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CEE 577: Surface Water Quality Modeling

Lecture #5
(particular solutions)
Chapra L4

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Non-steady state solutions

- After a change in loading
 - how long will it take for WQ to improve?
 - what will the shape of the curve look like?
- Return to the mass balance and solve

$$V \frac{dc}{dt} = W(t) - Qc - kVc - vA_s c$$

Divide by V

$$\frac{dc}{dt} = \frac{W(t)}{V} - \frac{Q}{V}c - kc - \frac{v}{H}c$$

An eigenvalue
“the cleansing rate”

$$\frac{dc}{dt} + \lambda c = \frac{W(t)}{V}$$

Where: $\lambda = \frac{Q}{V} + k + \frac{v}{H}$ $\lambda \equiv \frac{\alpha}{V}$

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Approximate Solution

- Non-steady state lake is described by an ODE:

$$\frac{dc}{dt} = \frac{W(t)}{V} - \frac{Q}{V}c - kc - \frac{v}{H}c$$

$$c_{t+\Delta t} = c_t + \frac{dc}{dt} \Delta t$$

- assuming you know the initial concentrations and coefficients, you can project future concentration numerically
- some error because dc/dt changes continuously with c

Exact Solution to MB equation

$$c = c_g + c_p$$

The general and particular solutions

- The general solution

- where $W(t)=0$

$$\frac{dc}{dt} + \lambda c = 0$$

$$\frac{dc}{c} = -\lambda dt$$

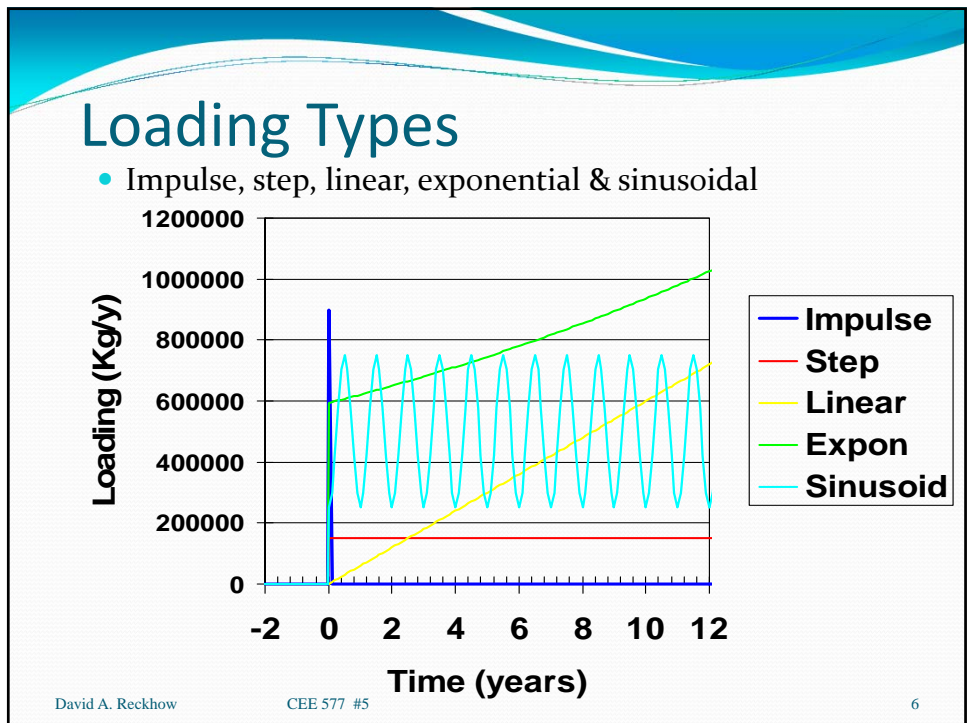
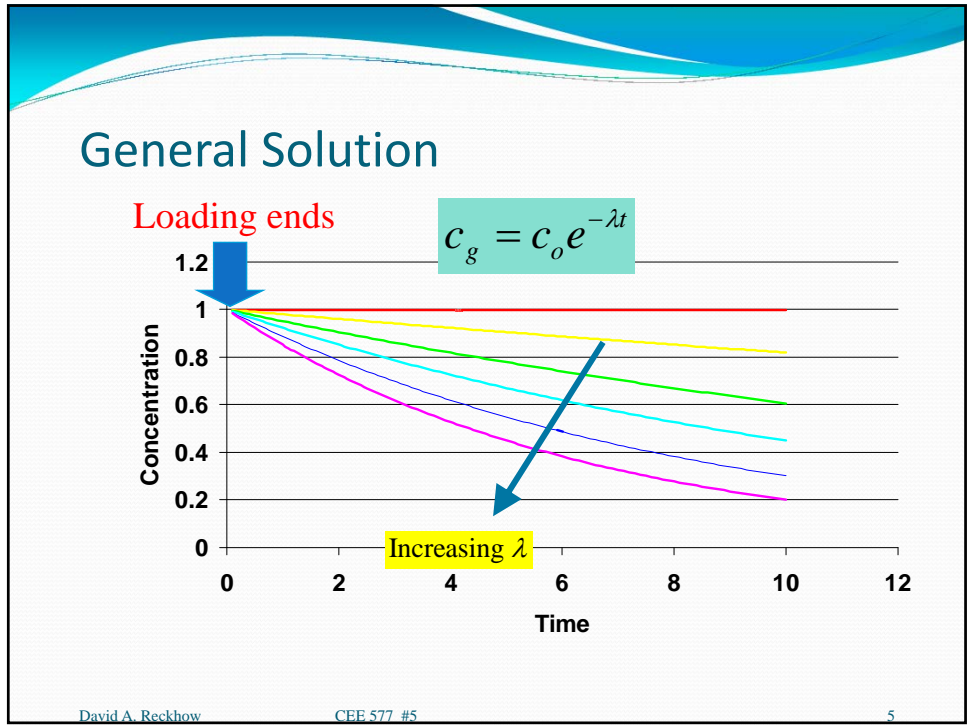
$$\int_{c_o}^c \frac{dc}{c} = -\lambda \int_0^t dt$$

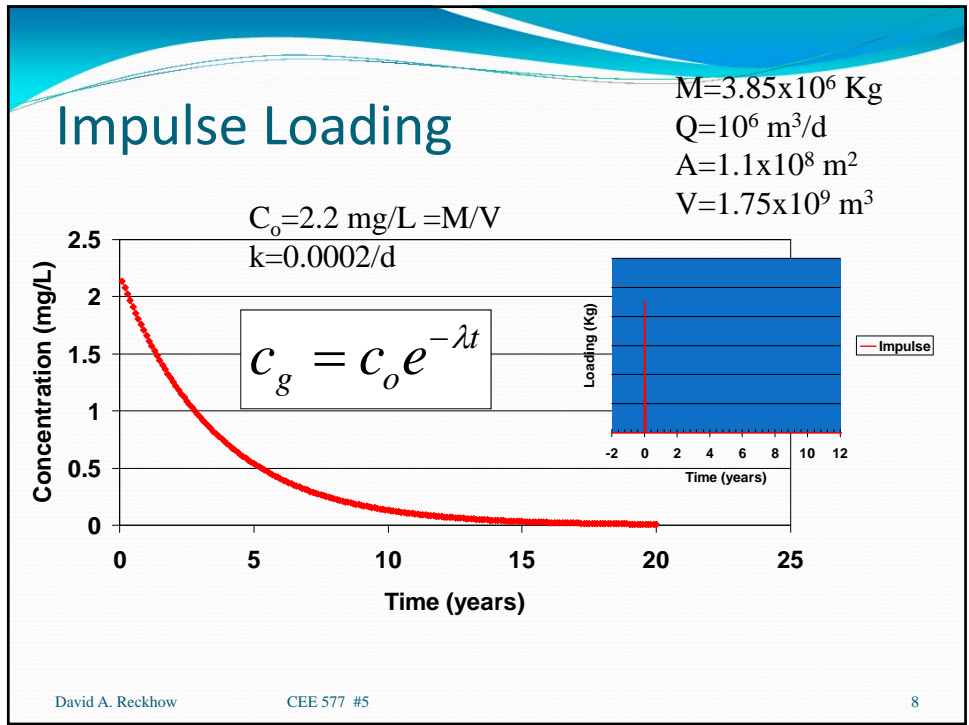
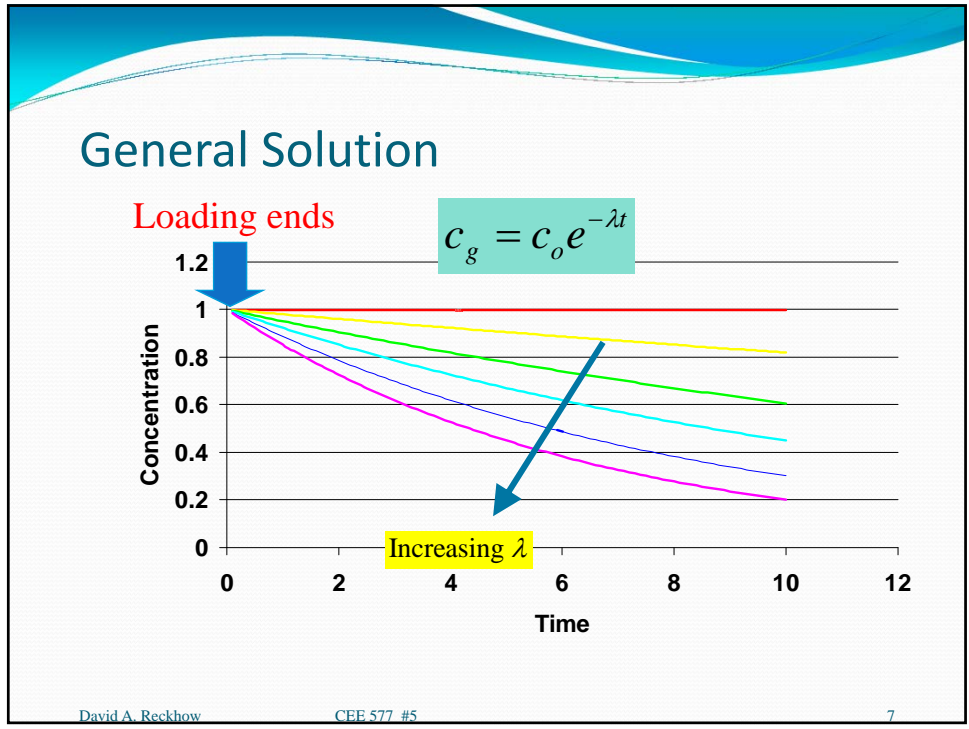
$$c \equiv c_g$$

$$\ln c \Big|_{c_o}^c = -\lambda t \Big|_0^t$$

$$\ln c = \ln c_o - \lambda t$$

$$c_g \equiv c = c_o e^{-\lambda t}$$





Solving for the particular solution

- Use the integrating factor method

$$\frac{dx}{dy} + p(y)x = g(y)$$

$$I = e^{\int p(y)dy}$$

$$\frac{dc}{dt} + \lambda c = \frac{W(t)}{V}$$

$I = e^{\int \lambda dt} = e^{\lambda t}$

$$e^{\lambda t} \frac{dc}{dt} + e^{\lambda t} \lambda c = e^{\lambda t} \frac{W(t)}{V}$$

$$\frac{d}{dt}(e^{\lambda t} c) = e^{\lambda t} \frac{W(t)}{V}$$

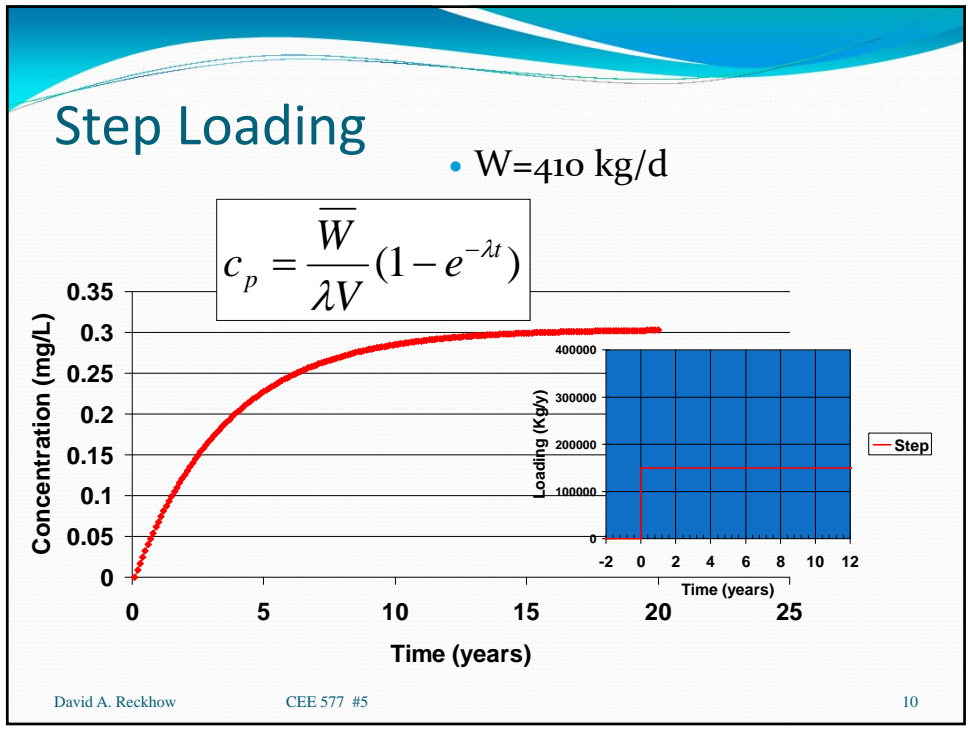
$$e^{\lambda t} c \Big|_0^t = \frac{1}{V} \int e^{\lambda t} W(t) dt$$

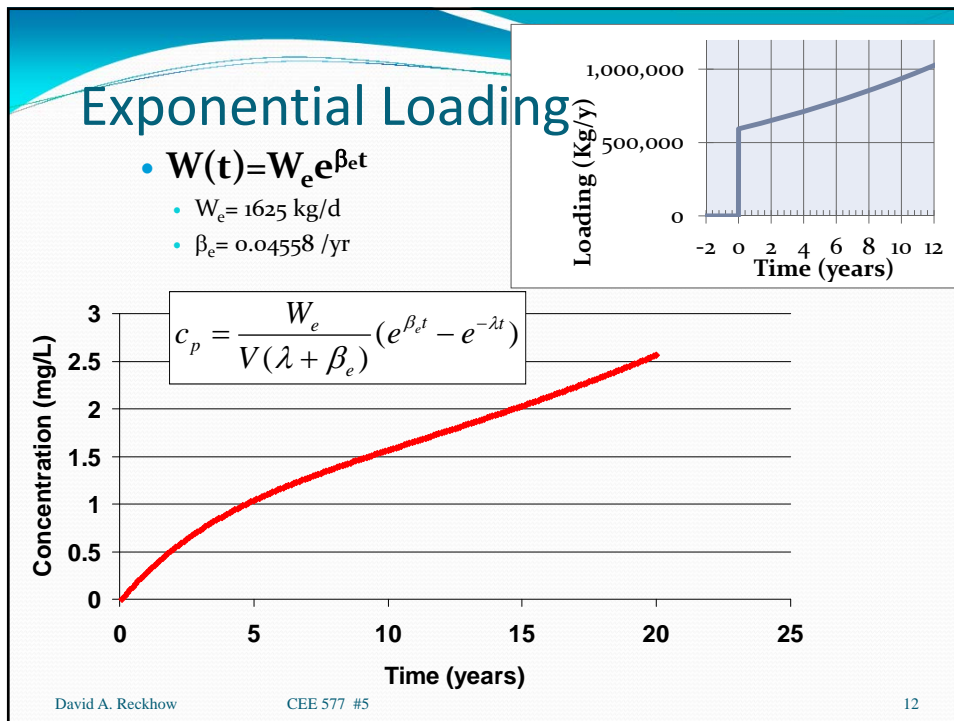
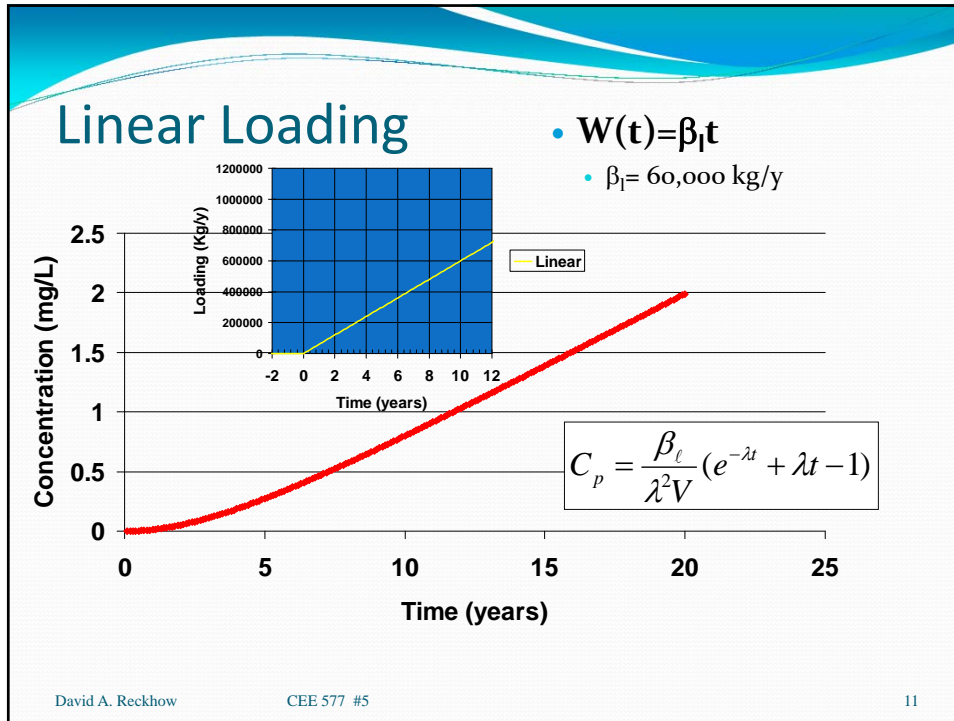
$$c e^{\lambda t} - c_0 = \frac{1}{V} \int e^{\lambda t} W(t) dt$$


$$c(t) = c_0 e^{-\lambda t} + \frac{e^{-\lambda t}}{V} \int_0^t e^{\lambda t} W(t) dt$$

c_g c_p

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- To next lecture

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