FPR Presentation SmartWheel

Bingjun Wang Yaroslav Burdin Bingze Li Jack Tam

Department of Electrical and Computer Engineering April 21, 2017

Team Members



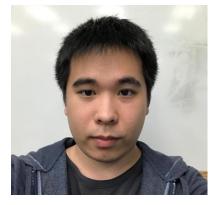
Advisor Lixin Gao



Bingze Li EE



Bingjun Wang EE

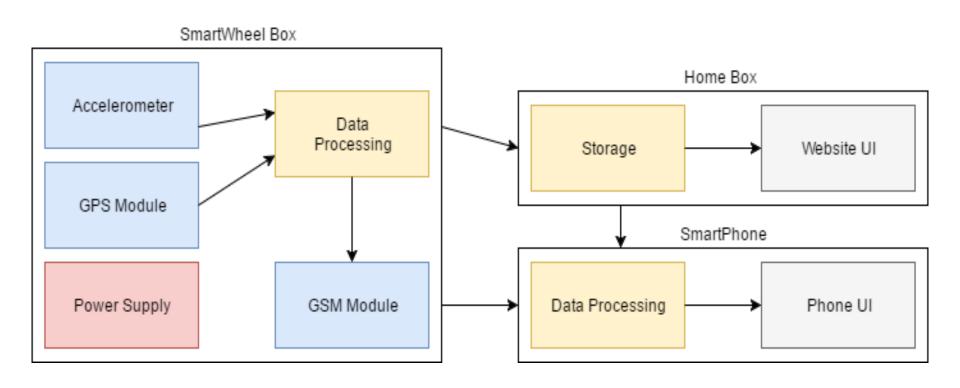


Jack Tam CSE



Yaroslav Burdin CSE

Overview\ Block Diagram



FPR Deliverables

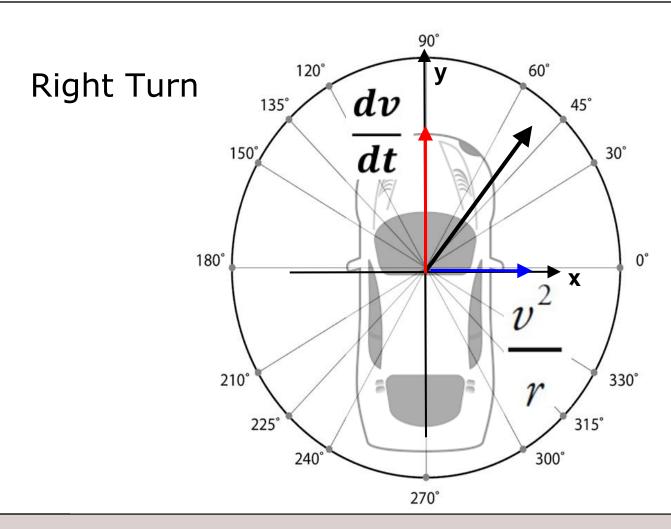
Proposed Deliverables

Fully integrated system

Added Deliverables After Feedback

- Phone Application Addresses
- Various Text Message Alerts
- SmartWheel Misposition Detection
- 3D Printed Case
- Web User Interface

Accelerometer



Smartphone Application

Improvements

- Added more options for acceleration
- Added addresses
- Changed map to satellite view

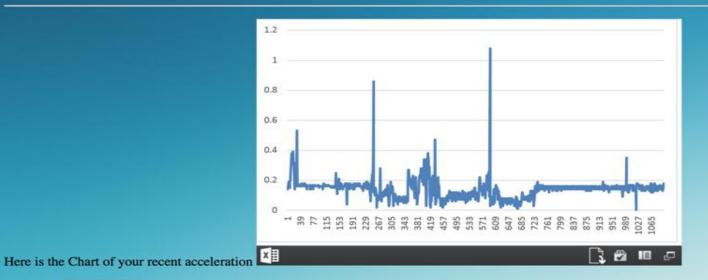




Website User Interface

SmartWheel

We watch behind your wheels



you have times dangerous driving

Remind User by Email: click Here

Take a look at the data history click Here

Bookmark This Page

OneDirve



- Similar to google Drive.
- Gives the embed code for website programming.

3D Printed Case (TinkerCad)





- Free to Use
- Saving .STL Files
 Online
- Easy for Beginners

Indicator and Reset Button

Indicator:

Blink: connect to serve

On: working

Off: stop working

Reset Button:

Reset Python code



Specifications

Electrical and Computer Engineering 2017

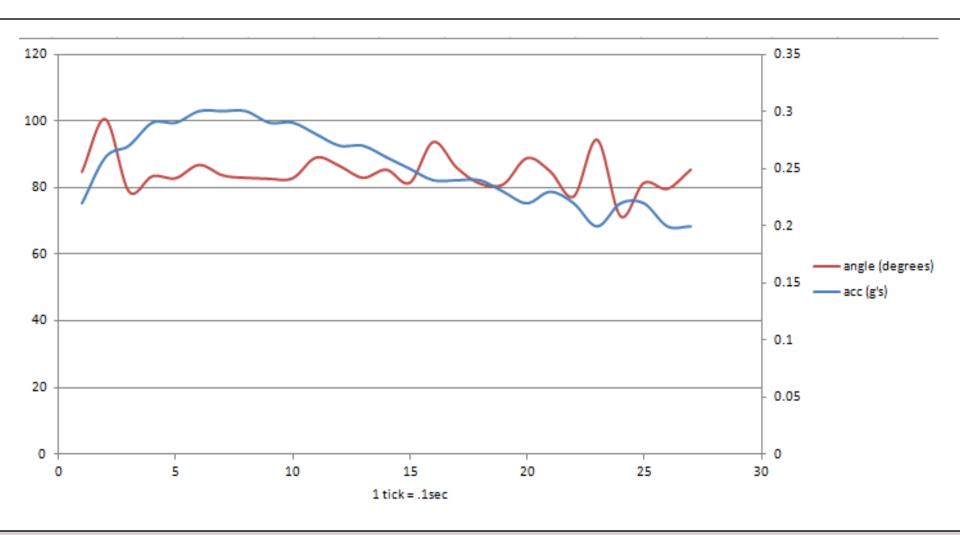
Specification	Proposed	Actual
Dimensions	11x8x5 cm^3	11.5x8.5x4.5 cm^3
Weight	250 grams	340 grams
Battery Life	12 hours	16 hours
Unit Price	<\$150	<\$120
Text Message Alert Delay	<15 seconds	< 10 seconds
Storage Capacity	72 hours of driving	14 days of driving
Server Connection Radius	>15 meters with a wall between	>70 meters in open area; > 32.5 meters with a wall in between.

UMassAmherst DEMO

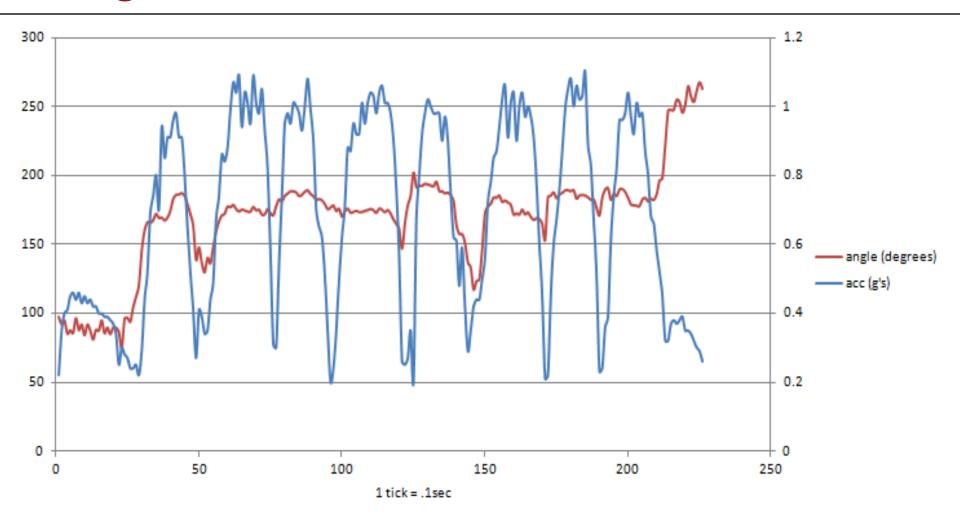




Safe Acceleration



Dangerous 8 Left Turns



Wiggling, Dangerous Acceleration/Deceleration

