

# Project Sauron

## Midyear Design Review

Senior Design Project

Fall 2015



# The Team



Advisor:  
Tilman Wolf



Zach Goodman  
EE



Walter Brown  
CSE & CS



Omid Meh  
CSE & EE



Jose LaSalle  
EE

# MDR Deliverables

- Demonstrate voice isolation between two individuals speaking simultaneously.
  - Components needed:
    - Microphone Array (SDP14 Array, Wolf Array)
    - Calibration System to identify time shifts needed to isolate a particular location ("delay learner" in PDR)
    - Beam-forming via time shifting
    - Additional filters to clean up final signals

# Demos

- Acoustic Beamformer Array (from SDP14)
  - Calibration
  - Real Time Recording
- Wolf Array
  - Script Recording
  - Outdoor Test Results
  - Demo Beamforming on Script Recording

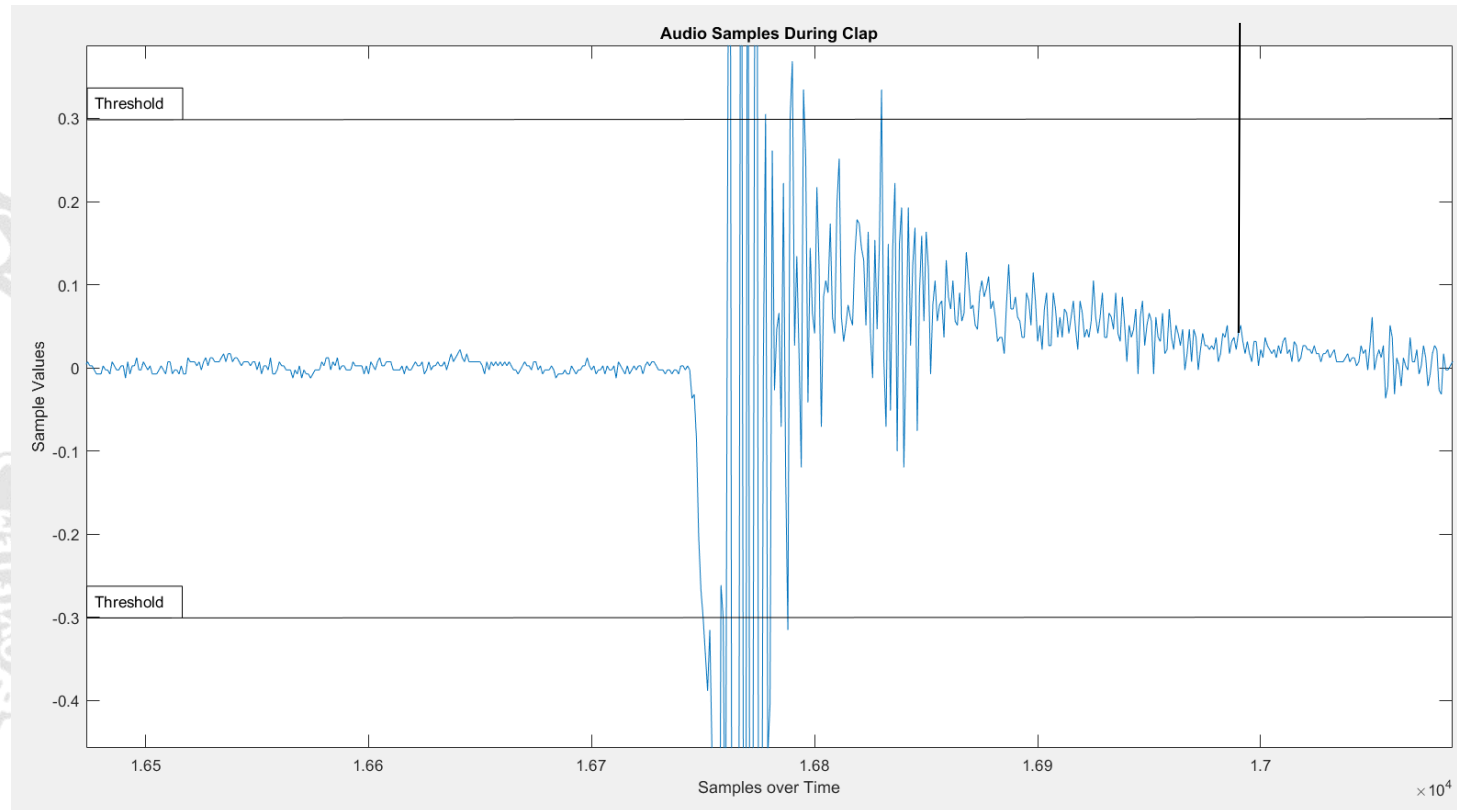
# Beamformer Array Interface

## Specifications

- Can import audio to Matlab
- Can operate continuously in real time
- Audio isn't skipped
- Can report delays of an impulse
- Allow relative ease in swapping arrays

# Beamformer Array Interface

## Detect Calibration Claps



# Beamformer Array Interface

Real Time Recording

- Can import to Matlab

No Skips

- Current demo

Can read into

# Wolf Array – Script Recording

## Script 1 (Hollot)

“Inaccuracies between a physical system and its mathematical model are often accounted for via the introduction of uncertain parameters.”

## Script 2 (Moritz)

“We hope to provide insights in how performance is affected by the interaction of architectural aspects, various programming models and communication styles, and resource managing schemes.”



# Wolf Array – Outdoor Test

Setup:

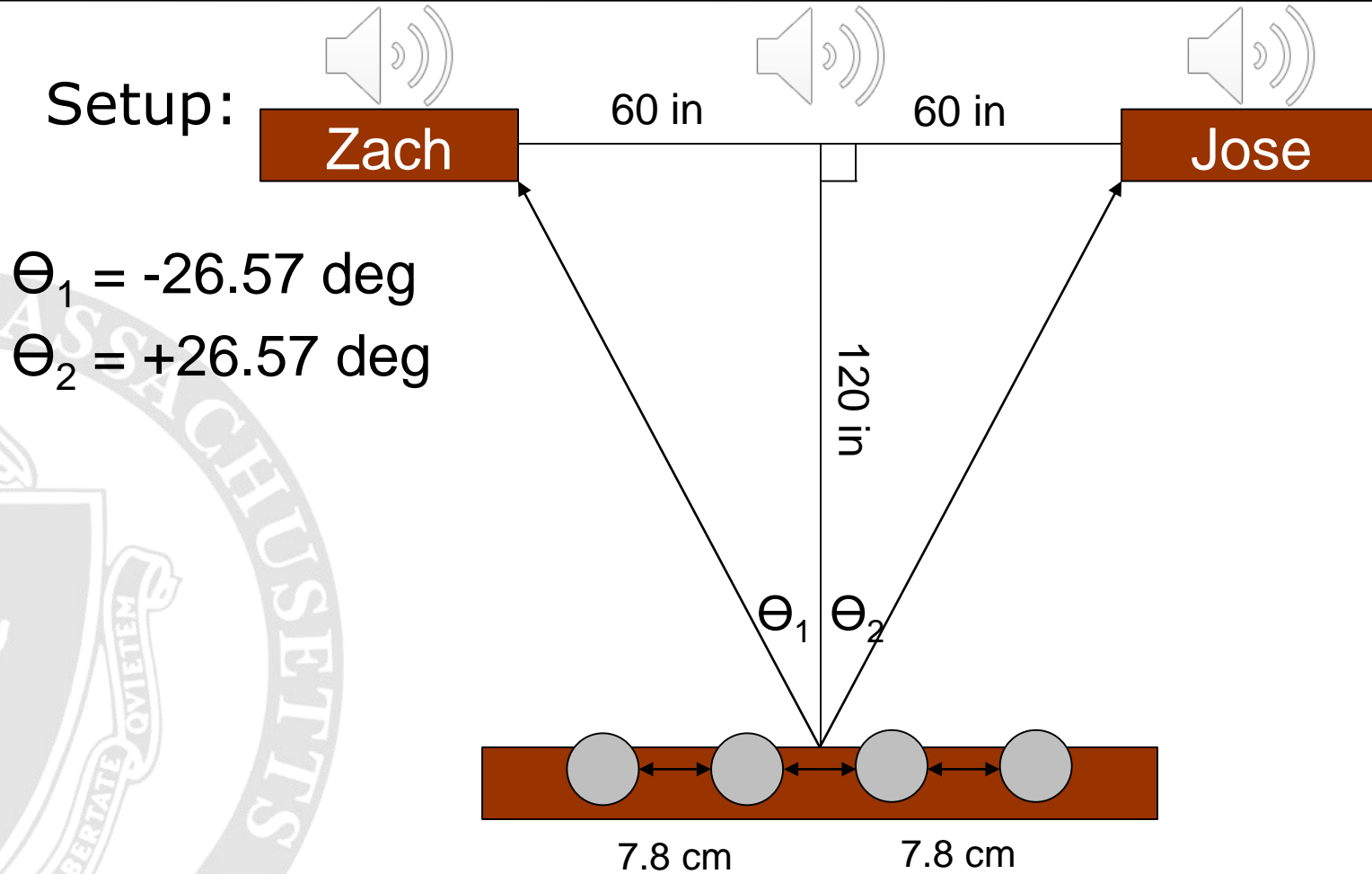
Mics: 4 cardioid linear array, 7.8cm Spacing

Zach @  $-26.57^\circ$ , 3.4m from array

Jose @  $+26.57^\circ$ , 3.4m from array



# Wolf Array – Outdoor Test



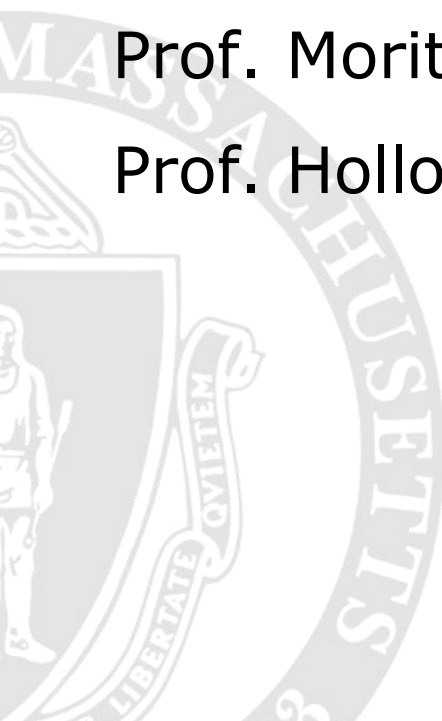
# Wolf Array – MDR Demo

Setup:

Mics: 4 cardioid linear array, 7cm Spacing

Prof. Moritz @  $-30^\circ$ ,  $\sim 2\text{m}$  from array

Prof. Hollot @  $+30^\circ$ ,  $\sim 2\text{m}$  from array

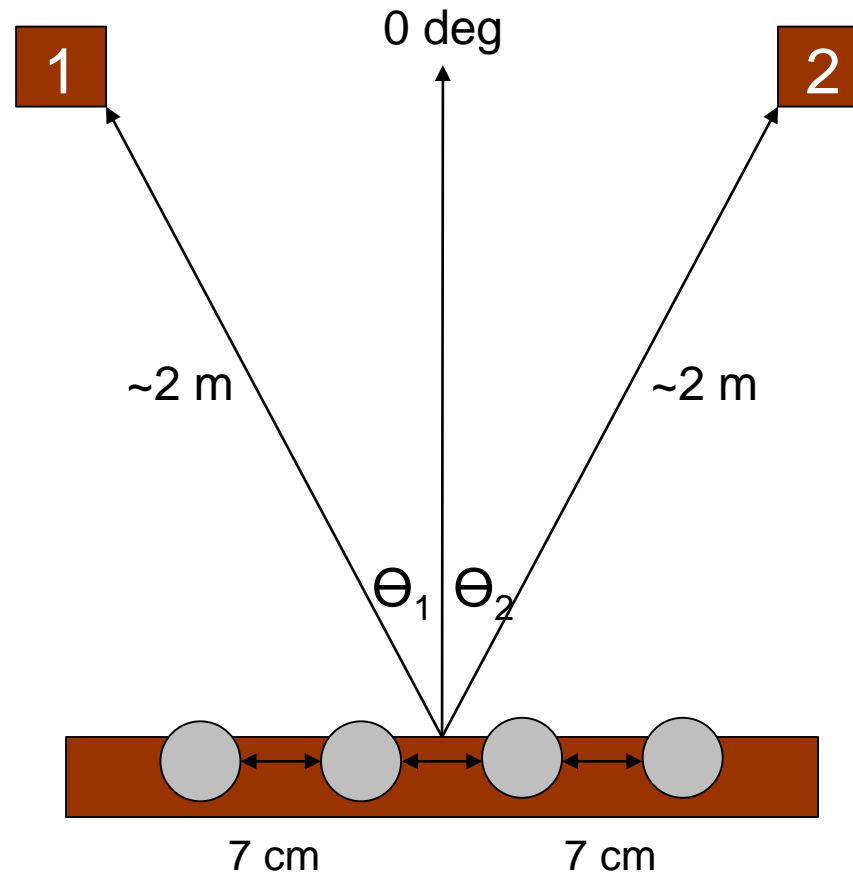


# Wolf Array – MDR Demo

Setup:

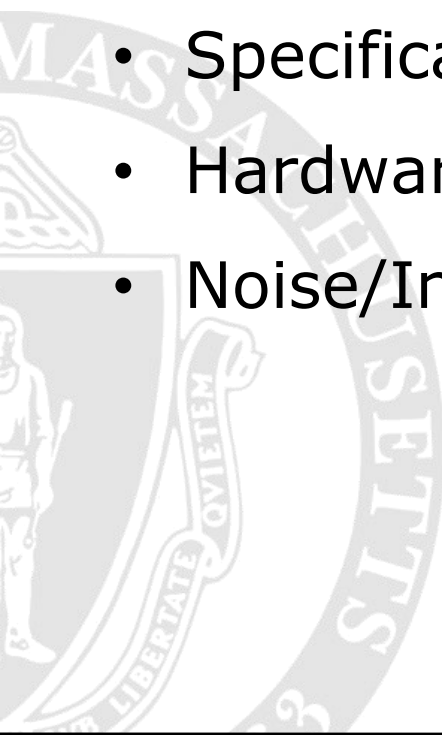
$$\Theta_1 = -30 \text{ deg}$$

$$\Theta_2 = +30 \text{ deg}$$



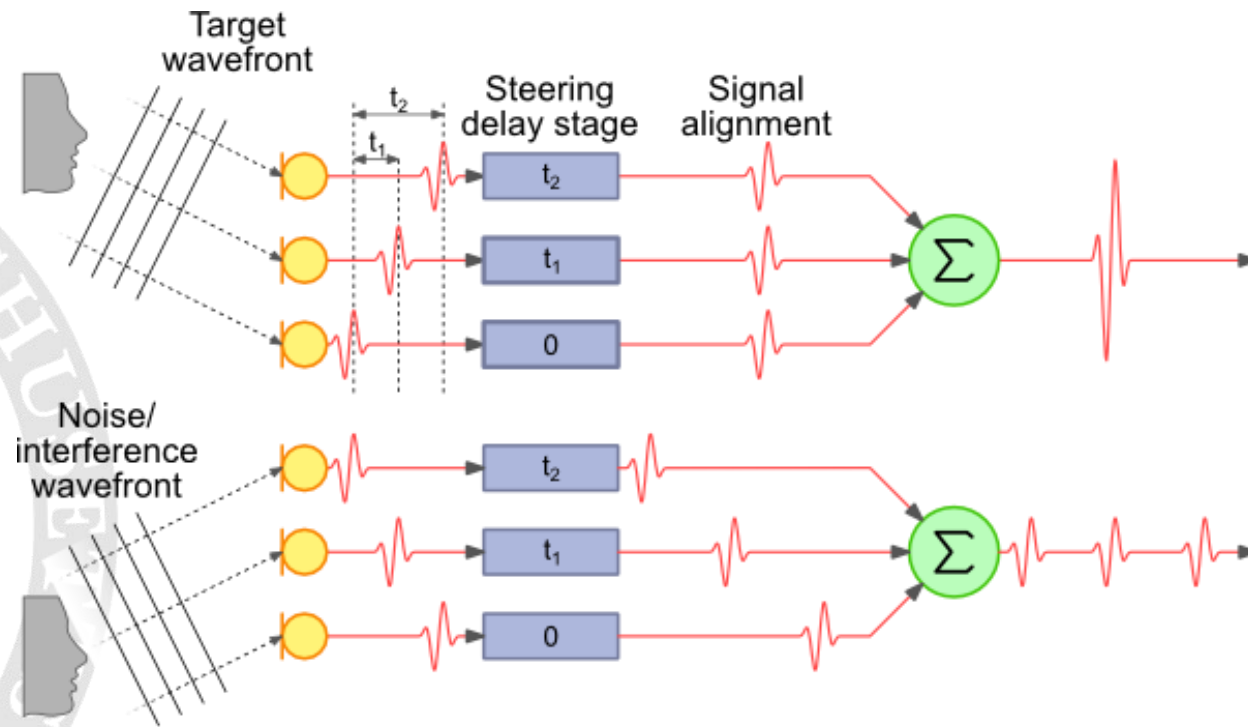
# Explanations

- Time-Delay Beamforming
- Reverb
- Specifications
- Hardware
- Noise/Interference Removal



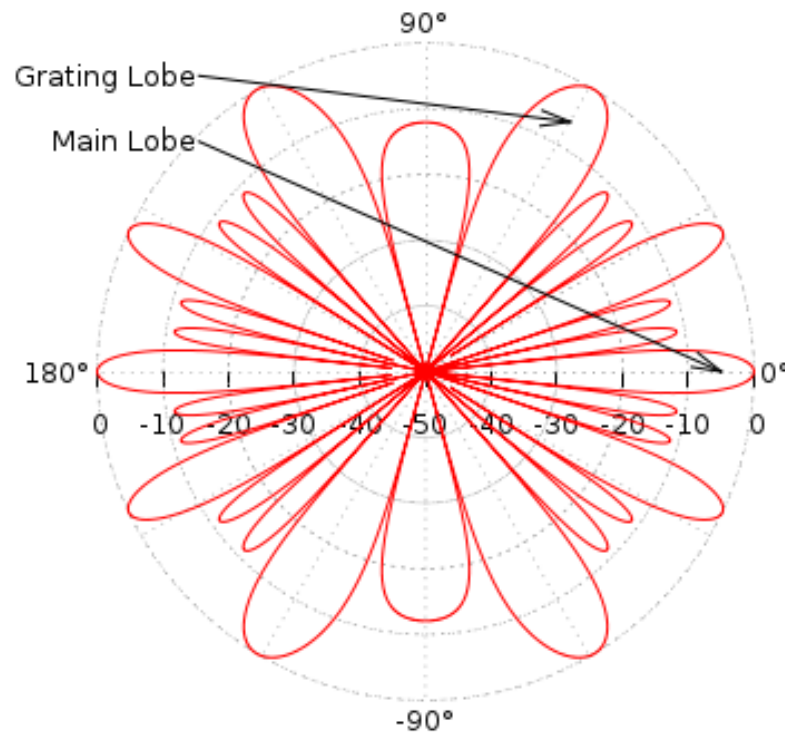
# Time-Delay Beamforming

## Delayed Interference



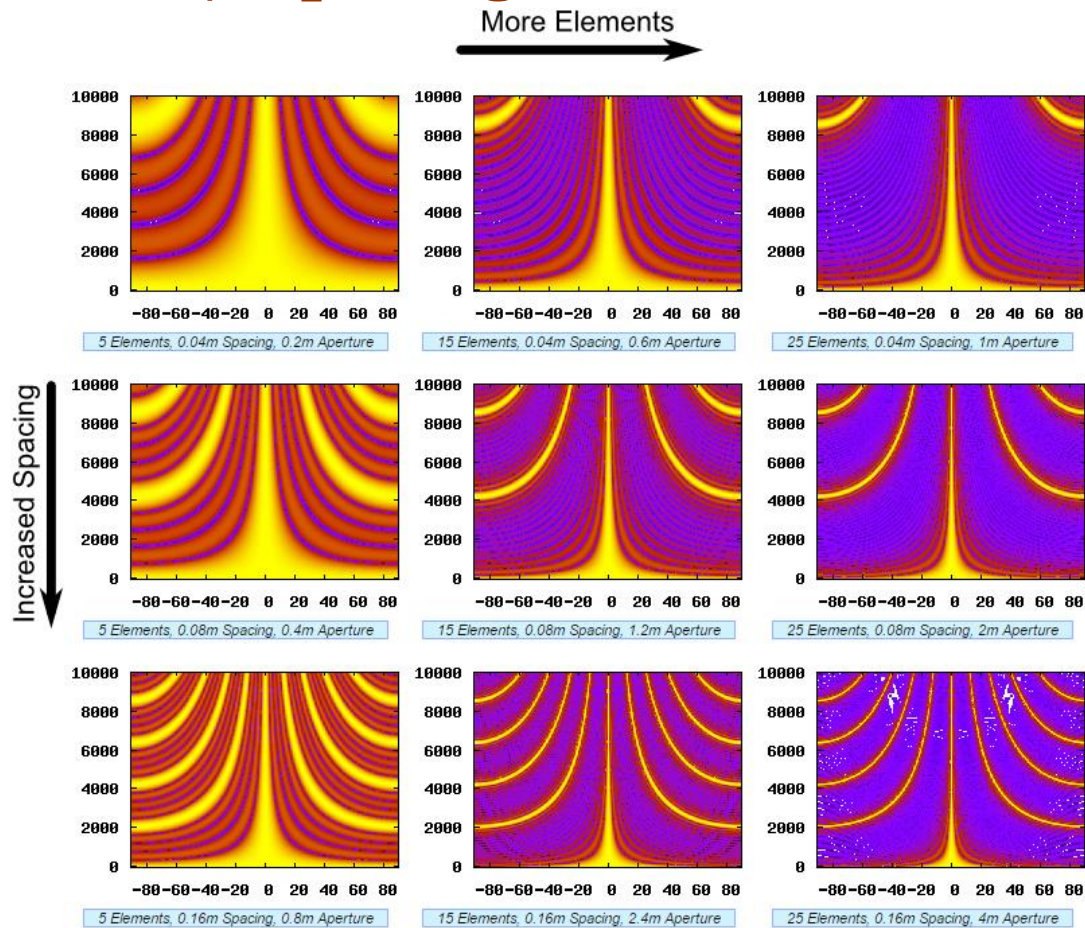
# Time-Delay Beamforming

## Main Lobe vs. Side Lobe



# Time-Delay Beamforming

## Element Count / Spacing vs Beam



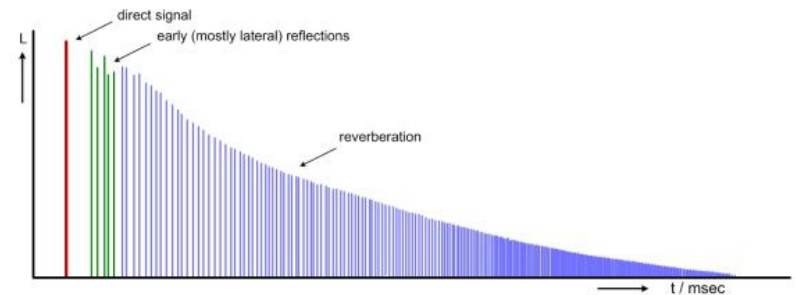
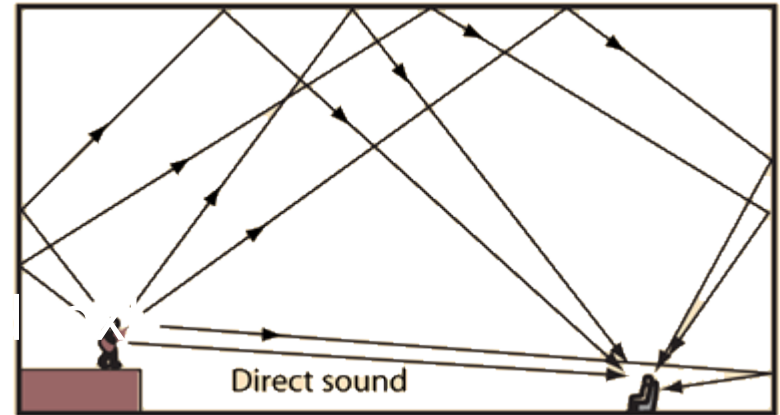


# Reverb A Note On Reverb

The persistence of sound  
after a sound is produced

All sounds coming from all  
Directions

Makes Beamforming less  
useful as



Reverb Impulse Response

# Specifications

Min Distance: 1m

Max Distance: 3m

Spanning Angle:  $130^\circ$  ( $-65^\circ$  to  $65^\circ$ )

Beamwidth:  $40^\circ$

Frequency: 500Hz-3.5kHz

# Hardware

## Microphones

- High Sensitivity, Frequency Response

## Amplifiers

- High slew rate, low distortion, and low noise are desired for high quality audio and high performance instrumentation applications.

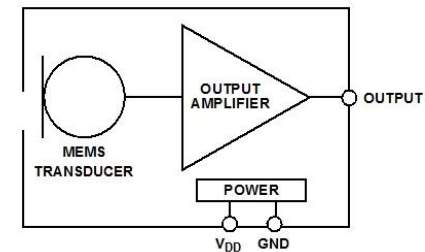
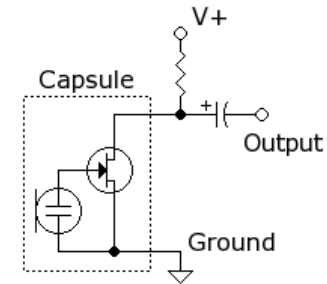
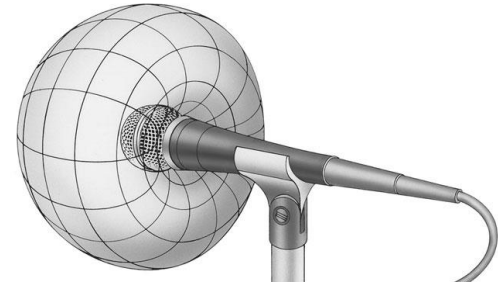
## Transmission Lines

- Electrical wire vs. XLR cable
- Shielding resists RF and EM interference

# Hardware

## Microphones

- Cardioid
  - -54dBV sensitivity
  - 50-15kHz frequency range
- Electret
  - -44dBV sensitivity
  - 20-20kHz frequency range
- MEMS
  - -38dBV sensitivity
  - 100-15kHz frequency range



# Hardware

## Amplifiers

- LM386
  - High Distortion
  - High Noise
  - Sensitive to variations in power supply
- ADA4075
  - Low Distortion
  - Low Noise
  - High Slew Rate
- AD8273
  - Low Distortion
  - High Slew Rate
  - Single-Ended to Differential

# Hardware

## Transmission Lines

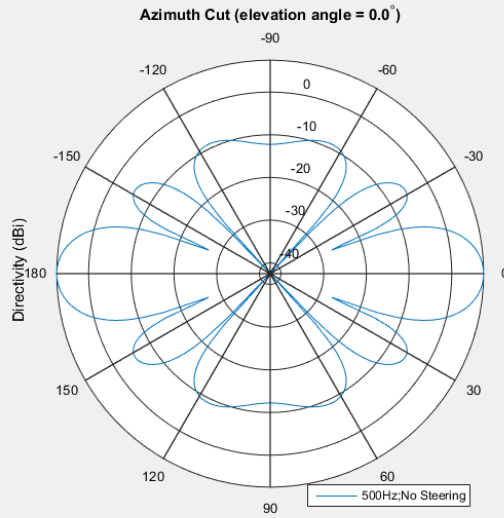
- Unshielded Wire
  - Sensitive to EMI and RFI noise
- XLR
  - Quiet
  - Durability
  - Three-pin (differential audio signal & ground)

# Directivity Plots

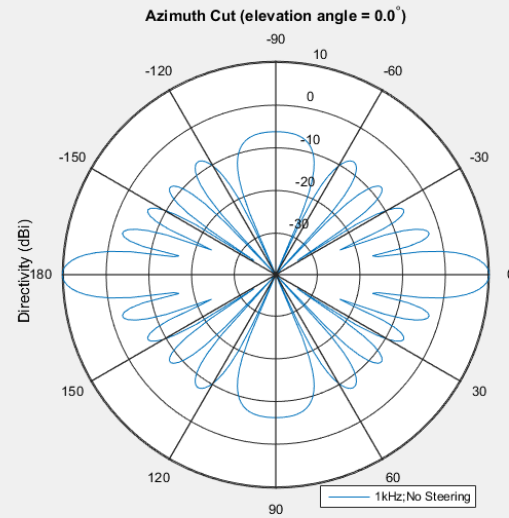
## Acoustic Beamformer

- 8 electret mic linear array, 23.5cm spacing
- 500MHz, 1kHz, 1.5kHz, 2kHz

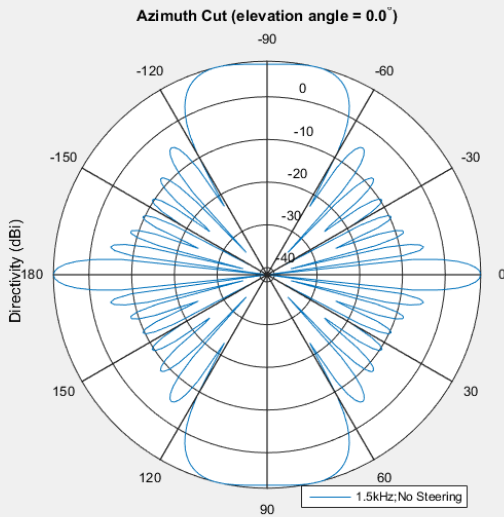




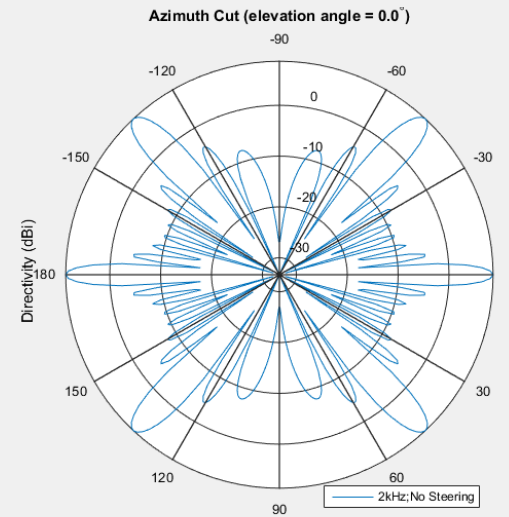
Directivity (dBi), Broadside at 0.00 degrees



Directivity (dBi), Broadside at 0.00 degrees



Directivity (dBi), Broadside at 0.00 degrees



Directivity (dBi), Broadside at 0.00 degrees

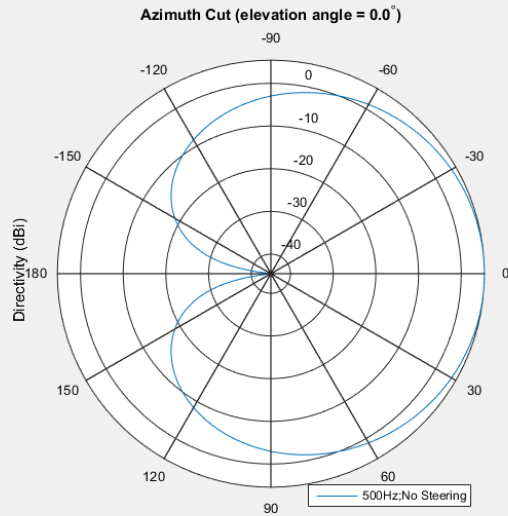


# Directivity Plots

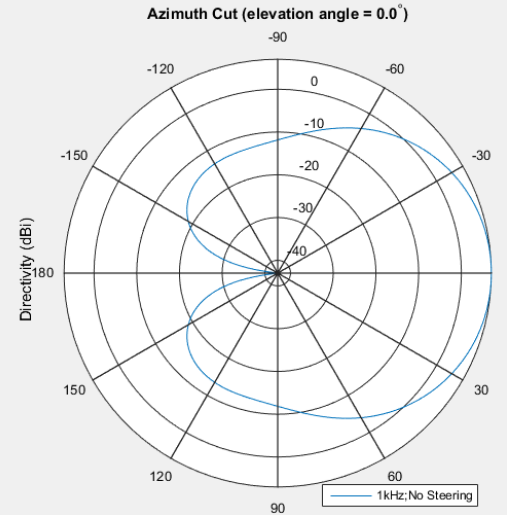
## Wolf Array

- 4 cardioid mic linear array, 7cm spacing
- 500MHz, 1kHz, 1.5kHz, 2kHz

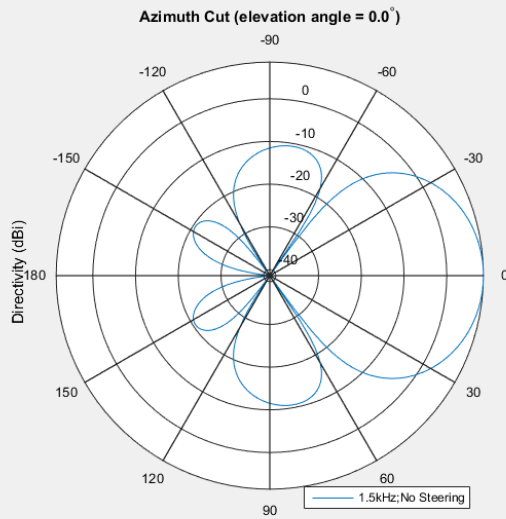




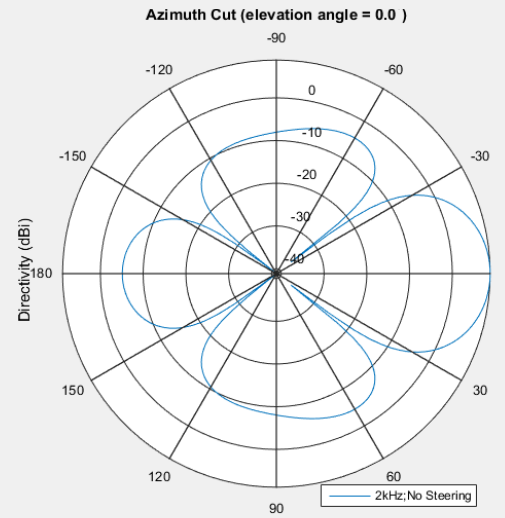
Directivity (dBi), Broadside at 0.00 degrees



Directivity (dBi), Broadside at 0.00 degrees



Directivity (dBi), Broadside at 0.00 degrees



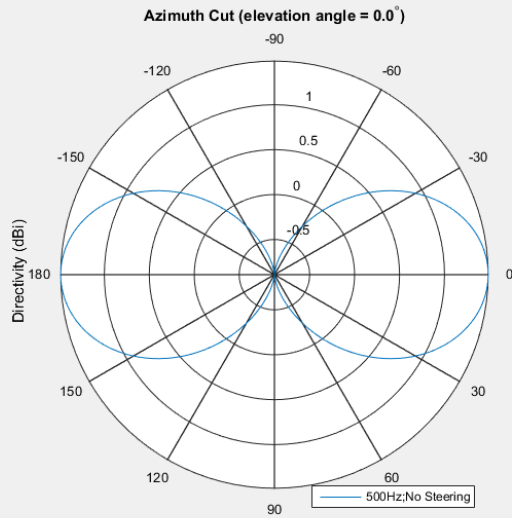
Directivity (dBi), Broadside at 0.00 degrees

# Directivity Plots

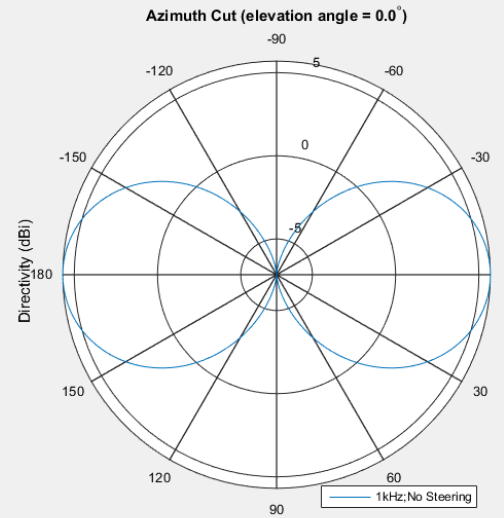
## Proposed Array

- 16 mems mic square array, 7cm x 7cm
- 500MHz, 1kHz, 1.5kHz, 2kHz

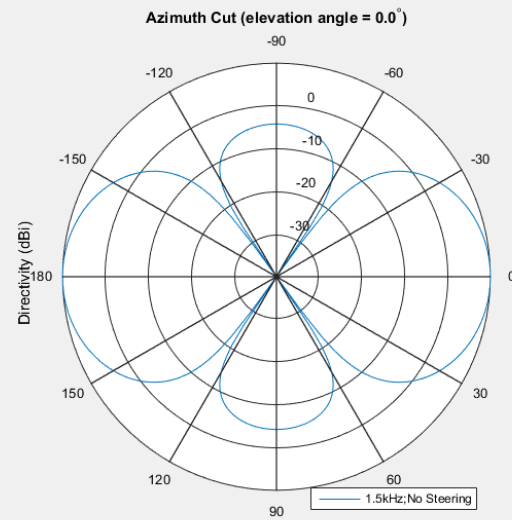




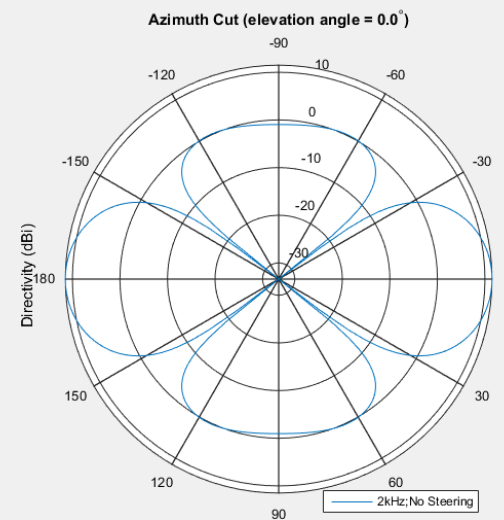
Directivity (dBi), Broadside at 0.00 degrees



Directivity (dBi), Broadside at 0.00 degrees

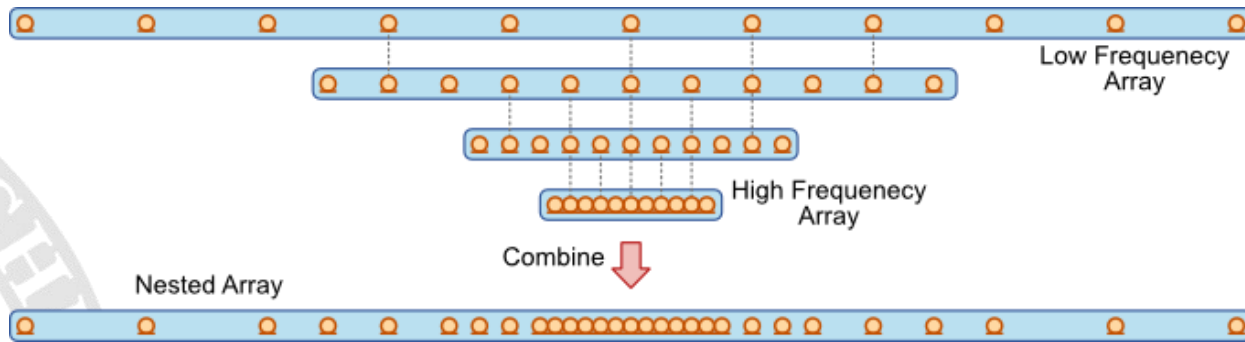


Directivity (dBi), Broadside at 0.00 degrees



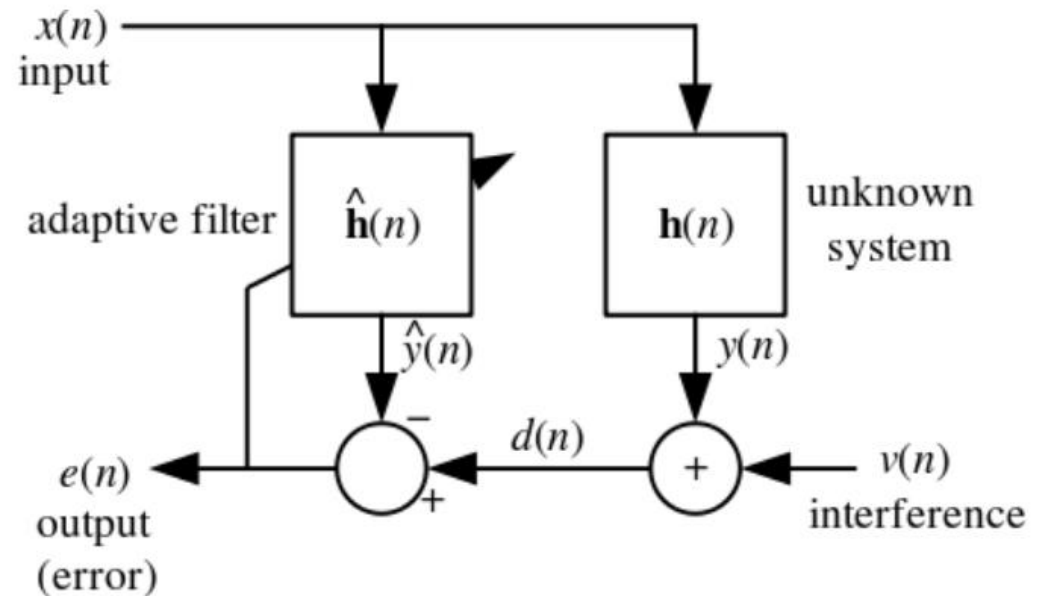
Directivity (dBi), Broadside at 0.00 degrees

# Compound Mic Array

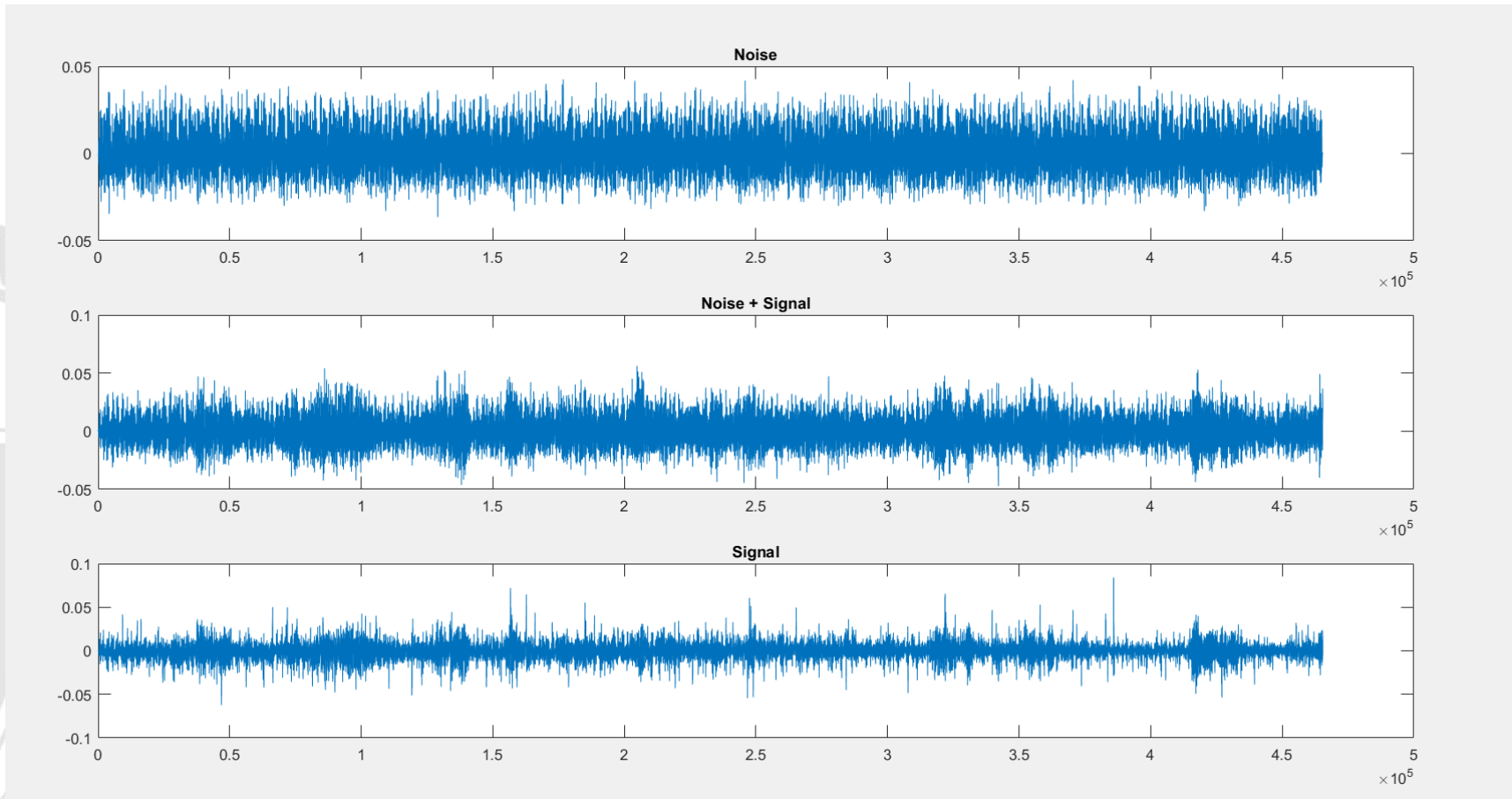


# Noise/Interference Removal

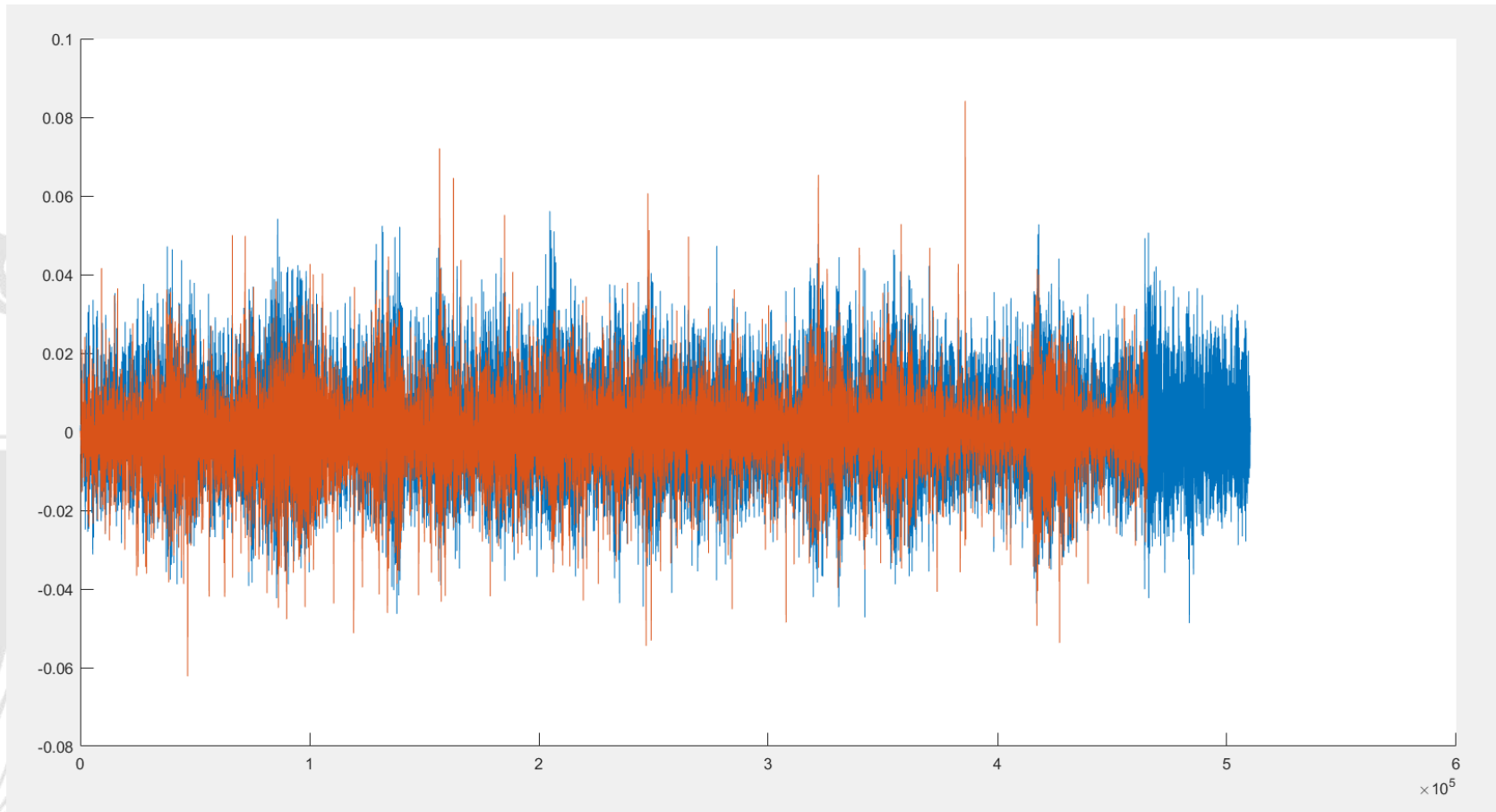
## LMS Adaptive Filter



# Noise/Interference Removal



# Noise/Interference Removal

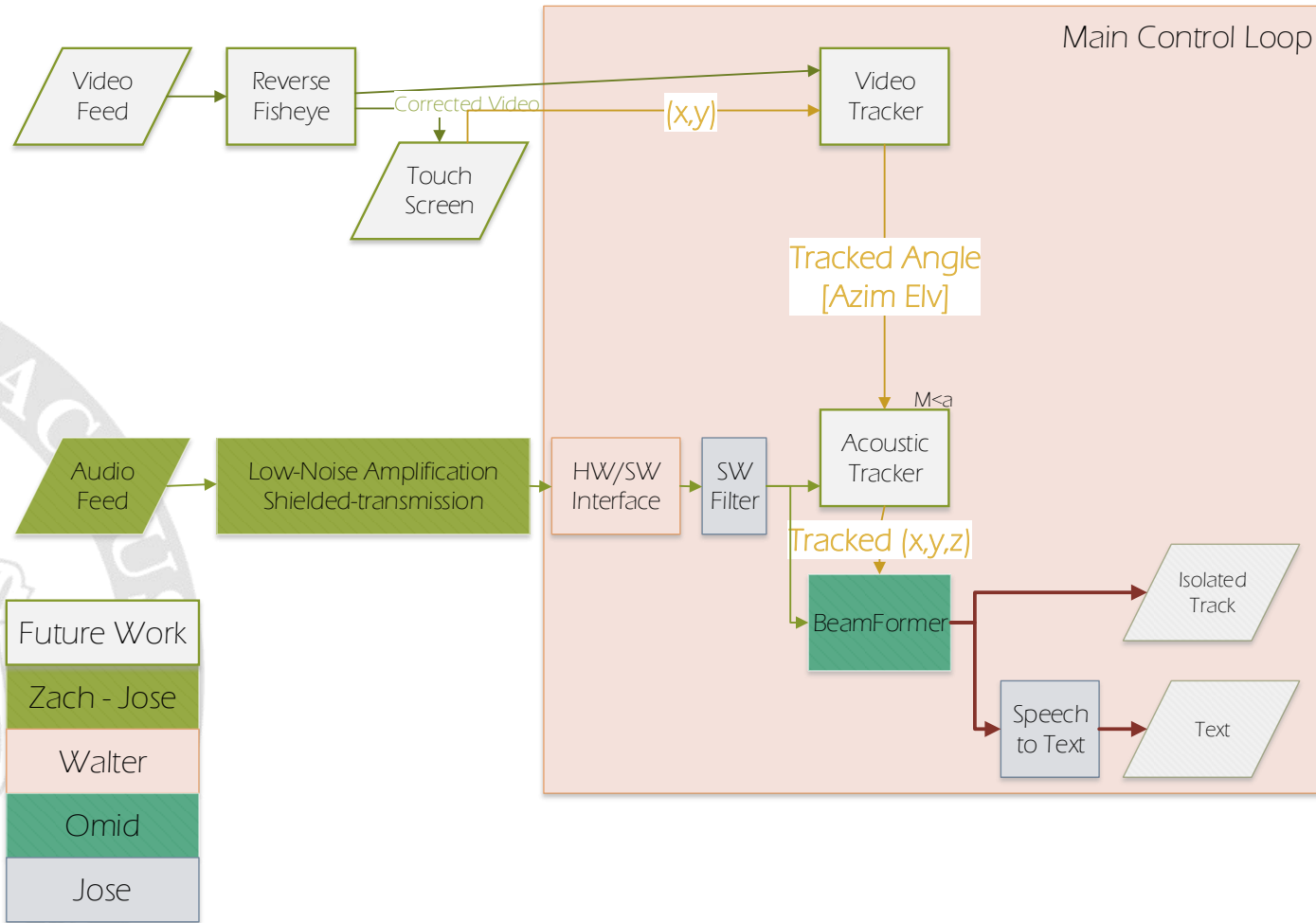




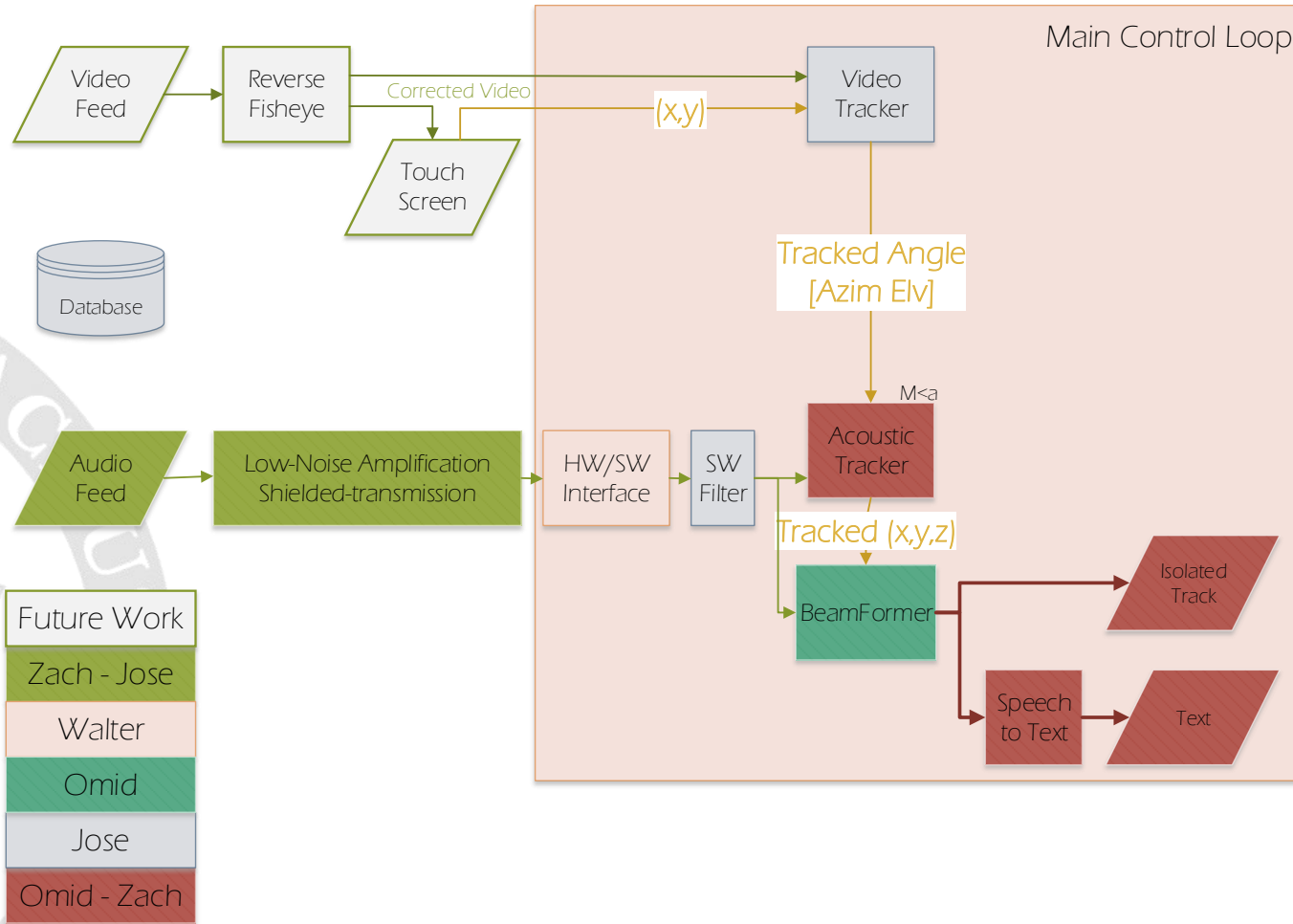
# Looking Forward

- End of Winter
  - Array Assembled, H/S Interface modified
  - Get Fish Eye
- End of February:
  - Database
- End of March
  - Video to Angle
- End of April
  - Video Tracking

# Block Diagram (Current)



# Block Diagram (Future)



- Future Work
- Zach - Jose
- Walter
- Omid
- Jose
- Omid - Zach