 - 0x04 interrupt vector
- Programs start **AFTER** 0x04
- 8 level deep stack



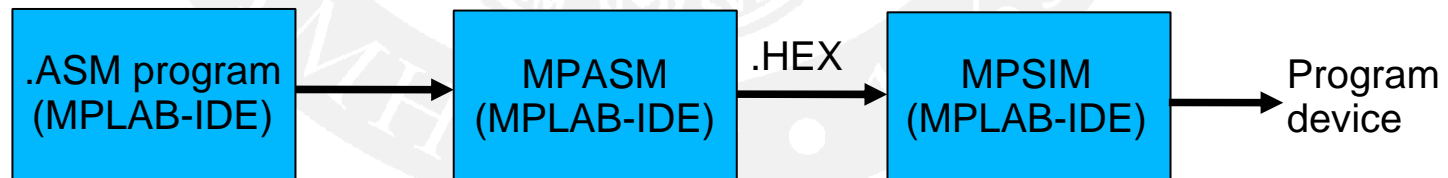
PIC Assembly Format

Column 1	Column 2	Column 3
Label, constants	Assembly opcode	Operands

Example :



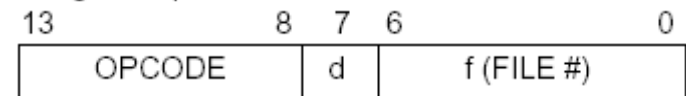
Assembly flow :



Instruction Format

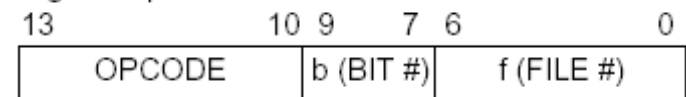
- 3 instruction types
 - Byte oriented
 - Bit oriented
 - Literal and control
- Full instruction listing in datasheet and Peatman
- All instructions take one cycle except conditional

Byte-oriented file register operations



d = 0 for destination W
d = 1 for destination f
f = 7-bit file register address

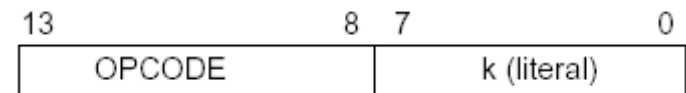
Bit-oriented file register operations



b = 3-bit bit address
f = 7-bit file register address

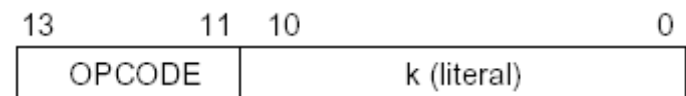
Literal and control operations

General



k = 8-bit literal (immediate) value

CALL and GOTO instructions only



k = 11-bit literal (immediate) value

Instruction Examples

- Byte oriented operations
 - **ADDWF f,d**
 - Add contents of W with register f
 - If d=0 store result in W else store in register f
 - Example : `addwf 0x20,0`
 - Can use constants to refer to file registers (recommended)
 - **CLRF f**
 - Contents of register f are cleared and Z bit (STATUS) is set
 - Example : `clrf 0x30`
 - **MOVWF f**
 - Move data from W register to register f
 - Example : `movwf 0x04`

Instruction Examples

- Byte oriented operations (contd.)
 - **MOVF *f*,*d***
 - Move contents of register *f* to register *W* (*d*=0) or itself (*d*=1)
 - Example : `movf 0x20,1`
 - **DECFSZ *f*,*d***
 - Decrement register *f*, place result depending on value of *d*
 - Skip the next instruction if result = zero
 - Example : `decfsz 0x20,1`
 - » instruction A
 - » instruction B
 - **DECf *f*,*d***
 - Decrement *f*, place result depending on value of *d*
 - Example : `decf 0x30,0`

Instruction Examples

- Bit oriented operations
 - BSF `f,b`
 - Bit `b` in register `f` is set to 1
 - Example : `bsf 0x03,5`
 - **Manipulate bits of STATUS and INTCON register**
 - **enable/disable interrupts, select register banks**
 - BTFSC `f,b`
 - Test bit `b` of register `f`, skip next instruction if bit is 0
 - Skip the next instruction if result = zero
 - Example :
`btfsc 0x03,2`
`instruction A`
`instruction B`

Instruction Examples

- Literal and control operations
 - **ADDLW k**
 - Add literal k to register W
 - Example : `addlw 0x05`
 - **MOVLW k**
 - Move literal k into register W
 - Example : `movlw 0x21`
 - **GOTO k**
 - Unconditional branch. Literal k is loaded into PC
 - Example : `GOTO THERE`
 - Use of labels is recommended

Assembler Directives

- Special instructions to assembler
- Important directives
 - **ORG k**
 - Place next instruction at location specified by k in program memory
 - Example :

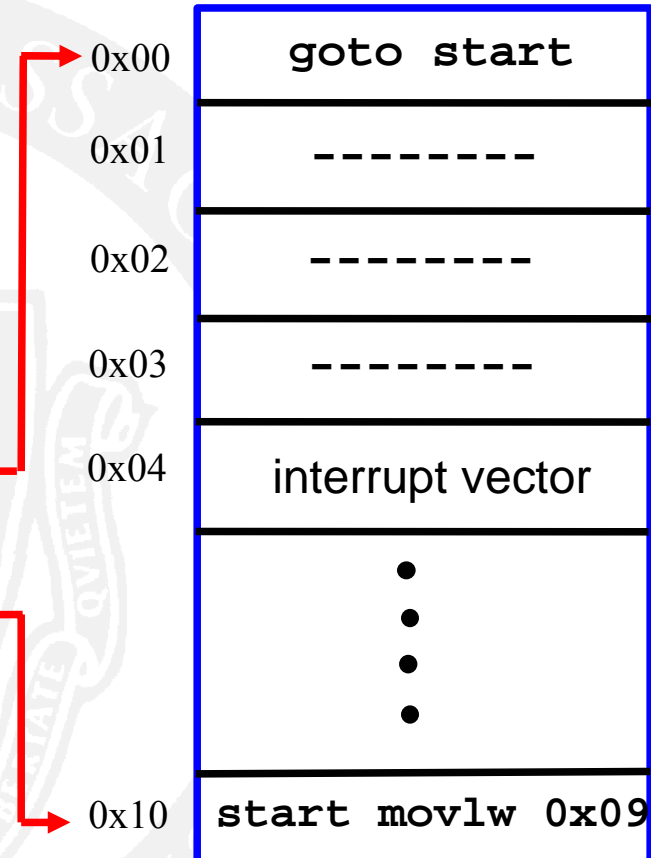
```
ORG 0x10
movlw 0x09
```
 - **constant EQU value**
 - Value is assigned to constant
 - Example : `COUNT EQU 0x20`
 - Useful for linking register addresses to variable names
 - **END**
 - Indicates end of assembly program

Reset Sequence

- Device reset causes PC to be reset to 0x00 (reset vector)
- Interrupt vector at 0x04
- All programs must start at 0x00
- Actual program starts after 0x04

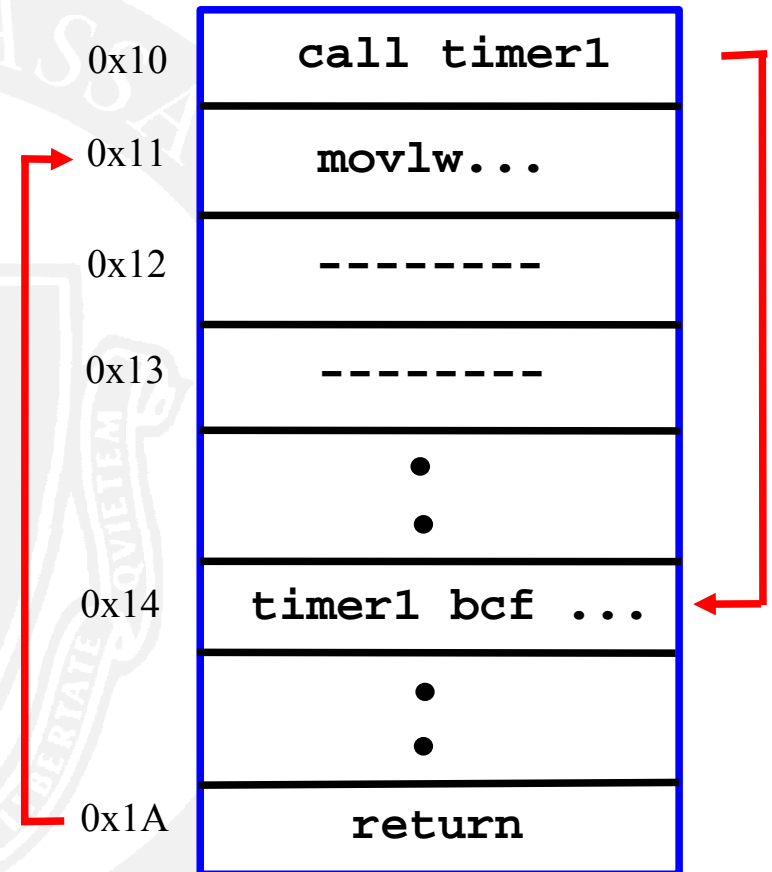
– Use ORG directive

```
org 0x00  
goto start  
org 0x10  
start movlw 0x09
```



Subroutines

- 0x11 pushed onto stack
- PC loaded with 0x14
- Subroutine executes till 0x1A
- 0x11 popped off stack and stored in PC
- Upto 8 levels possible
 - What does this mean ?
- Stack wraps around



Interrupts

- Many sources of interrupts
- INTCON register
 - Bit 7 (GIE) enable/disable interrupts
 - GIE cleared when interrupt occurs
 - GIE set when “retfie” is executed
- Location 0x04 contains interrupt vector
 - Interrupt Service Routine (ISR) at 0x04
 - Return PC value saved onto stack
 - ISR must store/restore values of other registers (STATUS,W)
 - ISR must check type of interrupt

Interrupt Service Routine

```
ISR1  movwf  TEMP_W  
      swapf STATUS,W  
      movwf STATUS_TEMP
```

store values of
W,STATUS

```
;   
; EXECUTE ISR CODE HERE  
;
```

```
      swapf STATUS_TEMP,W  
      movwf STATUS  
      swapf W_TEMP,W  
      retfie
```

restore values of
W,STATUS

return from ISR,
enable all interrupts

0x00

goto start

0x01

0x02

0x03

0x04

call ISR1

•
•
•
•

0x10

start movlw 0x09

Indirect Addressing

- Data memory address is not fixed
- Special register (FSR - 0x04) used as pointer to memory location
- Opcode performed on INDF register (0x00)
- Useful for manipulating data tables in memory
- Example: clear a block of memory from 0x20 to 0x2F

```
movlw 0x20      |
movwf FSR      | → initialize the FSR register
next clrf INDF  | → clear location pointed to by FSR using
                | INDF
incf FSR,1     |
btfs FSR,4     | → increment FSR, check if done
goto next
```

Common Code Sequences

- if-then-else condition checking

```
        btfsc STATUS,Z
        goto Zset
Zclear  bsf ....          → if (z==0)
        ; instructions to execute if Z=0
        goto Zdone
Zset
        ; instructions to execute if Z=1
Zdone  movlw....        ; Carry on with program
        end
```

- Use
 - btfsc,btfss to test with bits
 - decfsz,incfsz to test with bytes

A Simple Example

```
count equ 0x20      ; Equate register 0x20 to count
org 0x00            ; Initialize reset vector
goto start         ;
org 0x10            ; Actual program starts here
start movlw 0x09    ; Move constant to W
movwf count        ; Move W to count (0x20)
loop  decfsz count,1 ; Decrement count, skip if zero
      goto loop     ;
      movlw 0xFF    ; If count=0, move 0xFF to W
      movwf count   ; Move 0xFF to count
end
```

Assembly Program Template

```
count equ 0x30
```

Assign symbolic names to registers

```
org 0x00  
goto start  
org 0x04  
call IS_ROUTINE  
org 0x10
```

Initialize reset and interrupt vectors

```
; PROGRAM BODY
```

Main program body

```
IS_ROUTINE  
; ISR BODY  
retfie  
end
```

Interrupt Service Routine body

Design Tips

- Use variable equates (equ) to assign registers symbolic names
- Comment your code
- Use MP-SIM to debug your code before you program device
- MPLAB-IDE
 - “RAM” - look at contents of register file
 - “ROM” - look at contents of program memory
 - “SFR” - look at contents of special function registers

Summary

- PIC 16F877
 - architecture
 - instruction set
 - addressing modes
 - special registers STATUS,FSR,INDF,INTCON
- Power on reset
- Subroutines, Interrupts, ISRs
- Use MPLAB-IDE to debug your work