

UMASS  
AMHERST

# SDP 18: EfficienSeat

6 March 2018  
Comprehensive Design Review

**Team 26**

**Advised by Professor Tilman Wolf**

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Dennis Donoghue, Aarsh Jain

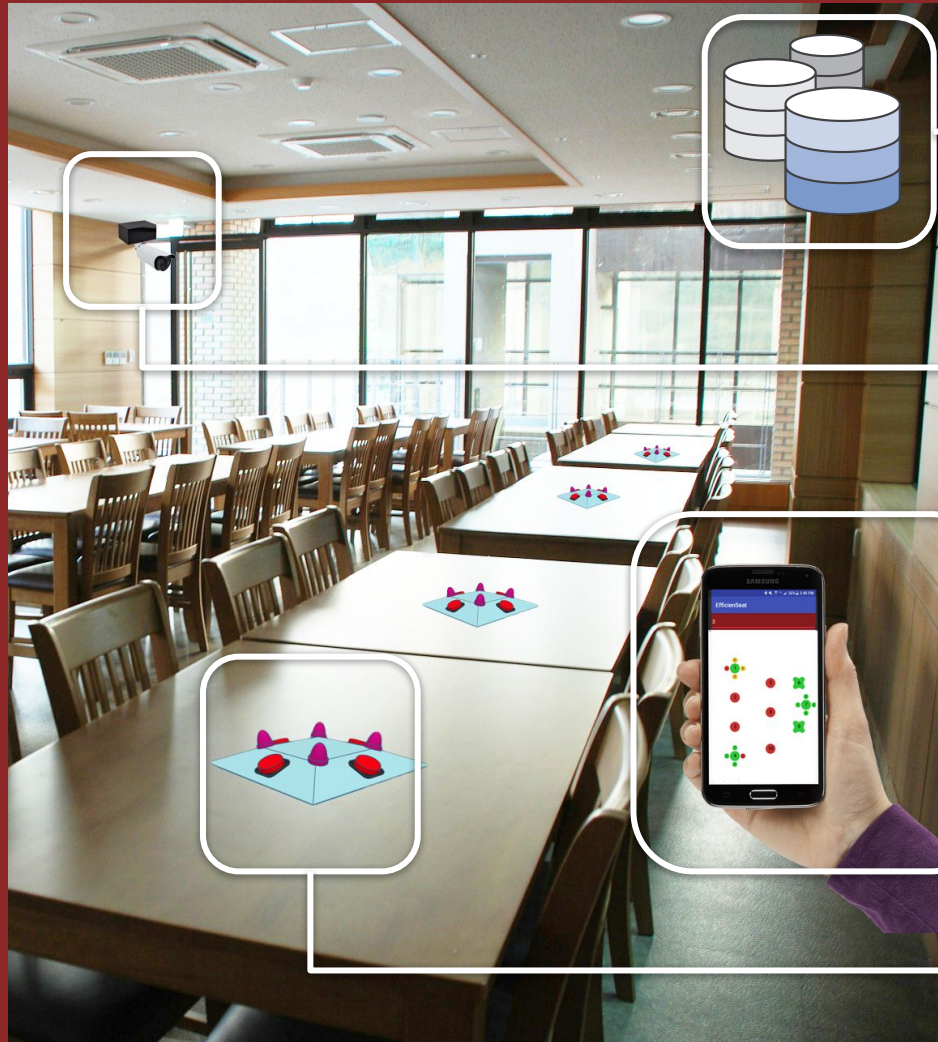


# Problem Statement

- Dining halls suffer due to seating inefficiencies
- A useful solution is convenient and saves time
  - Patrons need improved seat identification methods
  - Dining halls need an easily implementable and maintainable system



# Our Vision for a New System



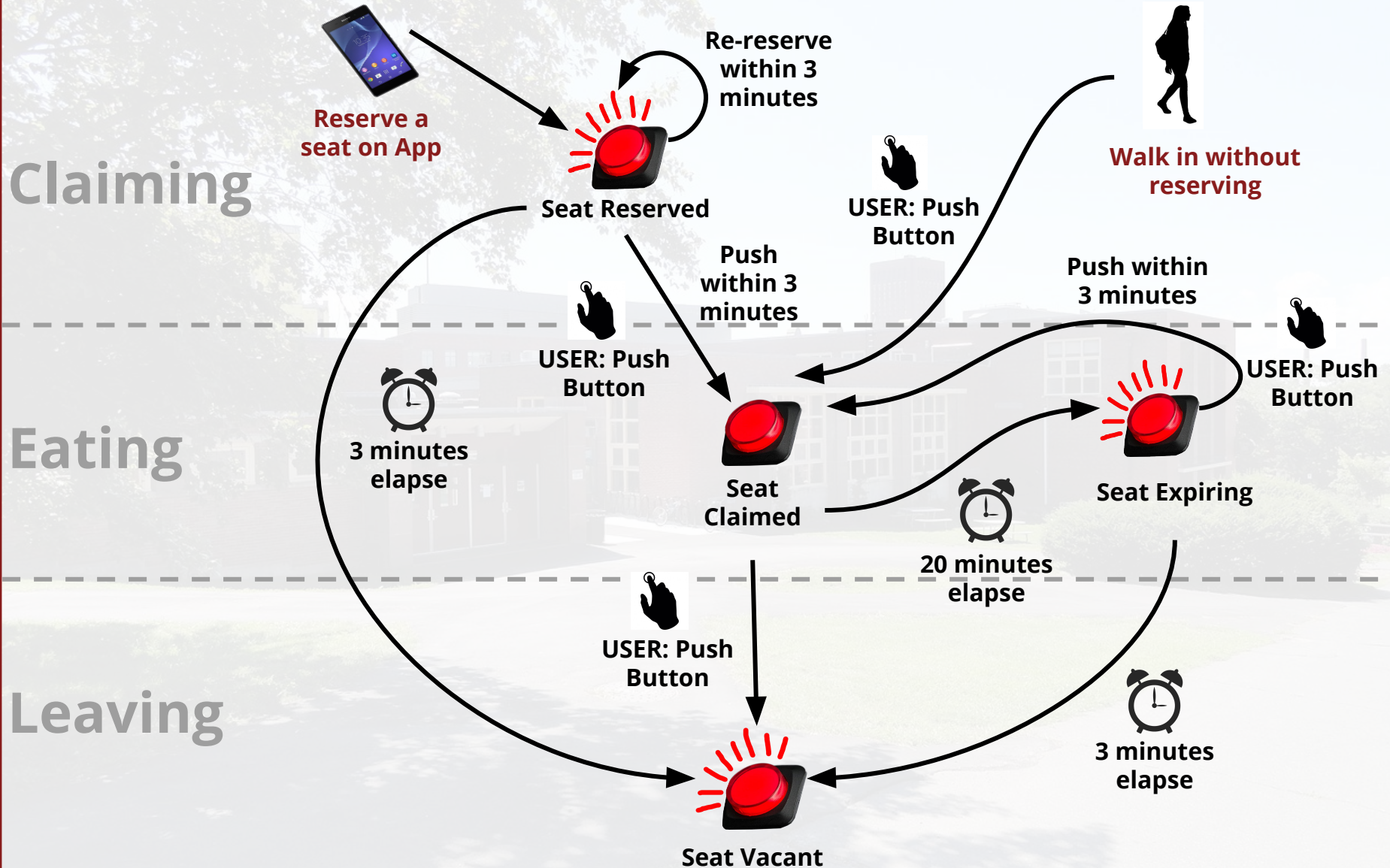
Database to act as hub for table seat data

Sky Unit for data relay and table positioning

App for mobile interaction with dining hall

Table Units with pushbuttons with four seats per table

# User Interaction State Diagram



# System Requirements

- Patrons should be able to:
  - Use an app to interact with dining hall
    - View a map of the dining hall
    - Make timed seat reservations
    - Search for seats by party size
  - Have choice of not using app
    - Table Units have physical user interface
- System implementation should be:
  - Easy to maintain
  - Safe around food

# System Specifications

- Allows app users to search for available seats by party size through app
- Users will receive response from the app within 2 seconds
- **The app will generate a depiction of table locations accurate to ½ a table length**
- **Orientation of Table Unit detected within 90 degrees**
- Can function in a dining hall of several hundred seats
- **Table Unit is compliant with IPX4 (Splashproof)**
- Table Units should have a push button interface
- **Battery life of Table Unit should last a month**

# Challenges

## 1. System Communication

→ Interfacing between four mediums

## 2. Data Synchronization

→ Table data agreement across system

## 3. Table Localization

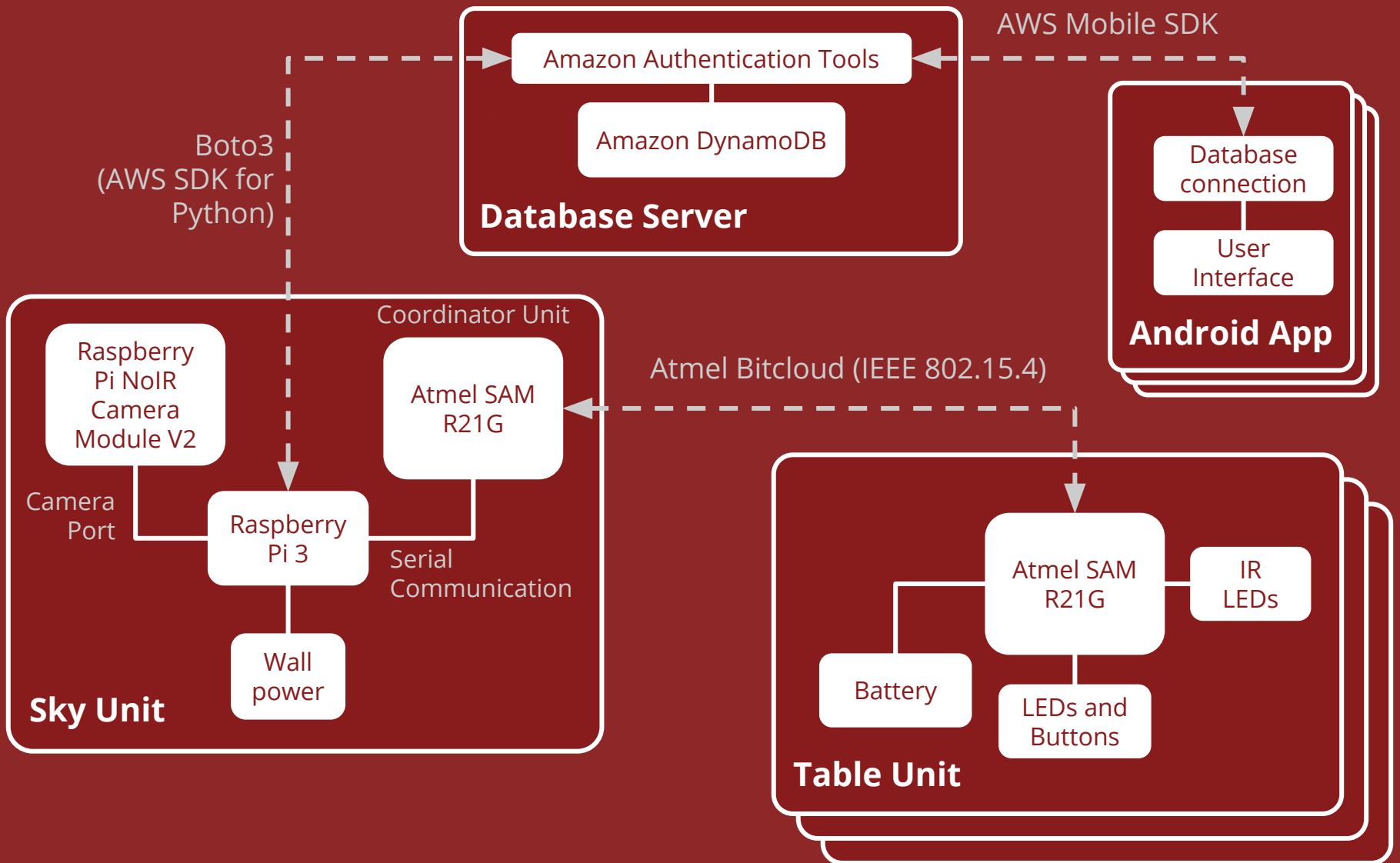
→ Indoor positioning problem to find tables

## 4. Low power, Unobtrusive Nodal Units

→ High-functioning with low power costs



# Block Diagram





# CDR Deliverables

- Demonstrate full system communication
  - Hitting button on the Table Unit is reflected on the app
  - Reserving tables from app is reflected on the Table Unit
  - Conscientious data writing from both Sky Unit and App
- Prototype of table unit
  - Actual hardware for buttons and LEDs, battery
  - Case prototype design for Table Unit
- Demonstrate table localization ability
  - Configure a grid for a rectangular area
  - Determine position of a table unit

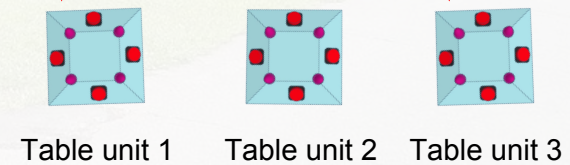
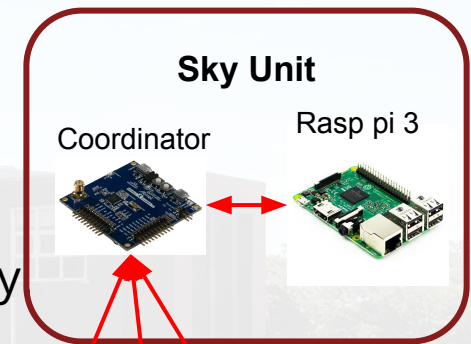
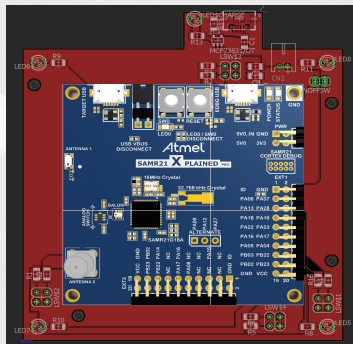
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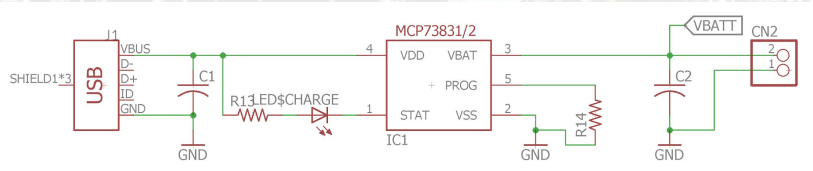
# Low Power, Unobtrusive Modular Units

Table unit features:

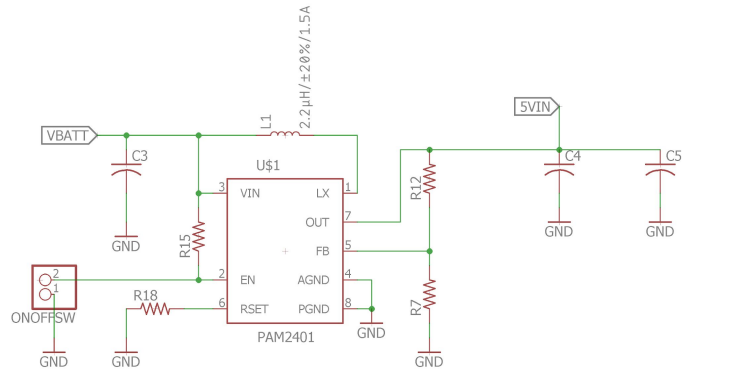
- Low powered chip with SoC for communication.
- Communication over IEEE 802.15.4 built on LwMesh.
- Powered using three 3400mAh batteries.
- Battery lasts up to 25 days with 14 hrs working each day
- Compact and modular design.



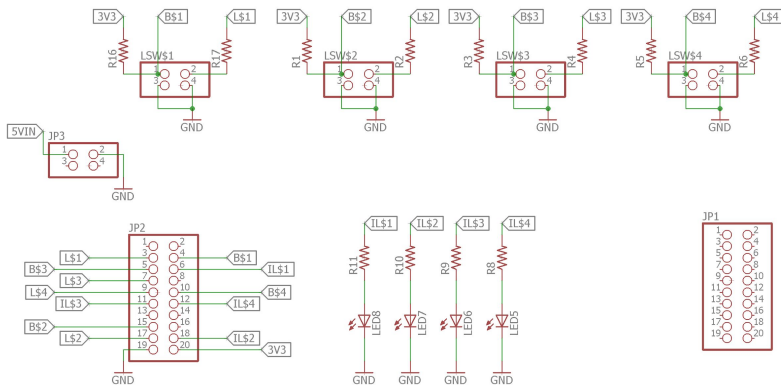
# PCB Design



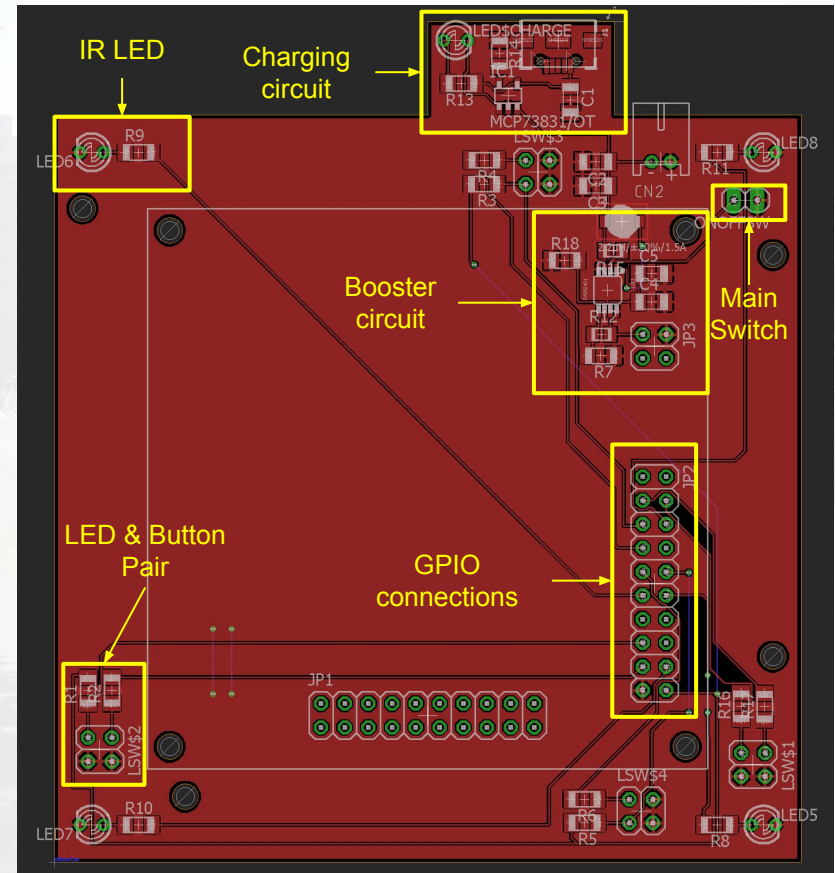
**Charging Circuit**



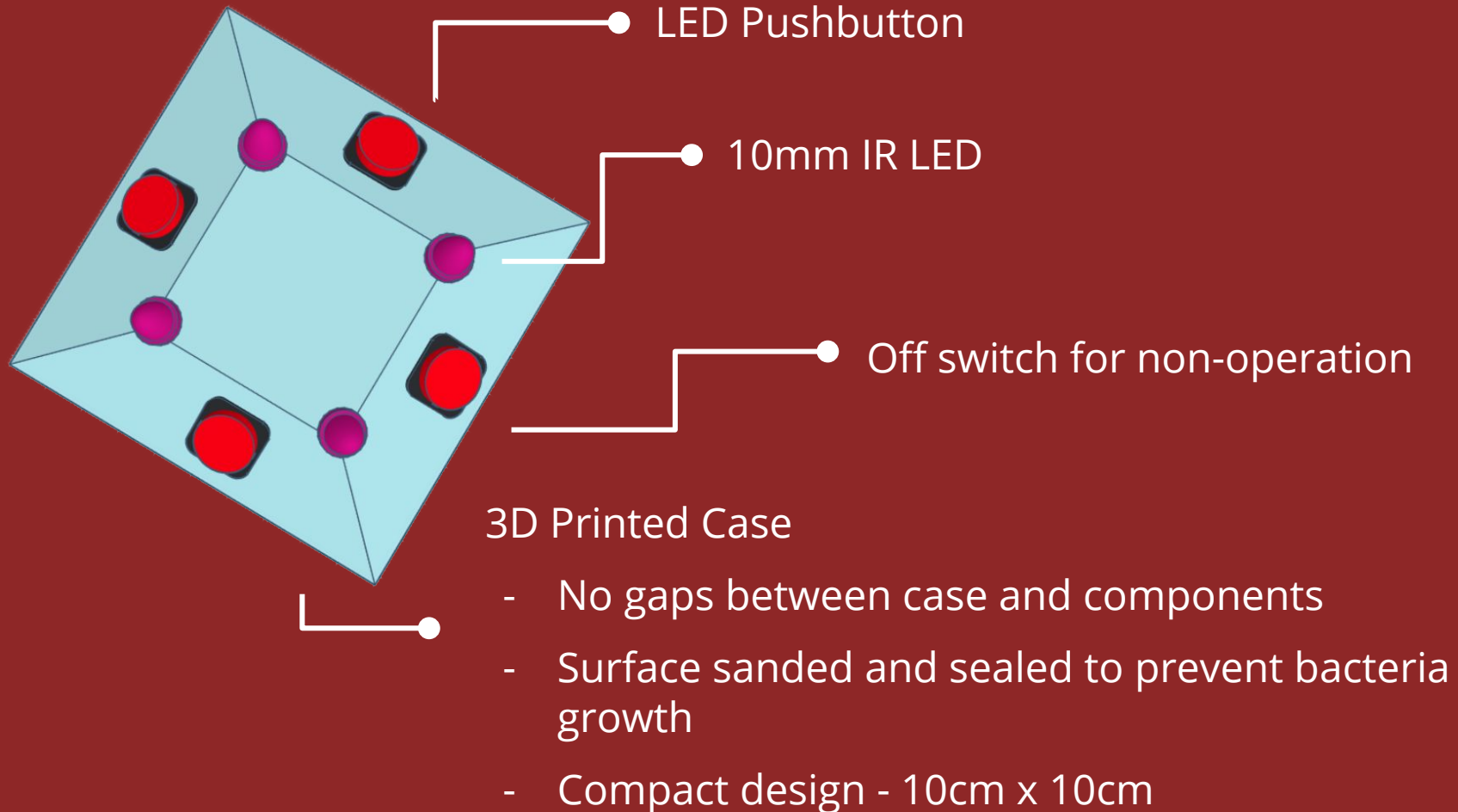
**Booster Circuit**



**GPIO, Power and LED connections**



# Prototype of Case Design



# CDR Deliverables

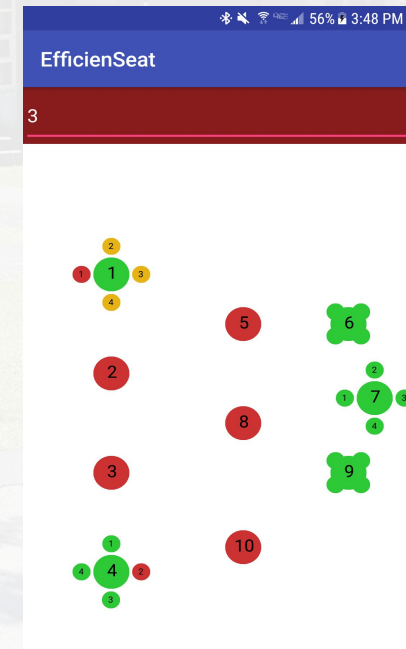
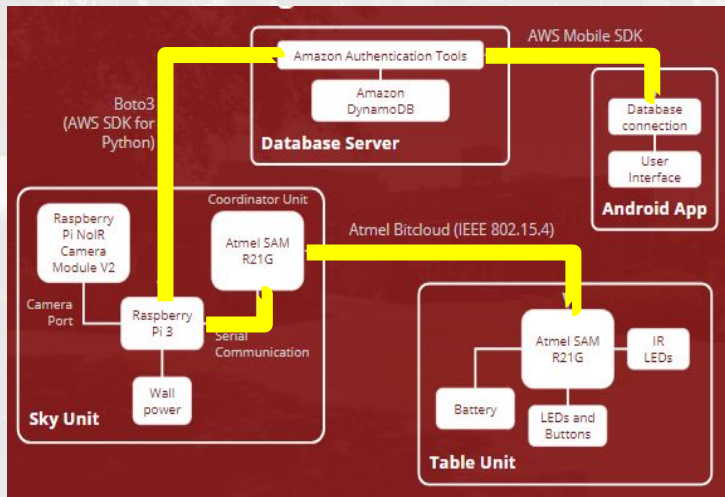
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# System Communication and Data Agreement

**Challenge:** Smooth system integration and state preservation

- Seat states must be reliably communicated throughout system
- States must be safely modified from two different systems (App, Table Unit)

**Solution:** Consistent conditional writing and efficient protocol



# Locating Tables in the Room

**Challenge:** Simple way to find table locations

- Accuracy: up to half a table length
- Speed: update every hour

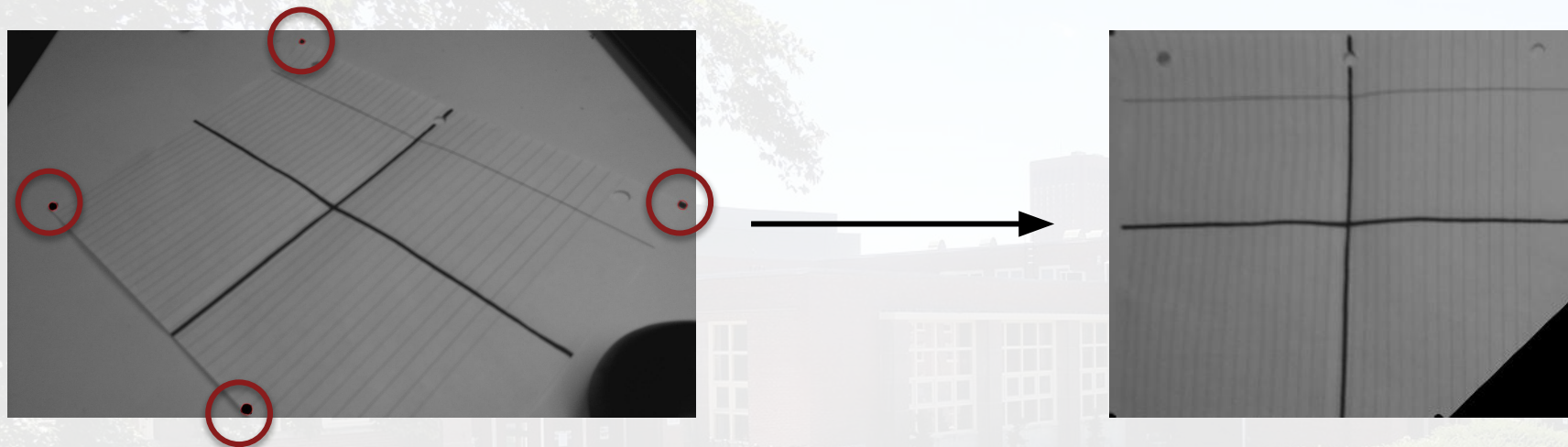
**Solution:** Use IR LEDs and camera to find the positions



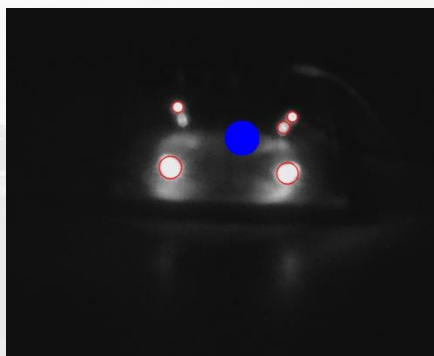


# The Process for Finding Tables

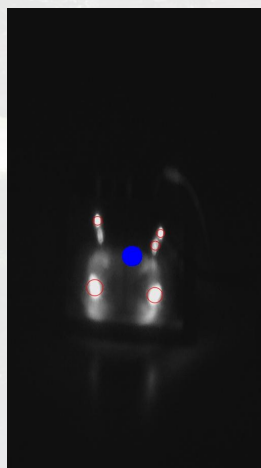
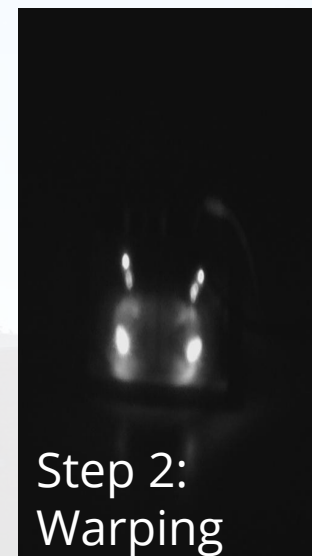
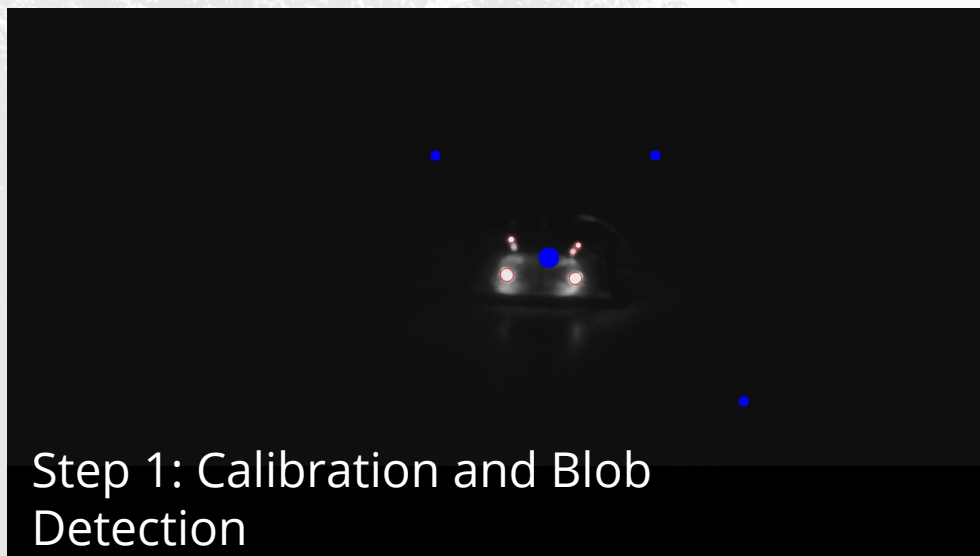
**Step 1:** Calibration - getting a “top down” view of room



**Step 2:** Blob detection - find Table Units by IR LEDs one at a time



# The Process for Finding Tables



Final Step: Blob Detection

## Results of Test

Actual Position	Calculated Position
(20cm, 45.5cm)	(22cm, 48cm)

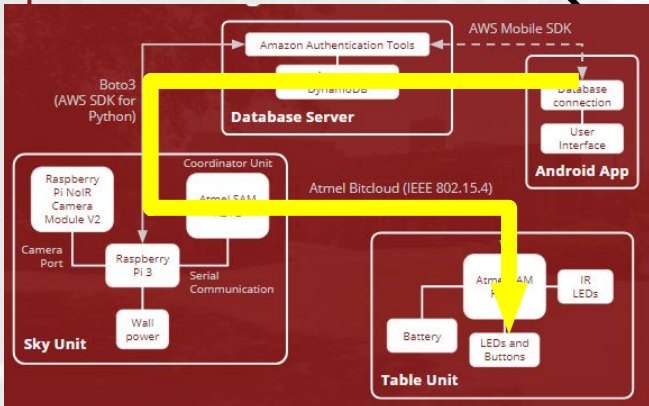
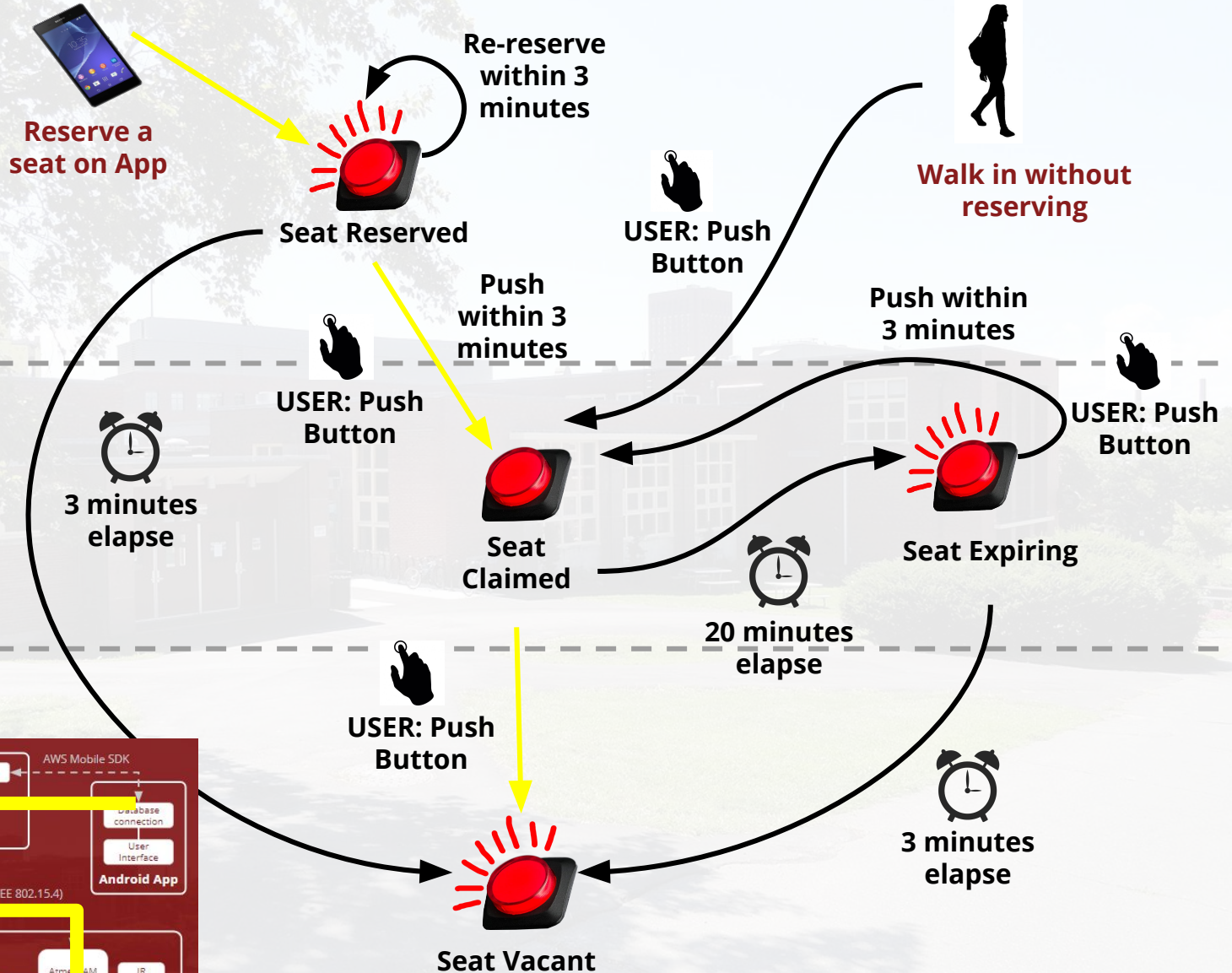
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# App reflected on Table Unit

Claiming

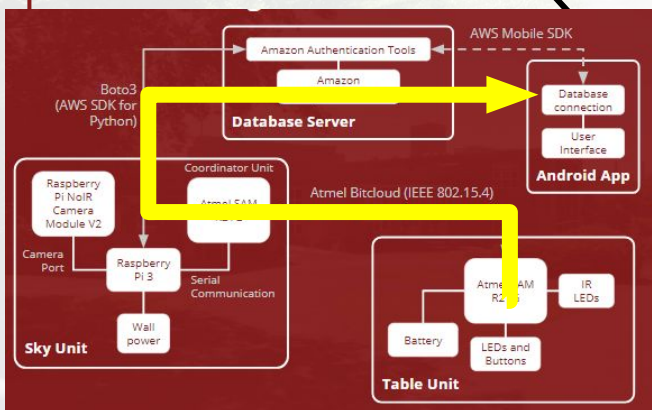
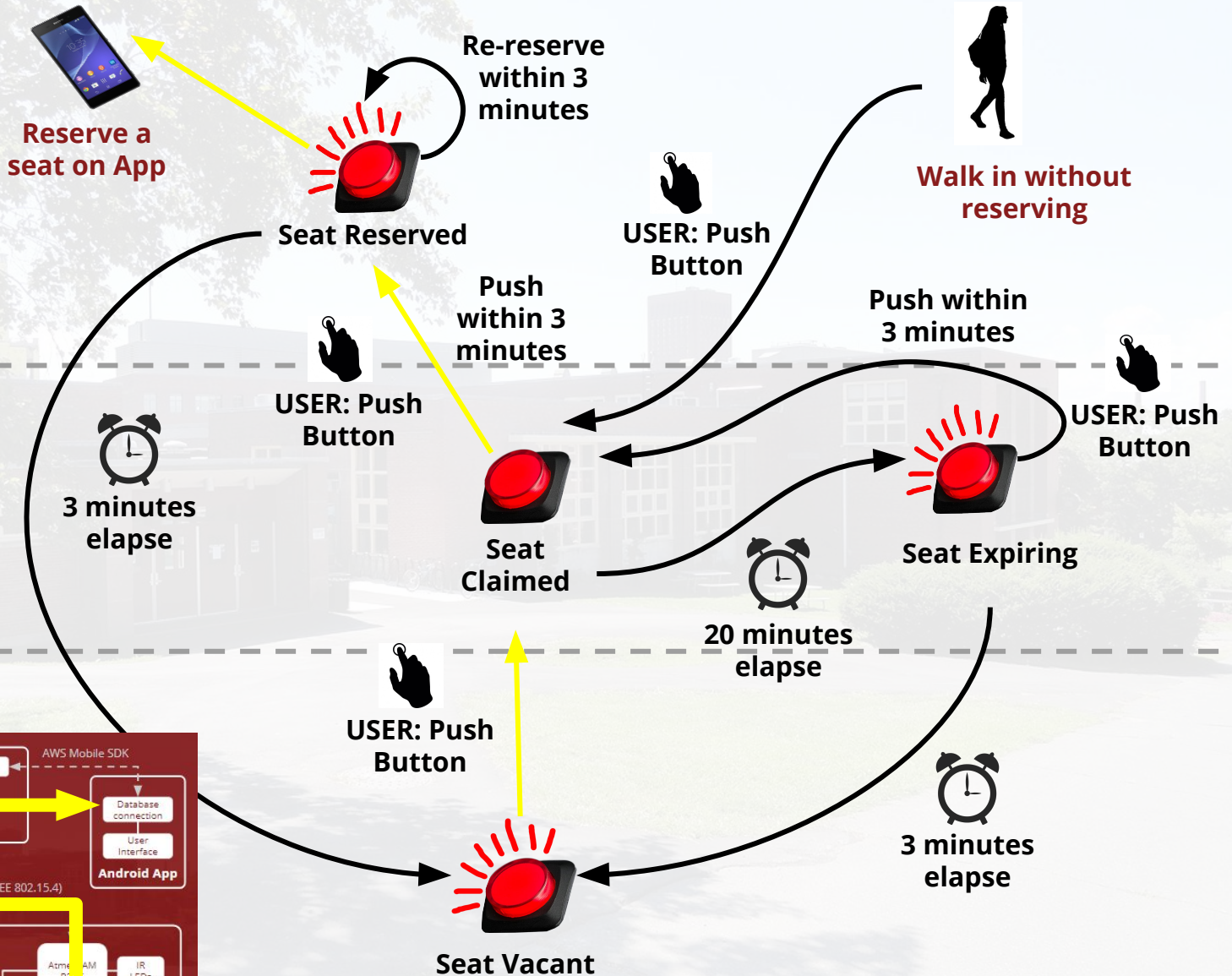
Eating



# Table Unit reflected on App

Claiming

Eating

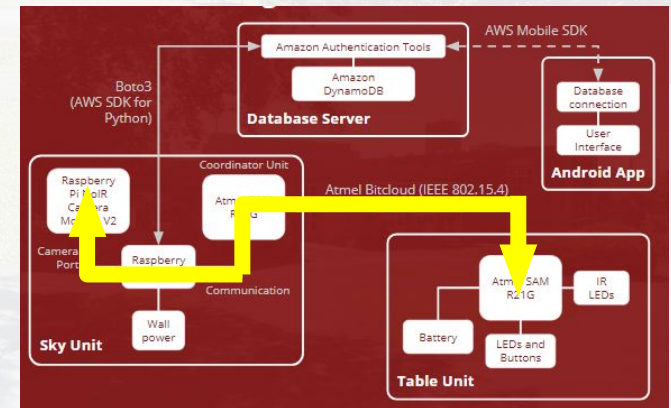


# Table Localization Demonstration

**Purpose:** Find position of table given the length and width of a room

## Demonstration Steps:

- Calibrated for marked area before presentation
- Run script to find coordinates of Point A
  - Display final result and coordinates
- Move IR LEDs to Point B and run script again



# CDR Deliverables



Demonstrate full system communication

- Hitting button on the Table Unit is reflected on the app
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- Conscientious data writing from Sky Unit and App



Prototype of table unit

- Actual hardware for buttons and LEDs, battery
- Case prototype design for Table Unit



Demonstrate table localization ability

- Configure a grid for a rectangular area
- Determine position of a table unit

# FPR Deliverables

- Deployable Table Unit
  - Case, PCB built and fully integrated
  - Case protects Table Unit from food/spills
- Demonstrate complete Table Localization ability
  - Improve algorithm for large scale implementation
- Complete and robust system operation
  - All parts fully integrated and working as one
  - Complete user App experience
  - Reservation and claim timers implemented



**Questions?**

# Questions to Consider I

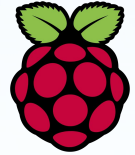
- Power concerns - current power consumption
  - What we're going to do to reduce it
  - Quick analysis? Take power reading and calculate
- Timing coordination
  - Where will the timing take place?
- Session IDs
- Authentication and Confidentiality
- LED ON/OFF situation
  - The workers will shut system down after operation hours
  - 9-3, 6-10 7-12 it's busy 60% of the time OFF is taken final answer - it's an aesthetic choice, easier to see a lit up LED
  - Take google plot for evidence

# Questions to Consider II

- Orientation of table unit
  - Know which LED is on
- Low battery indication, error
- Single reserve tables vs multi reserved tables?
  - If yes, how are we handling it?



Amazon DynamoDB

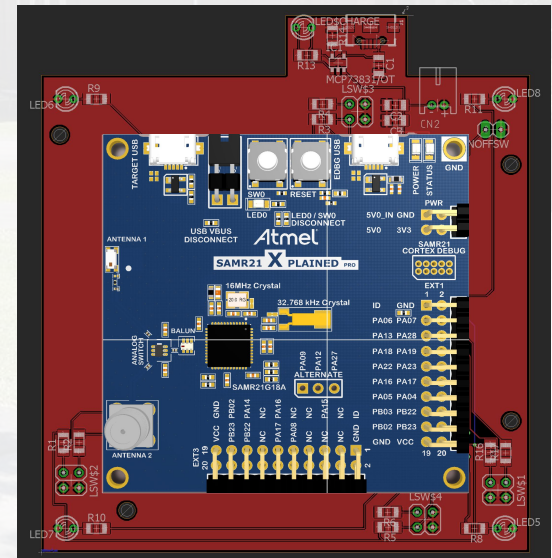


Raspberry Pi on  
Sky Unit

# PCB Design

The following features are included in the PCB:

- Li-ion/Li-po charging circuit through micro USB.
- Booster circuit to provide board with 5V.
- LED and Button pair on each corner for buttons and status LEDs.
- IR LEDs on diagonal corners for table localization.
- Easy to mount under SAM R21.
- Charging status LED.
- ON/OFF slider switch.

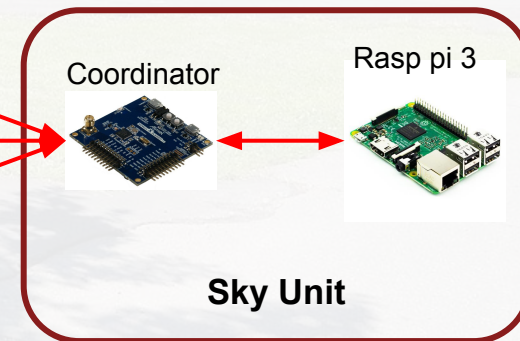


# Table Unit



Table unit features:

- Low powered chip with SoC for communication.
- Communication over IEEE 802.15.4 built on LwMesh.
- System powered through three 3400mAh batteries.
- Battery capacity upto 25 days with 14 hrs working.
- Charging and boosting features included.
- Compact and modular design.
- Robust network handling hundreds of nodes.



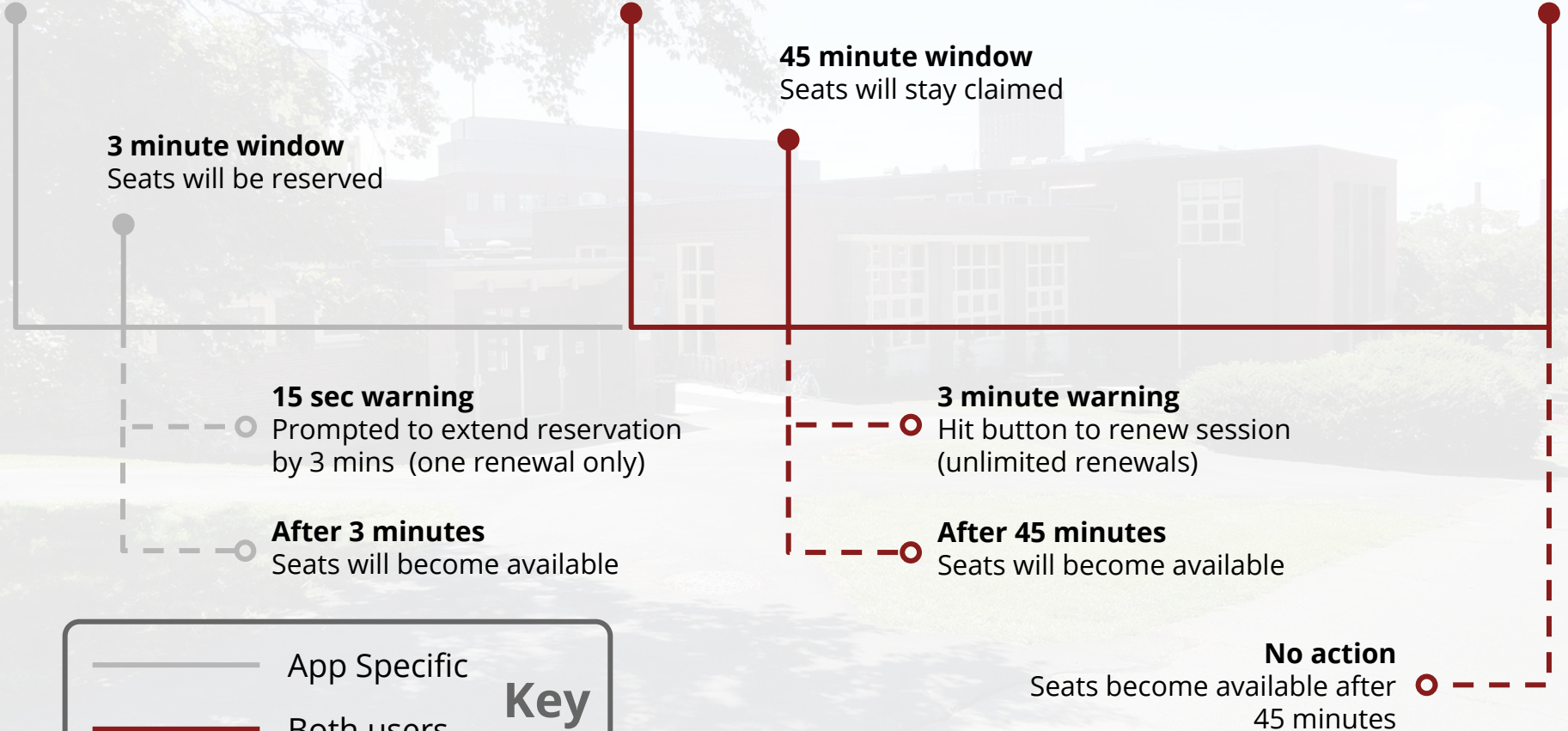
# Timeline for User Interaction MOVE

## App-Users

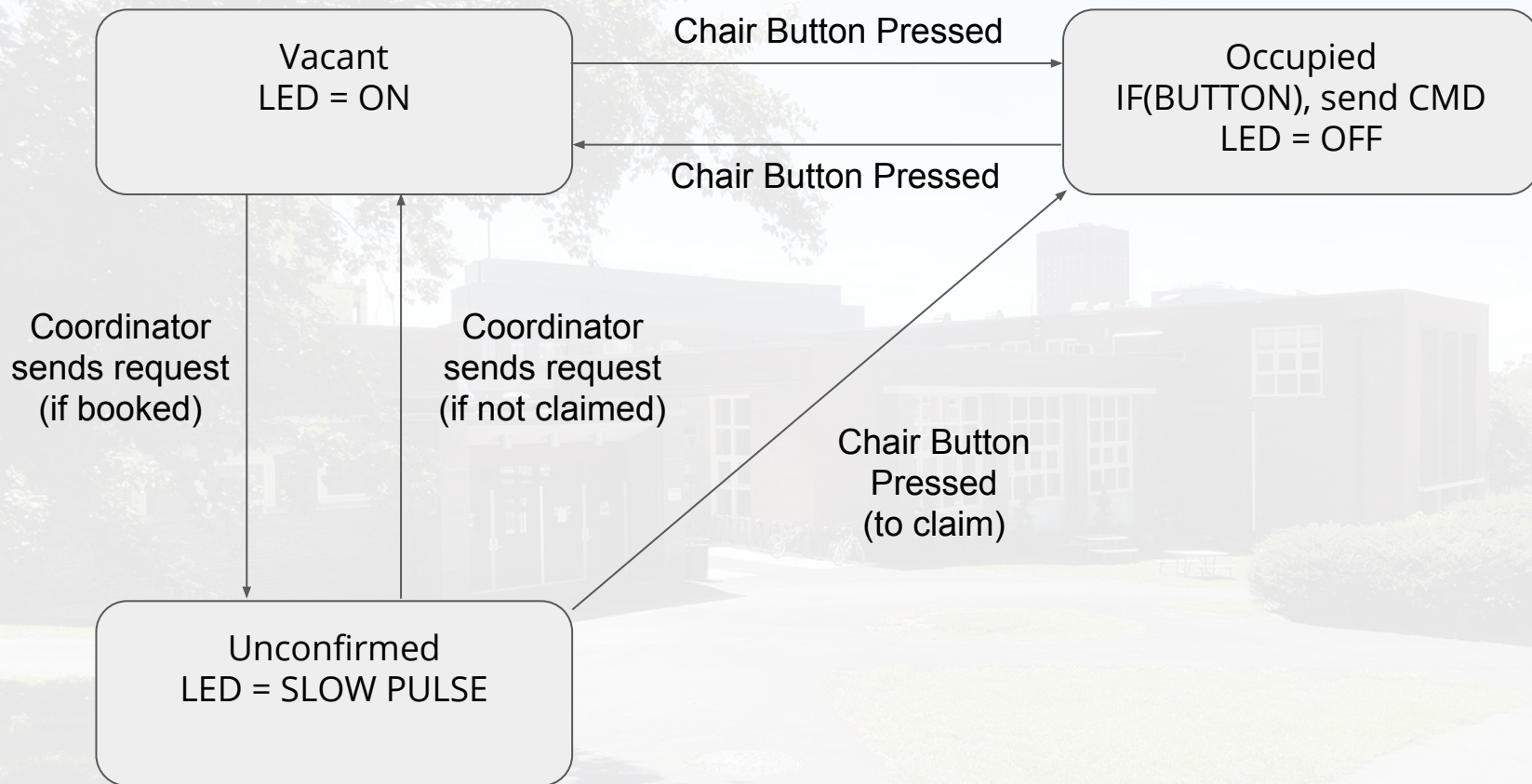
At or approaching the dining hall, find seats and reserve.

## Leaving

Patron will hit button to leave, seat will become available



# Table Unit: State Diagram



# Table/Sky Unit Communication Protocol

## Payload

2 bytes	1 byte	4 byte
<b>addr</b>	<b>cmd</b>	<b>light state</b>

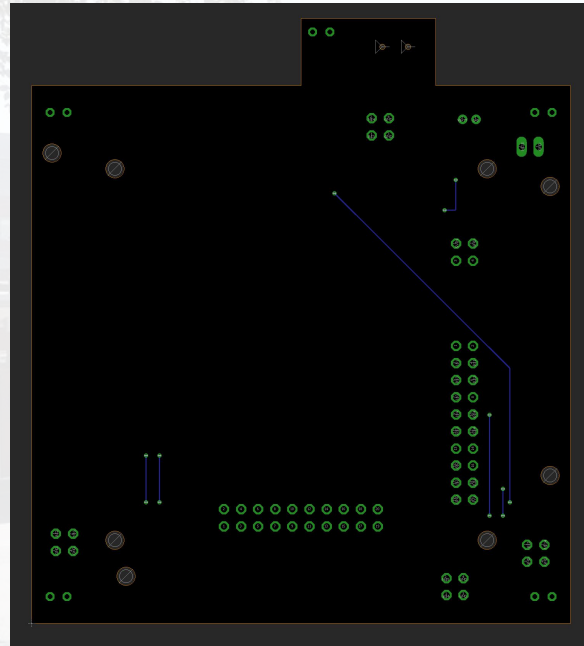
## Definitions

ID	Command
0	Invalid
1	Change seat state
2	Change IR LED state
3	Wake up

ID	Seat/IR State
0	Vacant/on
1	Occupied/off
2	Reserved



# Bottom Layer



# Nominal User Interaction

