

## ECE397A – Operating Systems

- Welcome!
- Instructor: Professor Csaba Andras Moritz
- Class webpage:  
<http://www.ecs.umass.edu/ece/andras/courses/ECE397>
- Instructors webpage:  
<http://www.ecs.umass.edu/ece/andras>
- 3 homeworks (10%), 4 projects/labs in Java/C (30%)
- 2 exams and pop quizzes (60%)
- All information will be put on the web, check the class webpage regularly.
- Acknowledgements: *material leveraged from Silberschatz, Galvin, and Gagne.*

## Chapter 1: Introduction

- What is an Operating System?
- Mainframe Systems (OS390, z/OS, Linux for S/390, available on G5, G6 and Multiprise 3000 procs. )
- Desktop Systems (WinNT, Me, 2000, XP, Linux, Solaris, BeOS, OS2-Warp, MAC OS X ...)
- Multiprocessor Systems (FreeBSD SMP, Raw OS,...)
- Distributed Systems – Middleware (CORBA, .NET, J2EE)
- Clustered System (SGI CXFS 2.0, TeraGrid project)
- Embedded Systems
- Real -Time Systems (RTOS, lots of specialized OS)
- Handheld Systems (Pocket PC2002, PalmOS)

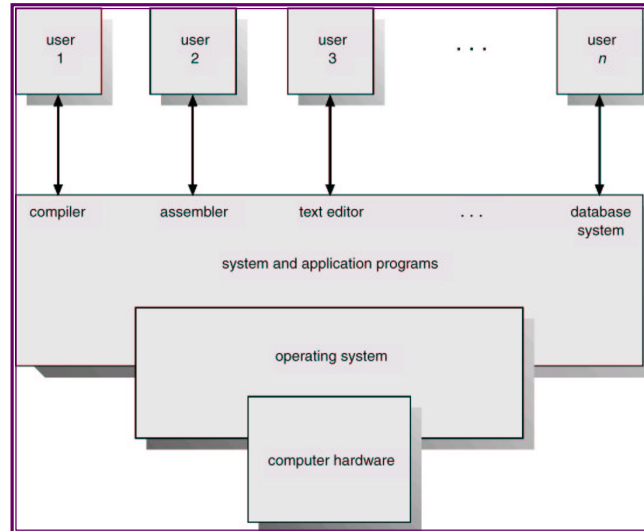
## What is an Operating System?

- A software that acts as an intermediary between a user of a computer and the computer hardware.
- Operating system goals:
  - ◆ Execute user programs and make solving user problems easier.
  - ◆ Make the computer system convenient to use. (G)UI interface.
  - ◆ Manage hardware resources
  - ◆ Use the computer hardware in an efficient manner.

## Computer System Components

1. Hardware – provides basic computing resources (CPU, cache, memory, disk, I/O devices).
2. Operating system – controls and coordinates the use of the hardware among the various application programs for the various users.
3. Applications programs – define the ways in which the system resources are used to solve the computing problems of the users (compilers, database systems, video games, business programs).
4. Users (people, other computers).

## Abstract View of System Components



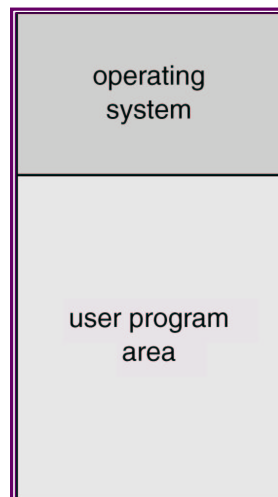
## Operating System Definitions

- Resource allocator – manages and allocates resources.
  - ◆ Why do we need to manage resources?
- Control program – controls the execution of user programs and operations of I/O devices .
  - ◆ Why can't we have all IO controls implemented in the applications directly?
- Kernel – the one program running at all times (all else being application programs).
  - ◆ Why do we need a kernel?

## Mainframe Systems

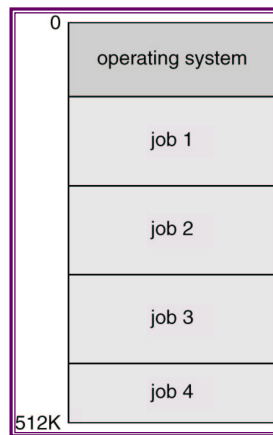
- Reduce setup time by batching similar jobs
- Automatic job sequencing – automatically transfers control from one job to another. First rudimentary operating system.
- Resident monitor
  - ◆ initial control in monitor
  - ◆ control transfers to job
  - ◆ when job completes control transfers back to monitor

## Memory Layout for a Simple Batch System



## Multiprogrammed Batch Systems

Several jobs are kept in main memory at the same time, and the CPU is multiplexed among them.



## OS Features Needed for Multiprogramming

- I/O routine supplied by the system.
- Memory management – the system must allocate the memory to several jobs.
- CPU scheduling – the system must choose among several jobs ready to run.
- Allocation of devices.

## Time-Sharing Systems–Interactive Computing

- The CPU is multiplexed among several jobs that are kept in memory and on disk (the CPU is allocated to a job only if the job is in memory).
- A job swapped in and out of memory to the disk.
- On-line communication between the user and the system is provided; when the operating system finishes the execution of one command, it seeks the next “control statement” from the user’s keyboard.
- On-line system must be available for users to access data and code.

## Desktop Systems

- *Personal computers* – computer system dedicated to a single user.
- I/O devices – keyboards, mice, display screens, small printers.
- User convenience and responsiveness.
- Can adopt technology developed for larger operating system’ often individuals have sole use of computer and do not need advanced CPU utilization of protection features.
- May run several different types of operating systems (Windows, MacOS, UNIX, Linux)

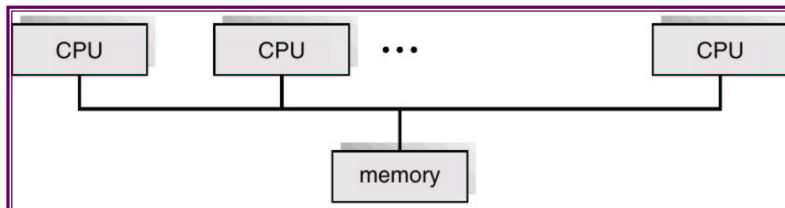
## Parallel Systems

- Multiprocessor systems with more than one CPU in close communication.
- *Tightly coupled system* – processors share memory and a clock; communication usually takes place through the shared memory.
- Advantages of parallel system:
  - ◆ Increased *throughput*
  - ◆ Economical
  - ◆ Increased reliability
    - ✓ graceful degradation
    - ✓ fail-soft systems

## Parallel Systems (Cont.)

- *Symmetric multiprocessing (SMP)*
  - ◆ Each processor runs an identical copy of the operating system.
  - ◆ Many processes can run at once without performance deterioration.
  - ◆ Most modern operating systems support SMP
- *Asymmetric multiprocessing*
  - ◆ Each processor is assigned a specific task; master processor schedules and allocates work to slave processors.
  - ◆ More common in extremely large systems

## Symmetric Multiprocessing Architecture



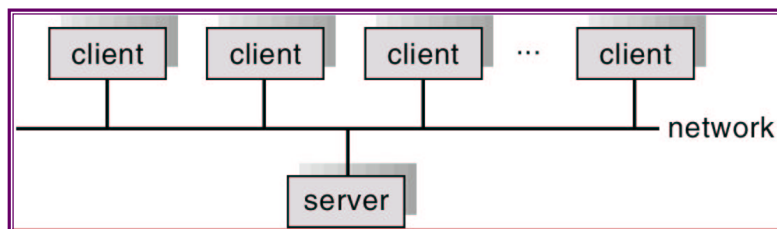
## Distributed Systems

- Distribute the computation among several physical processors.
- *Loosely coupled system* – each processor has its own local memory; processors communicate with one another through various communications lines, such as high-speed buses or telephone lines.
- Advantages of distributed systems.
  - ◆ Resources Sharing
  - ◆ Computation speed up – load sharing
  - ◆ Reliability
  - ◆ Communications

## Distributed Systems (cont)

- Requires networking infrastructure.
- Local area networks (LAN) or Wide area networks (WAN)
- May be either client-server or peer-to-peer systems.

## General Structure of Client-Server



## Clustered Systems

- Clustering allows two or more systems to share storage.
- Provides high reliability.
- *Asymmetric clustering*: one server runs the application while other servers standby.
- *Symmetric clustering*: all N hosts are running the application.

## Real-Time Systems

- Often used as a control device in a dedicated application such as controlling scientific experiments, medical imaging systems, industrial control systems, and some display systems.
- Well-defined fixed-time constraints.
- Real-Time systems may be either *hard* or *soft* real-time.

## Real-Time Systems (Cont.)

- Hard real-time:
  - ◆ Secondary storage limited or absent, data stored in short term memory, or read-only memory (ROM)
  - ◆ Conflicts with time-sharing systems, not supported by general-purpose operating systems.
- Soft real-time
  - ◆ Limited utility in industrial control of robotics
  - ◆ Useful in applications (multimedia, virtual reality) requiring advanced operating-system features.

## Handheld Systems

- Personal Digital Assistants (PDAs)
- Cellular telephones
- Issues:
  - ◆ Limited memory
  - ◆ Slow processors
  - ◆ Small display screens.

