

Solutions to HW # 2

Problem 1:

Ideal delay system: $y(t) = x(t - T_d)$

(a) $y(t) = \int_{-\infty}^{\infty} h(\tau) x(t - \tau) d\tau$ for LTI systems

from input/output relationship $\Rightarrow x(t - T_d) = \int_{-\infty}^{\infty} \delta(\tau - T_d) x(t - \tau) d\tau$

$\Rightarrow h(\tau) = \delta(\tau - T_d) \Rightarrow \boxed{h(t) = \delta(t - T_d)}$

(b) $H(j\Omega) = \mathcal{F}\{h(t)\} = \int_{-\infty}^{\infty} h(t) e^{-j\Omega t} dt$

$= \int_{-\infty}^{\infty} \delta(t - T_d) e^{-j\Omega t} dt = e^{-j\Omega T_d}$

$\Rightarrow \boxed{H(j\Omega) = e^{-j\Omega T_d}}$

(c) $x(t) = A \cdot \cos(\Omega_0 t + \varphi)$,

$y(t) = A \cdot \cos(\Omega_0(t - T_d) + \varphi)$,

where $\Omega_0 = \frac{2\pi}{T}$, $A = \text{amplitude}$, and $\varphi = \text{phase at } t=0$

Measurement error: $e(t) = y(t) - x(t)$

Error variance (mean square): $\sigma^2 = \frac{1}{T} \int_0^T e^2(t) dt$

Recall: $\cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta$

$$\Rightarrow e(t) = A \left[\cos(\underbrace{\Omega_0 t + \varphi}_{\alpha} - \underbrace{\Omega_0 T_d}_{\beta}) - \cos(\underbrace{\Omega_0 t + \varphi}_{\alpha}) \right]$$

Now,

$$\begin{aligned} & \left[\cos(\alpha - \beta) - \cos \alpha \right]^2 \\ &= \left[\cos \alpha \cos \beta + \sin \alpha \sin \beta - \cos \alpha \right]^2 \\ &= \left[\cos \alpha (\cos \beta - 1) + \sin \alpha \sin \beta \right]^2 \\ &= \underbrace{\cos^2 \alpha (\cos \beta - 1)^2}_a + 2 \underbrace{\sin \alpha \cos \alpha (\cos \beta - 1) \sin \beta}_b + \underbrace{\sin^2 \alpha \sin^2 \beta}_c \\ &= a \cos^2 \alpha + 2b \sin \alpha \cos \alpha + c \sin^2 \alpha \end{aligned}$$

Now, find the mean square of e by integrating α from 0 to 2π and dividing by 2π :

$$\begin{aligned} \langle e^2 \rangle &= A^2 \left[\underbrace{\frac{a}{2\pi} \int_0^{2\pi} \sin^2 \alpha d\alpha}_a + \underbrace{\frac{2b}{2\pi} \int_0^{2\pi} \sin \alpha \cos \alpha d\alpha}_b + \underbrace{\frac{c}{2\pi} \int_0^{2\pi} \sin^2 \alpha d\alpha}_c \right] \\ &= \frac{A^2}{2} \left[(\cos \beta - 1)^2 + \sin^2 \beta \right] \end{aligned}$$

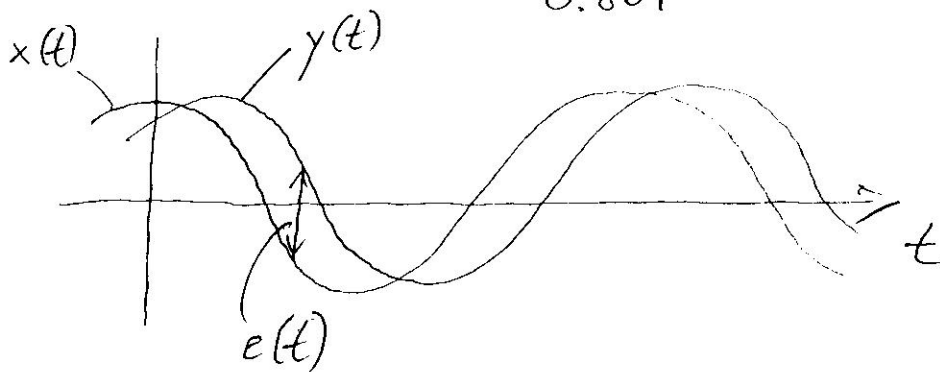
$$\begin{aligned} \Rightarrow \langle e^2 \rangle &= \frac{A^2}{2} [\cos^2 \beta - 2 \cos \beta + 1 + \sin^2 \beta] \\ &= \frac{A^2}{2} [2 - 2 \cos \beta] \\ &= A^2 (1 - \cos \beta) \end{aligned}$$

$$\Rightarrow \sigma_e = \sqrt{\langle e^2 \rangle} = A \sqrt{1 - \cos \beta} = A \sqrt{1 - \cos \left(\frac{2\pi}{T} T_d \right)}$$

Here: $A = 1 \text{ V}$, $T = 10 \mu\text{s}$, $T_d = 1 \mu\text{s}$

$$\Rightarrow \sigma_e = 1 \text{ V} \cdot \sqrt{1 - \cos \left(\frac{2\pi}{10 \mu\text{s}} \cdot 1 \mu\text{s} \right)} = \underline{\underline{0.437 \text{ V}}}$$

0.809



(d) From (c), we know:

$$e^2(t) = A^2 [a \cos^2 x + 2b \sin x \cos x + c \sin^2 x],$$

where $a = (\cos \beta - 1)^2$, $b = (\cos \beta - 1) \sin \beta$, $c = \sin^2 \beta$,

$$\beta = \frac{2\pi}{T} T_d, \quad x = \Omega_0 t + \varphi$$

Now, we let T_d be a random variable (R.V.) with a Gaussian p.d.f.:

$$f_{T_d}(T_d) = \frac{1}{\sqrt{2\pi} \sigma_{T_d}} e^{-\frac{T_d^2}{2\sigma_{T_d}^2}}$$

(Here, for the sake of simplicity, we let $\langle T_d \rangle = 0$. That is, we assume T_d to be a zero-mean R.V.)

Because $a = a(T_d)$, $b = b(T_d)$, $c = c(T_d)$, the three variables a, b, c are also R.V.'s

$$\Rightarrow \sigma_e^2 = \langle e^2(t) \rangle$$

$$= A^2 \left[\langle a \rangle \cos^2 \alpha + 2 \langle b \rangle \sin \alpha \cos \alpha + \langle c \rangle \sin^2 \alpha \right]$$

Note that at this point σ_e^2 is a function of time!

Now, evaluate the three expected values:

$$\langle a \rangle = \int_{-\infty}^{\infty} \underbrace{\frac{1}{\sqrt{2\pi} \sigma_{T_d}} e^{-\frac{T_d^2}{2\sigma_{T_d}^2}}}_{f_{T_d}(T_d)} \cdot \underbrace{\left(\cos \frac{2\pi}{T} T_d - 1 \right)^2}_a dT_d,$$

$$\langle b \rangle = \int_{-\infty}^{\infty} f_{T_d}(T_d) b dT_d, \quad \langle c \rangle = \int_{-\infty}^{\infty} f_{T_d}(T_d) c dT_d.$$

These integrals can be evaluated in close form.

Then, as the last step, integrate over α from 0 to 2π , as in 1(c).

Problem 2

Voltage error at some time t is the sum of thermal noise $n(t)$ and of digitization noise $q(t)$:

$$e(t) = n(t) + q(t).$$

(a) Precision of voltage measurement for $q(t)=0$:

$$\sigma_V = \sqrt{\langle e_V^2 \rangle} = \sqrt{\langle n^2 \rangle} = \sigma_n = 1 \mu V$$

Temperature precision:

$$\sigma_T^2 = \langle e_T^2 \rangle = \left\langle \left(\frac{\partial T}{\partial V} e_V \right)^2 \right\rangle = \left(\frac{\partial T}{\partial V} \right)^2 \langle e_V^2 \rangle = \left(\frac{\partial T}{\partial V} \right)^2 \sigma_V^2$$

$$\Rightarrow \sigma_T = \left| \frac{\partial T}{\partial V} \right| \sigma_V \stackrel{\text{here}}{=} \frac{1}{40} \frac{K}{\mu V} \cdot 1 \mu V = \frac{1}{40} K = \underline{\underline{0.025 K}}$$

$$(b) \sigma_V^2 = \langle e_V^2 \rangle = \langle (n+q)^2 \rangle = \langle n^2 + 2nq + q^2 \rangle$$

$$= \underbrace{\langle n^2 \rangle}_{=\sigma_n^2} + 2 \underbrace{\langle nq \rangle}_{=0 \text{ because } n, q \text{ stat. independent}} + \underbrace{\langle q^2 \rangle}_{=\frac{s^2}{12}}$$

$$= \sigma_n^2 + \frac{1}{12} s^2$$

$$\Rightarrow \sigma_V = \sqrt{\sigma_n^2 + \frac{1}{12} s^2} = \sqrt{(1 \mu V)^2 + \frac{1}{12} (1 \mu V)^2} = \sqrt{\frac{13}{12}} \mu V$$

$$\Rightarrow \sigma_T = \left| \frac{\partial T}{\partial V} \right| \sigma_V = \frac{1}{40} \frac{K}{\mu V} \cdot \sqrt{\frac{13}{12}} \mu V = 0.026 K$$

Problem 2 (cont'd)

$$(c) \sigma_V \leq \frac{11}{10} \sigma_n \Rightarrow \sigma_V^2 \leq \left(\frac{11}{10}\right)^2 \sigma_n^2$$

$$\Rightarrow \sigma_n^2 + \frac{1}{12} s^2 \leq \frac{121}{100} \sigma_n^2$$

$$\Rightarrow \frac{1}{12} s^2 \leq \frac{21}{100} \sigma_n^2$$

$$\Rightarrow s^2 \leq \frac{12 \cdot 21}{100} \sigma_n^2 \Rightarrow \underline{\underline{s \leq 1.59 \sigma_n}}$$

$$\Rightarrow s_T \leq 1.59 \cdot \underbrace{25 \mu\text{K}}_{\sigma_{n,T}} = 39.8 \mu\text{K}$$

Problem 3:

(a) We know: $S_0 = \frac{\alpha}{D_s^2}$, where $\alpha = \text{const.}$

$$\Rightarrow \frac{dS_0}{dD_s} = \alpha \cdot (-2) D_s^{-3} = -\underbrace{\frac{\alpha}{D_s^2}}_{= S_0} \cdot \frac{2}{D_s} = -2 \frac{S_0}{D_s}$$

$$\Rightarrow \frac{\Delta S_0}{\Delta D_s} \approx -2 \frac{S_0}{D_s}$$

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That is, if D_s decreases by $p\%$, then S_0 increases (minus sign!) by $2p\%$.

Problem 3 (cont'd):

(b) We know: $T_e = b S_0^{\frac{1}{4}}$, $b = \text{const.}$

$$\Rightarrow T_e = b \left(\frac{a}{D_s^2} \right)^{\frac{1}{4}} \Rightarrow T_e = c D_s^{-\frac{1}{2}}, \quad c = \text{const.}$$

$$\Rightarrow \frac{\Delta T_e}{T_e} \approx -\frac{1}{2} \frac{\Delta D_s}{D_s}$$

\Rightarrow That is, if D_s decreases by $p\%$,
then T_s increases by $\frac{p}{2}\%$.

Problem 4:

Let Sun, Earth and Moon be nearly aligned.
That is, we have full moon but not
a lunar eclipse.

